

Optimization of Heterogeneous Arrays of Wave Energy Converters

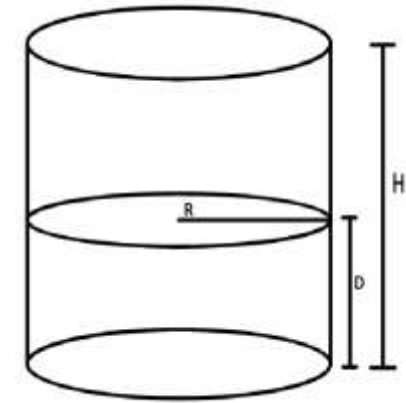
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Iowa State University**

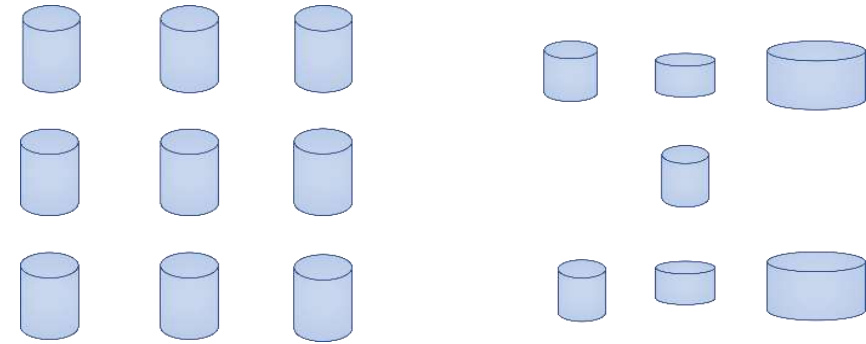
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- Problem description
- WEC Array Optimization
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Background/Research Question



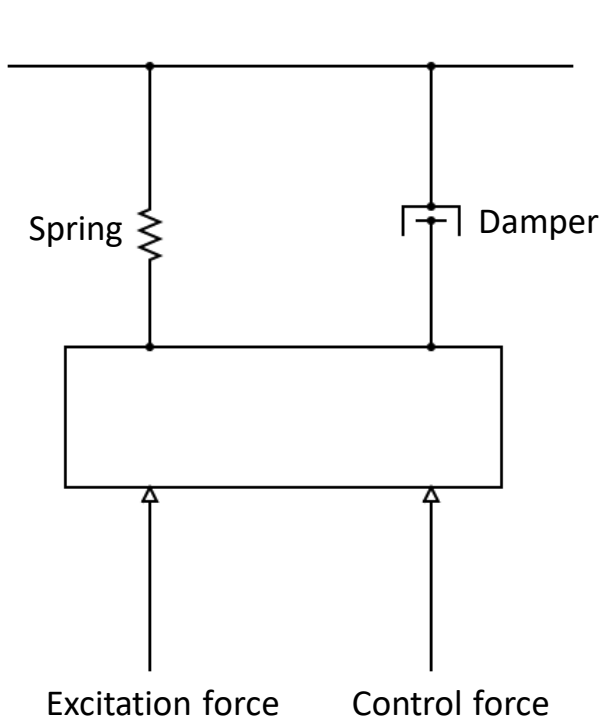
- The WEC dimensions are usually designed for the prevailing sea conditions in a particular location.
- Control co-design is desired.
- WEC arrays usually contain identical devices
- Can we optimize the dimensions and control to maximize the overall power absorption?



Hom. array Vs Het. array.

- How can we further improve performance by optimizing the number of devices in the array?

Dynamic Model: Spring-Mass-Damper Approximation



- Array dynamics

$$(M + M_\infty)\ddot{\vec{x}} + C_r\dot{\vec{x}} + K\vec{x} = \vec{f}_e - \vec{u}$$

- Hydrodynamic coefficients

$$M_\infty = \begin{bmatrix} m_{\infty 11} & \cdots & m_{\infty 1n} \\ \vdots & \ddots & \vdots \\ m_{\infty n1} & \cdots & m_{\infty nn} \end{bmatrix}$$

$$C_{r\omega} = \begin{bmatrix} Cr_{\omega 11} & \cdots & Cr_{\omega 1n} \\ \vdots & \ddots & \vdots \\ Cr_{\omega n1} & \cdots & Cr_{\omega nn} \end{bmatrix}$$

- A simple point absorber WEC

$$(m + m_\infty)\ddot{x} + C_r\dot{x} + kx = f_e - u$$

$$q - \text{factor} = \frac{P_{array}}{N * P_{isolated}}$$

Problem I: Homogenous array optimization

Homogenous array

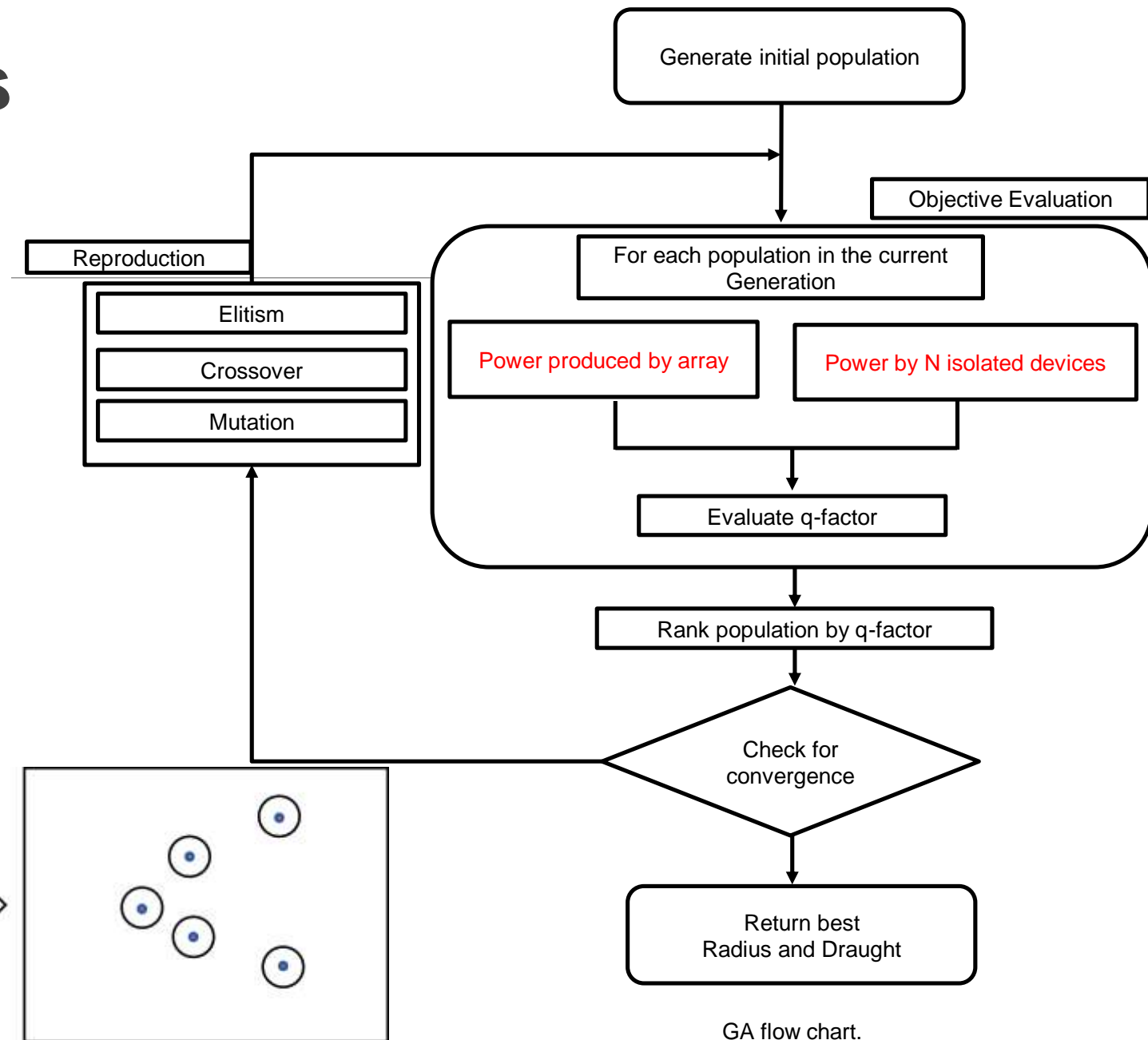
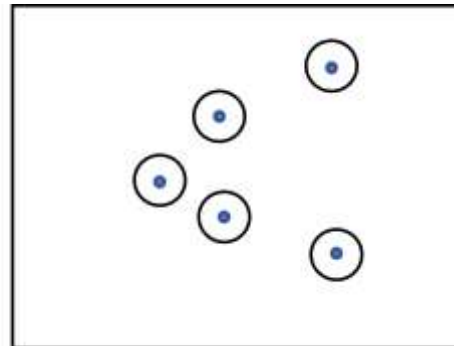
$$\text{Maximize: } q = \frac{P_{array}(R, D)}{N * P_{isolated}(R, D)}$$

Subject to:

$$R \in [R_{min}, R_{max}]$$

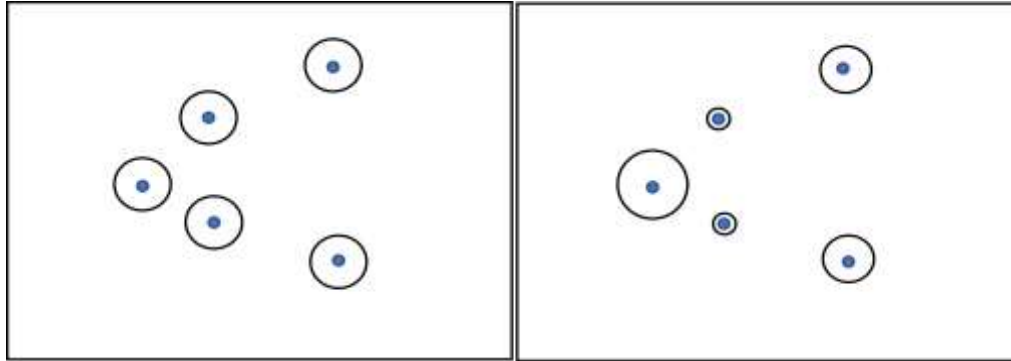
$$D \in [D_{min}, D_{max}]$$

Wave input →



GA flow chart.

Problem II: Heterogeneous array optimization



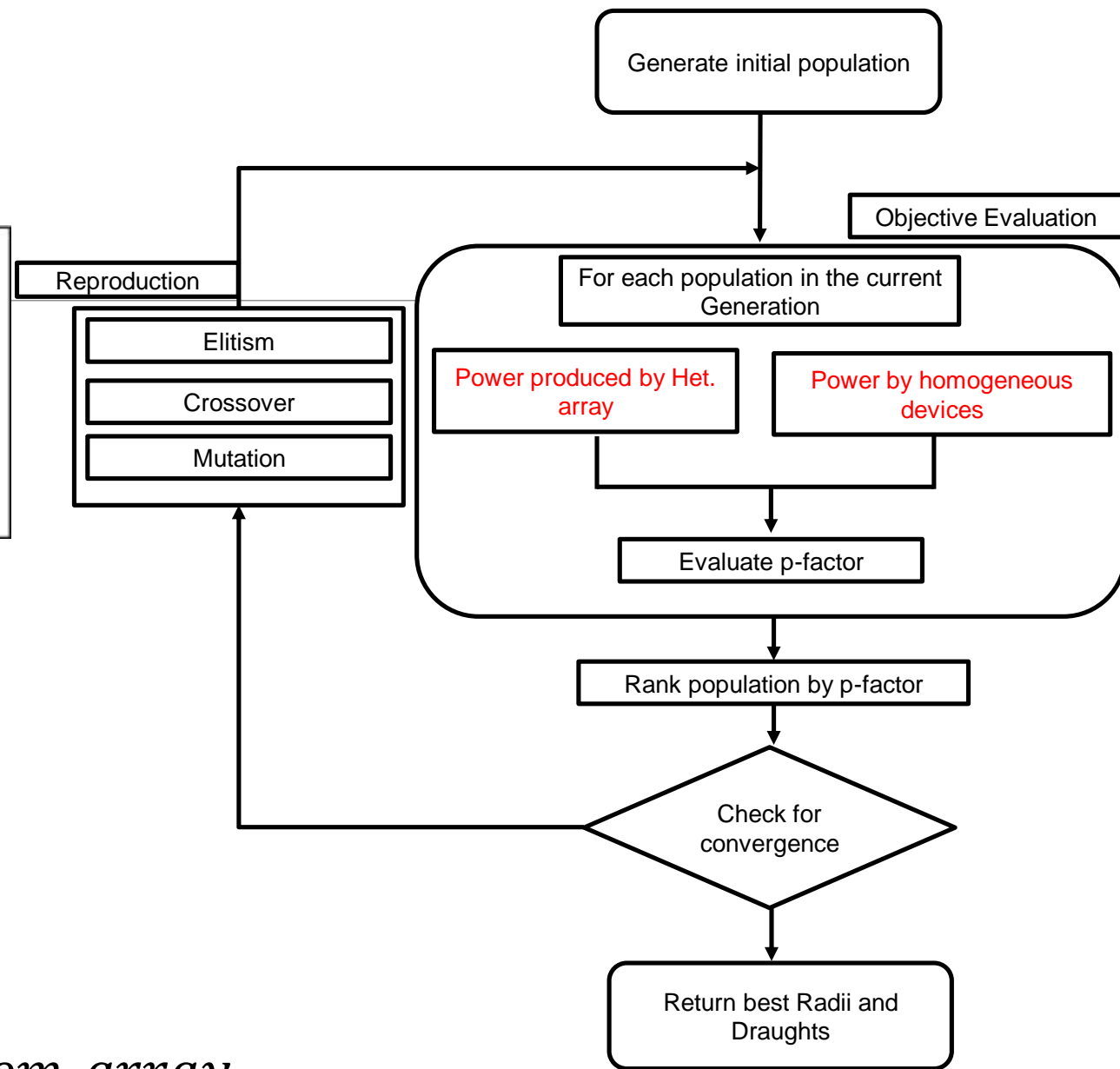
Heterogeneous array

$$\text{Maximize: } p = \frac{P_{\text{heterogeneous}}}{P_{\text{homogeneous}}}$$

Subject to:

$$R_i \in [R_{\min}, R_{\max}], D_i \in [D_{\min}, D_{\max}]$$

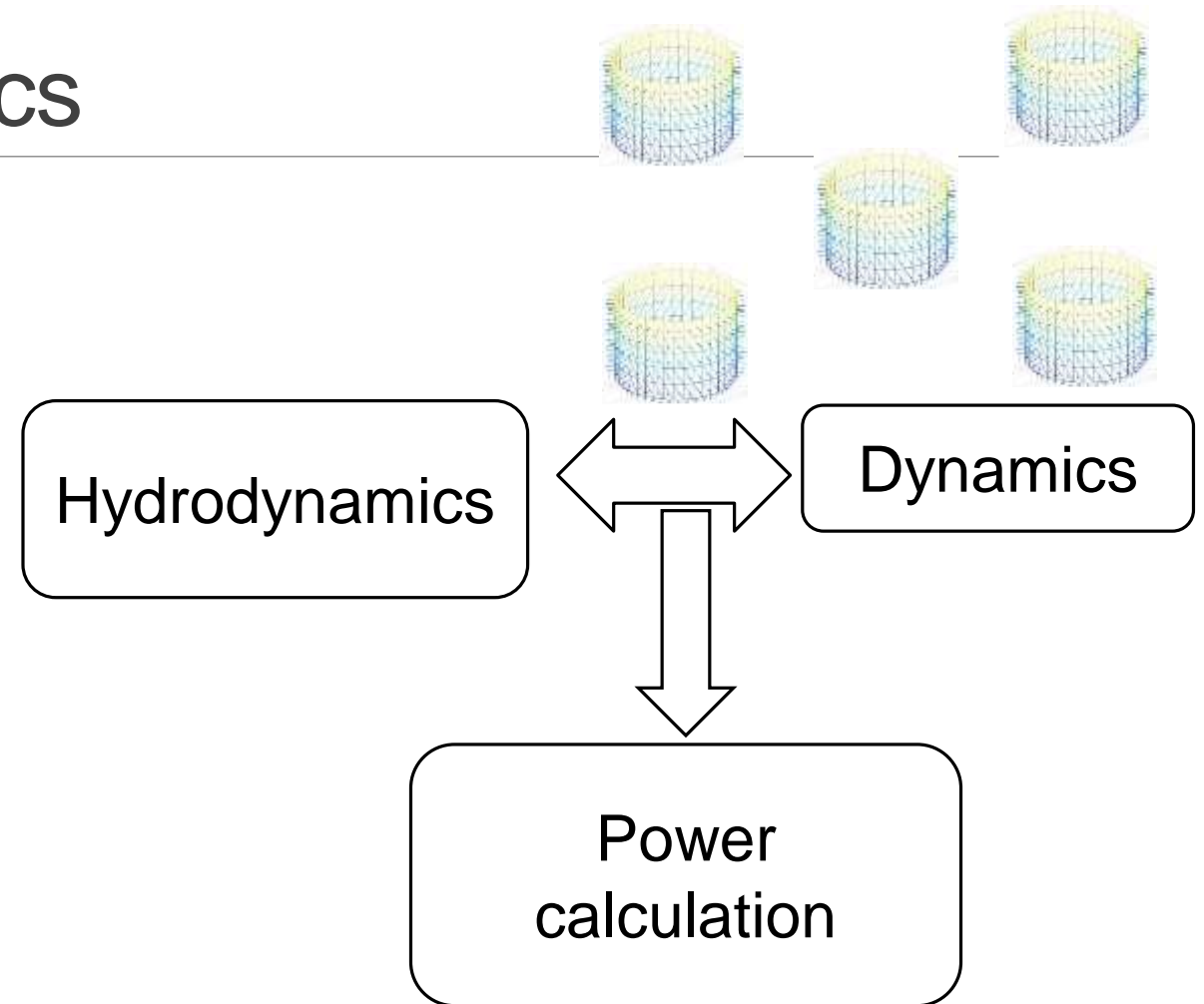
$$\text{Total Vol. of Het array} \leq \text{Total Vol. of Hom. array.}$$



GA flow chart.

WEC Array Hydrodynamics

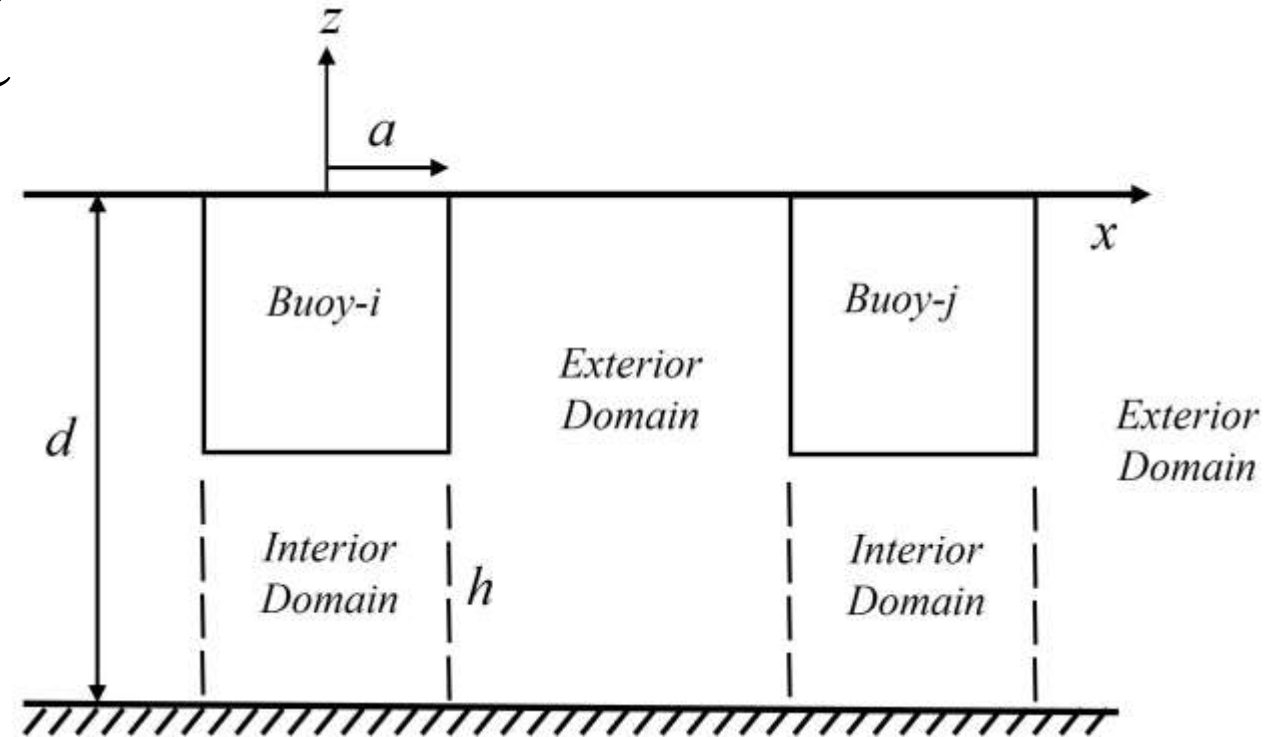
- We need to compute added mass, radiation damping coefficients, and excitation force coefficients.
- Boundary Element Methods tools vs. an approximate analytic method
- GA needs objective values only; qualitative conclusions on the objective values of different solutions are okay



Approximate analytic coefficients computation

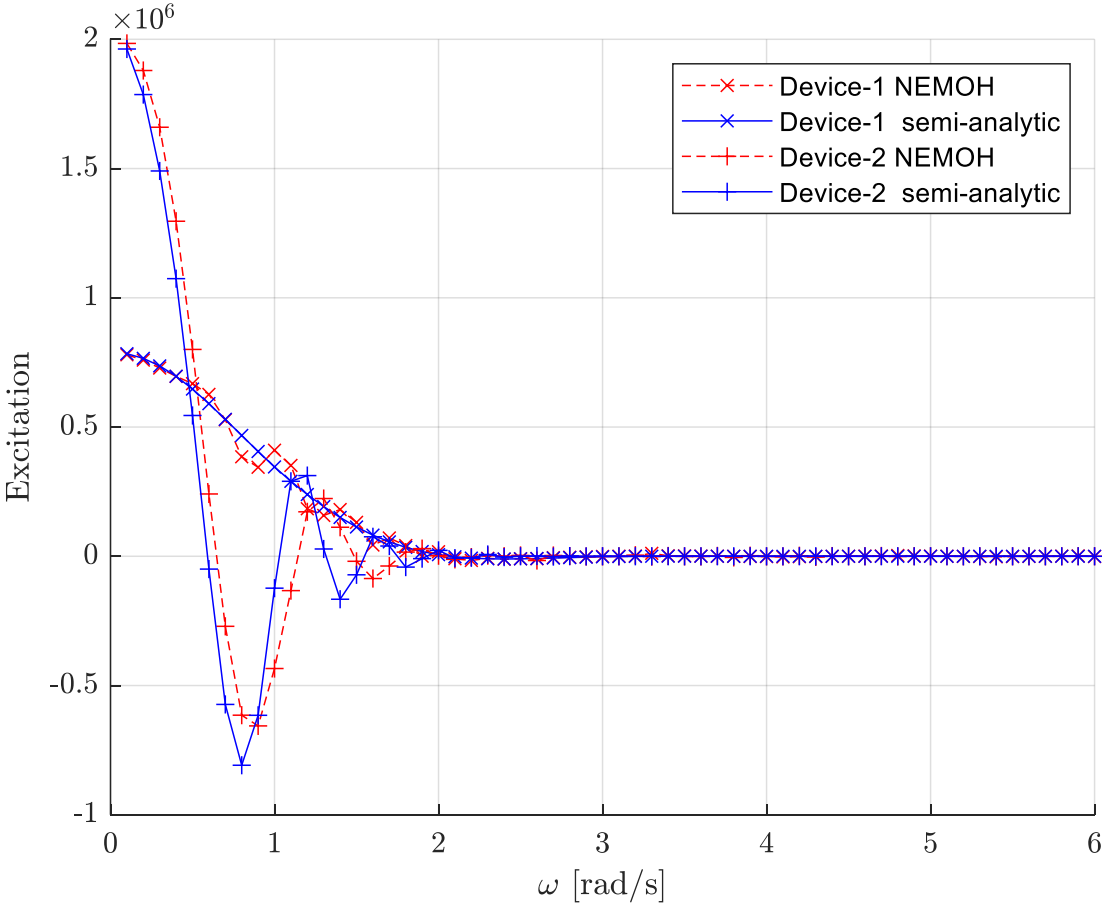
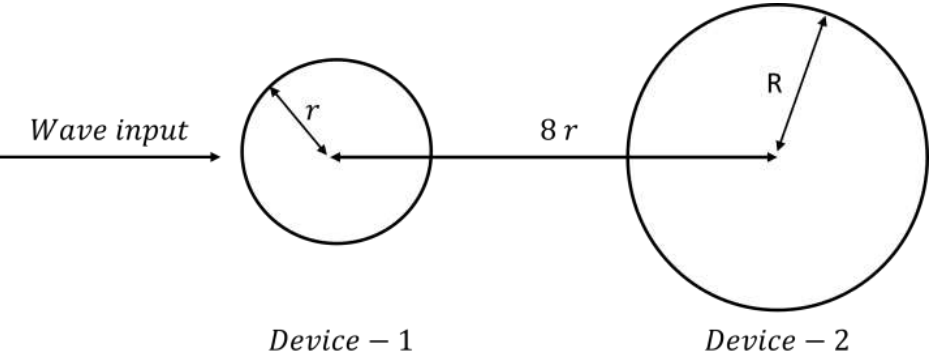
$$\phi(r, \theta, z) = \underbrace{\phi_0(r, \theta, z) + \phi_7(r, \theta, z)}_{\text{Diffraction}} + \underbrace{\sum_{q=1}^6 \phi_q(r, \theta, z)}_{\text{Radiation}}$$

➤ $\nabla^2 \phi = 0$

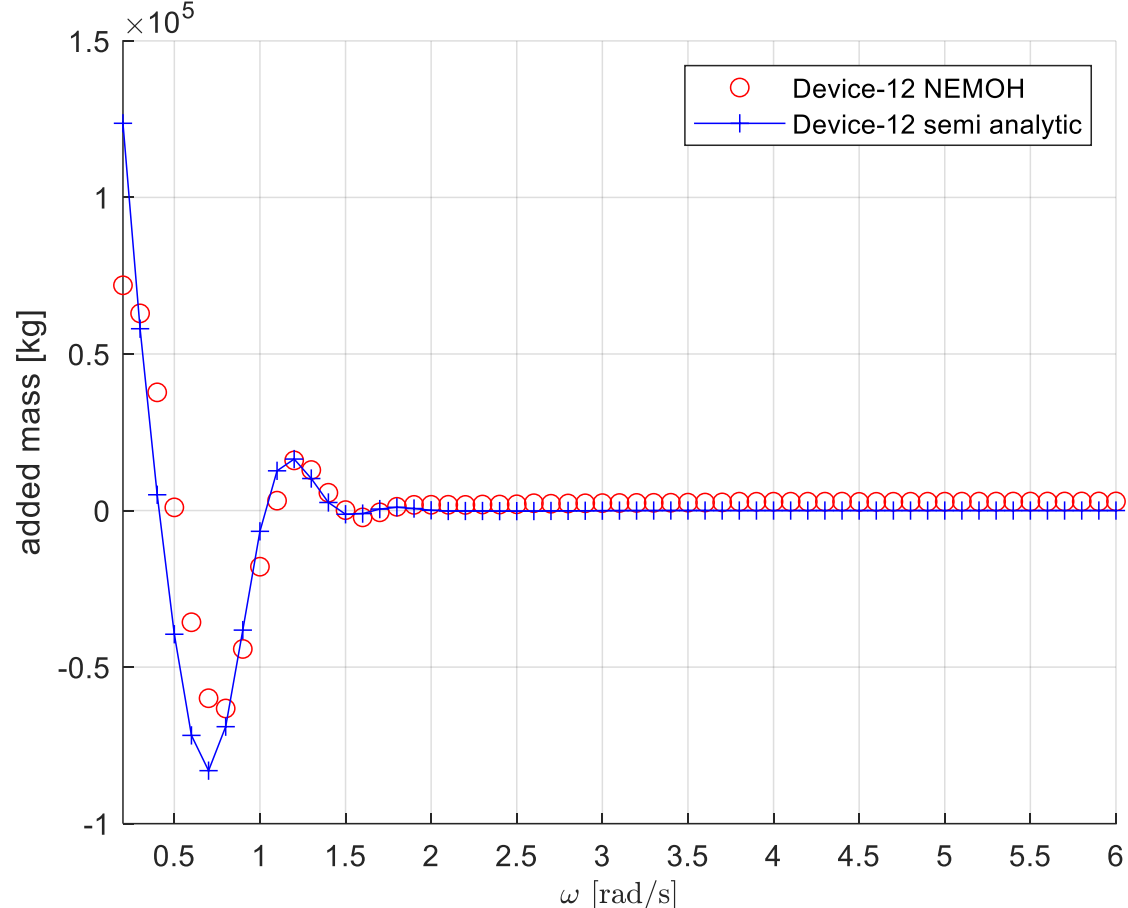
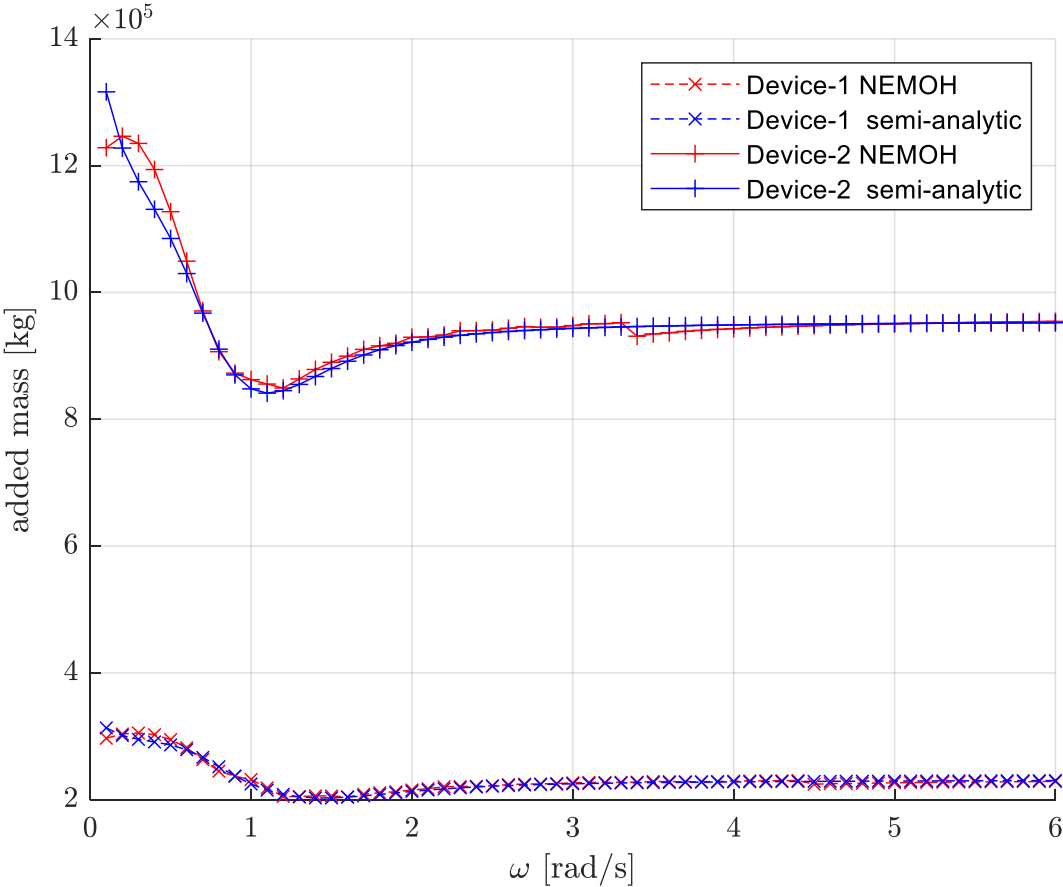


Fluid Domain.

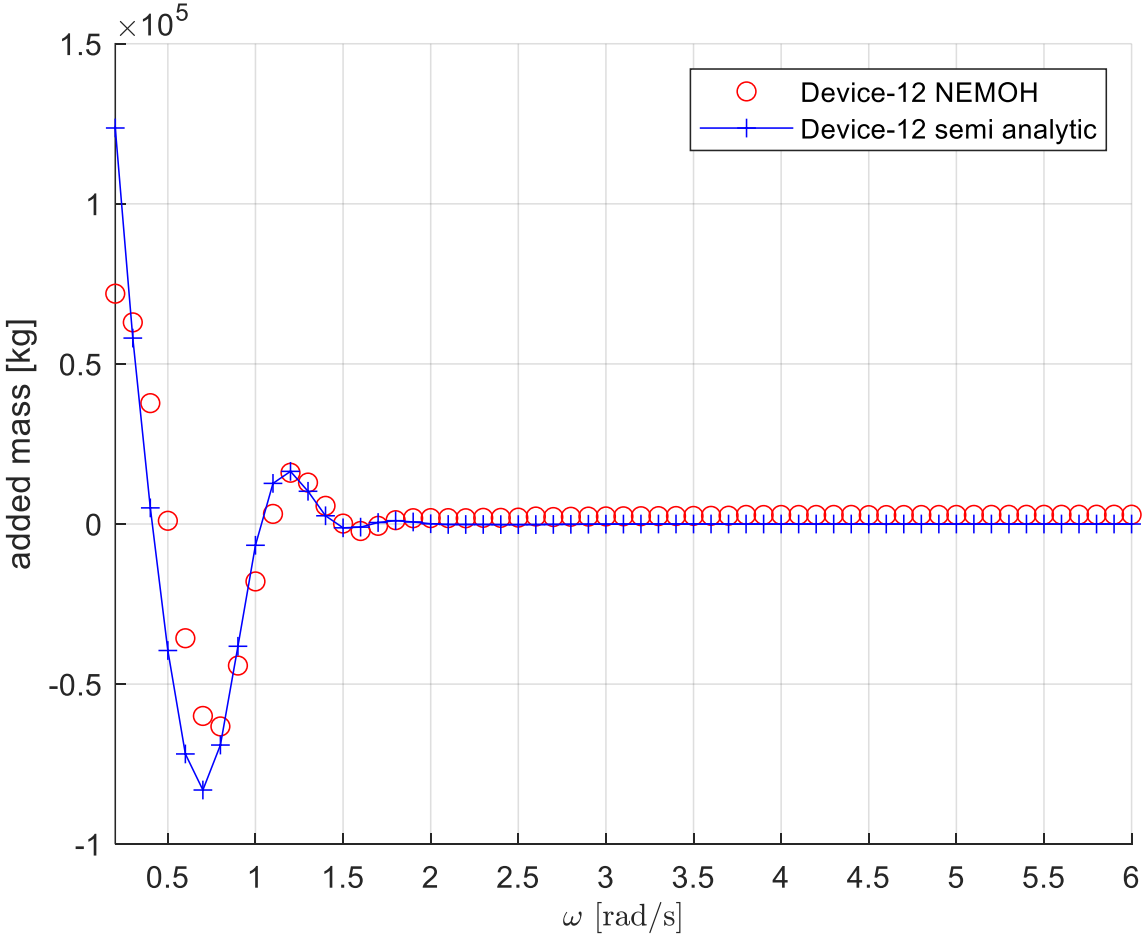
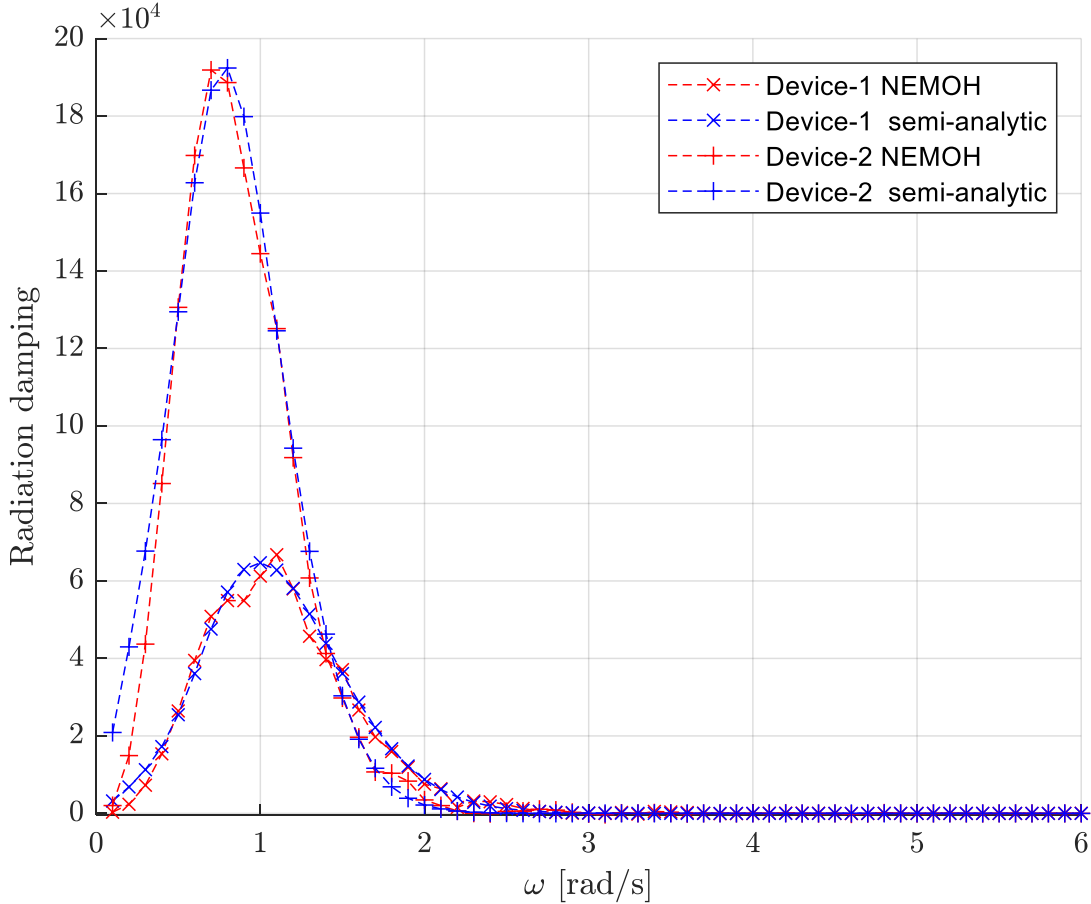
Validation of hydrodynamics



Validation of hydrodynamics



Validation of hydrodynamics



Computational speed

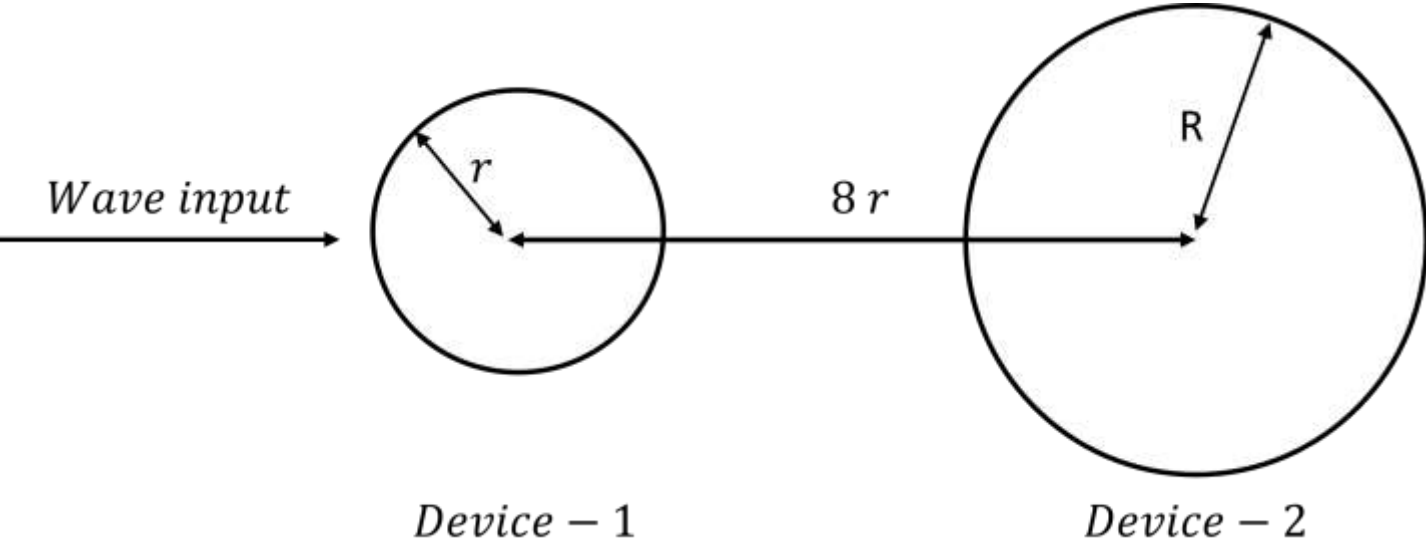
2 device array

	Semi Analytic	Nemoh
2	4.18226 s	113.814748 s

7 device array

	Semi Analytic	Nemoh
7	13.9748 s	2912.662 s (48 mins)

The radii are, $r = 5\text{ m}$, $R = 8\text{ m}$,
 draughts $h = 8\text{ m}$, $H = 7\text{ m}$.



Control Force



1

- The objective function:

$$\text{Minimize: } J(u(t), x_2(t)) = \sum_{n=1}^N \int_0^t \{-u_n(t) * x_{2n}(t)\} dt$$

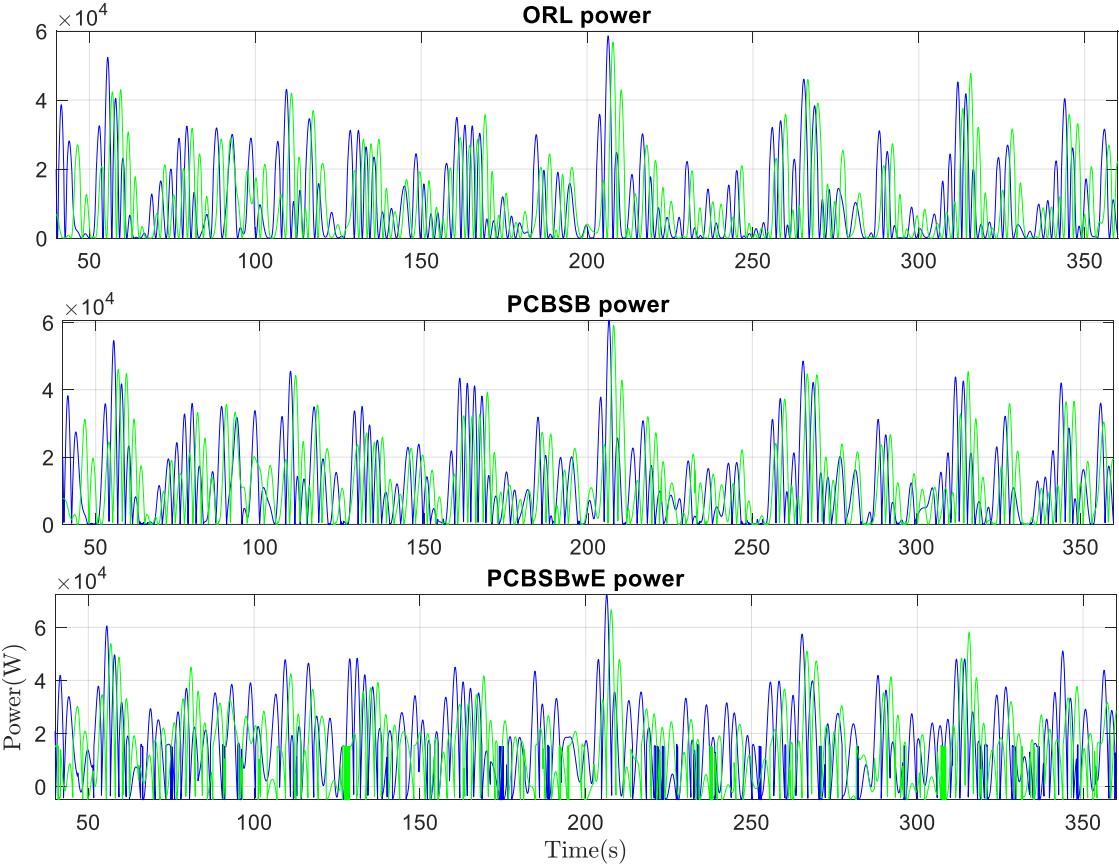
- Subject to EOM:

$$\begin{aligned} \dot{\vec{x}}_1 &= \vec{x}_2 \\ \dot{\vec{x}}_2 &= \frac{1}{M} (\vec{f}_e(x_3) - C\vec{x}_2 - K\vec{x}_1 - \vec{u}) \\ x_3 &= 1 \end{aligned}$$

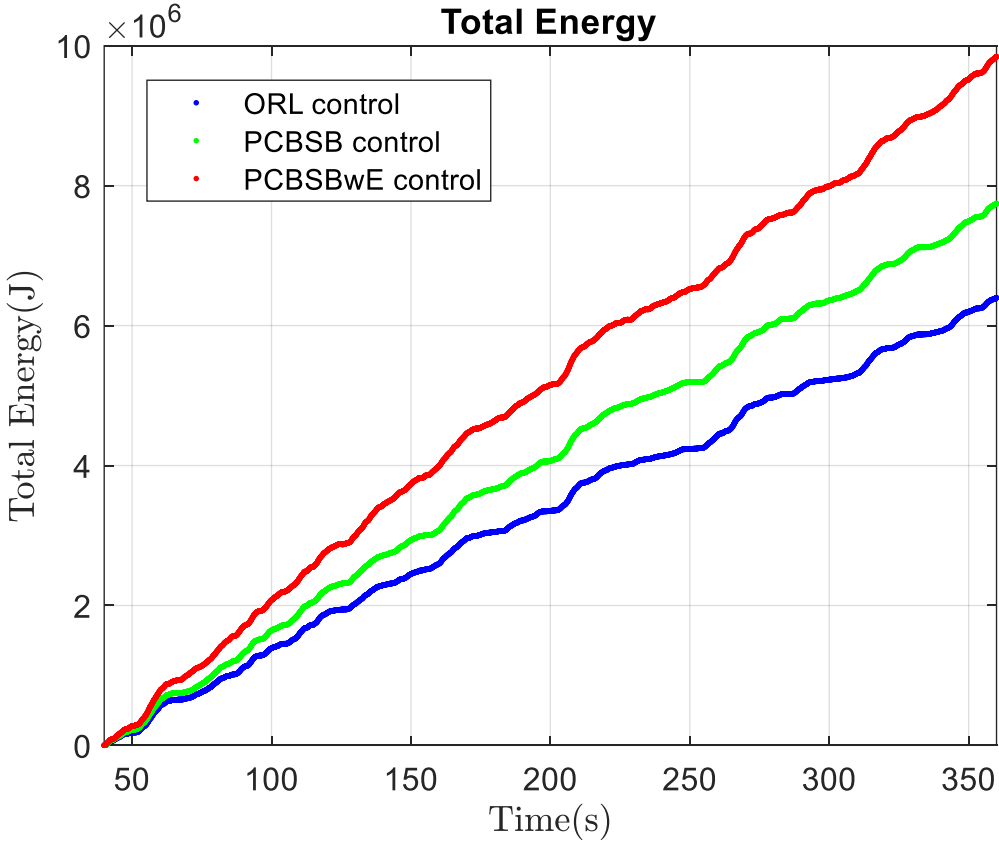
- The power constraints and control constraints:

$$\vec{u}(t) * \vec{x}_2(t) \geq -\vec{\epsilon} , \quad |\vec{u}(t)| \leq \vec{\Gamma}$$

Control Force and Power Computation



Power when using ORL and PCBSB.



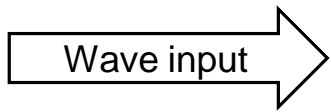
Energy extracted when using ORL and PCBSB.

Simulation

The simulation parameters are as follows:

- Wave condition: $T = 6s, H = 0.8222 m$. (**site**: Newport, Oregon)
- (*Radius and draught*) Upper Bound = 10 m.
- (*Radius and draught*) Lower Bound = 1m.
- Hydrodynamic parameters are calculated using the approximate analytic method.
- Power from the array is computed using the constrained control PCBSB

Homogenous array result – 3 Devices



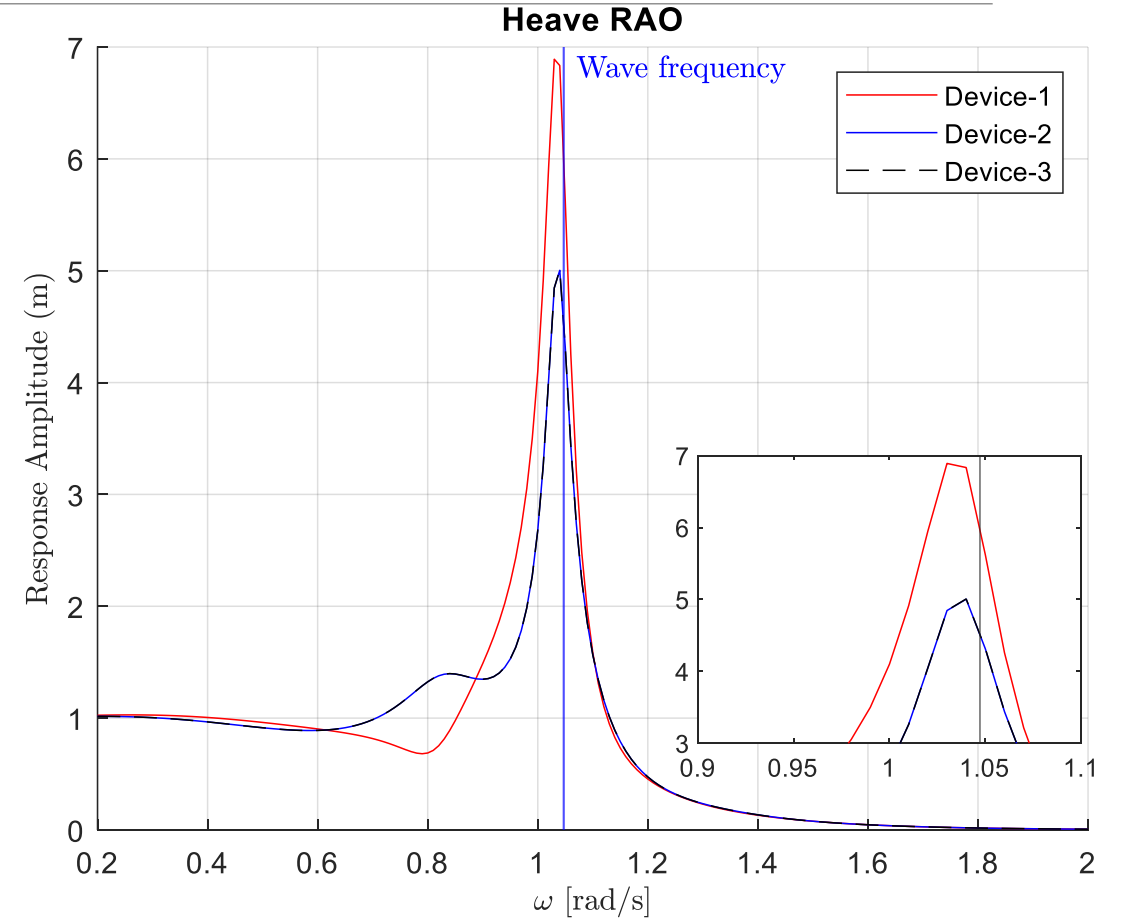
2

1

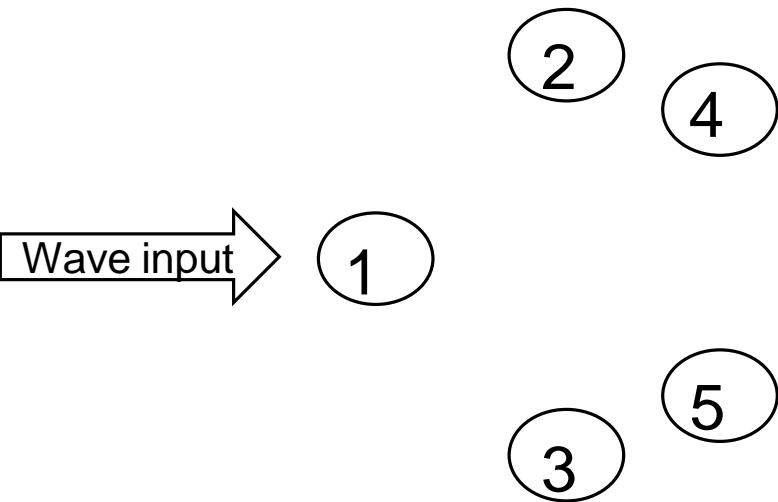
3

	X (m)	Y (m)
1	0	0
2	0	40.255
3	0	-40.255

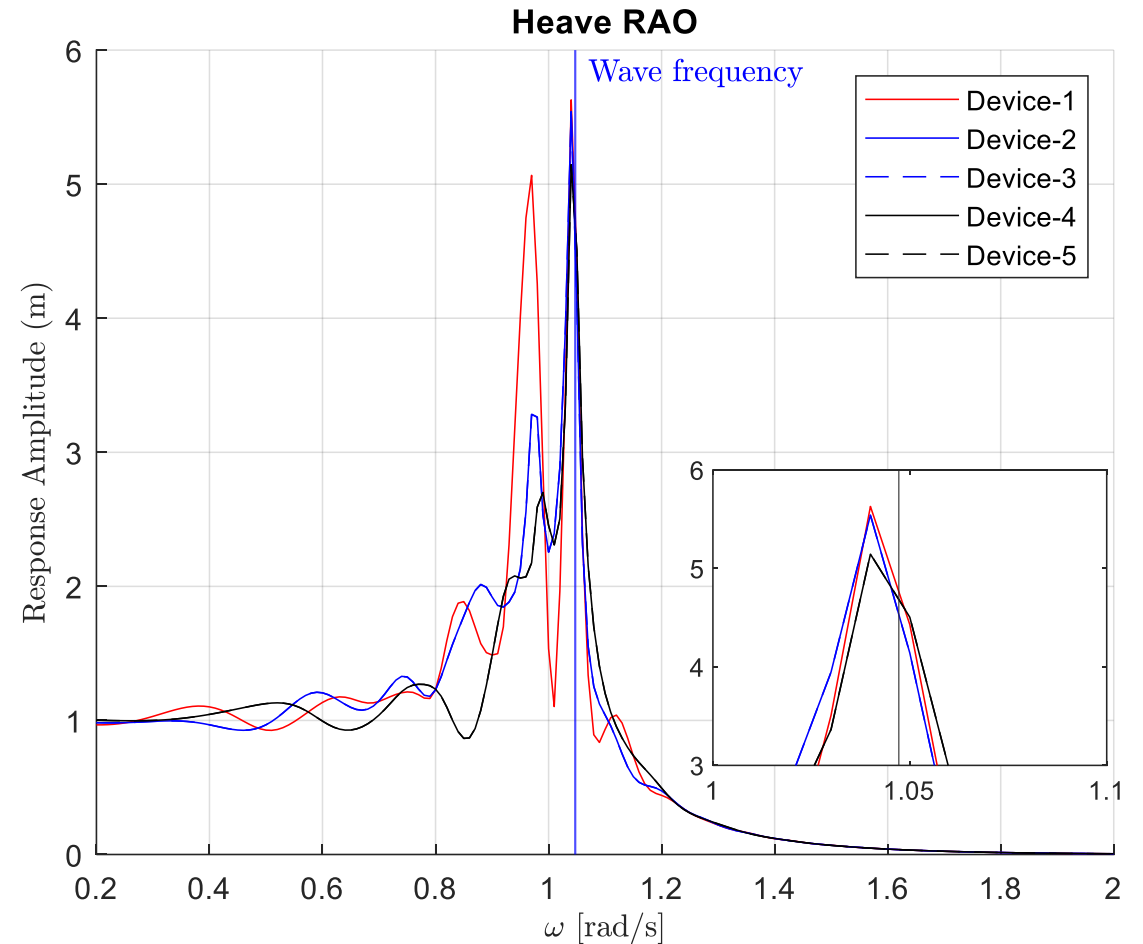
- Optimized Radius: $R = 7.2249 \text{ m}$



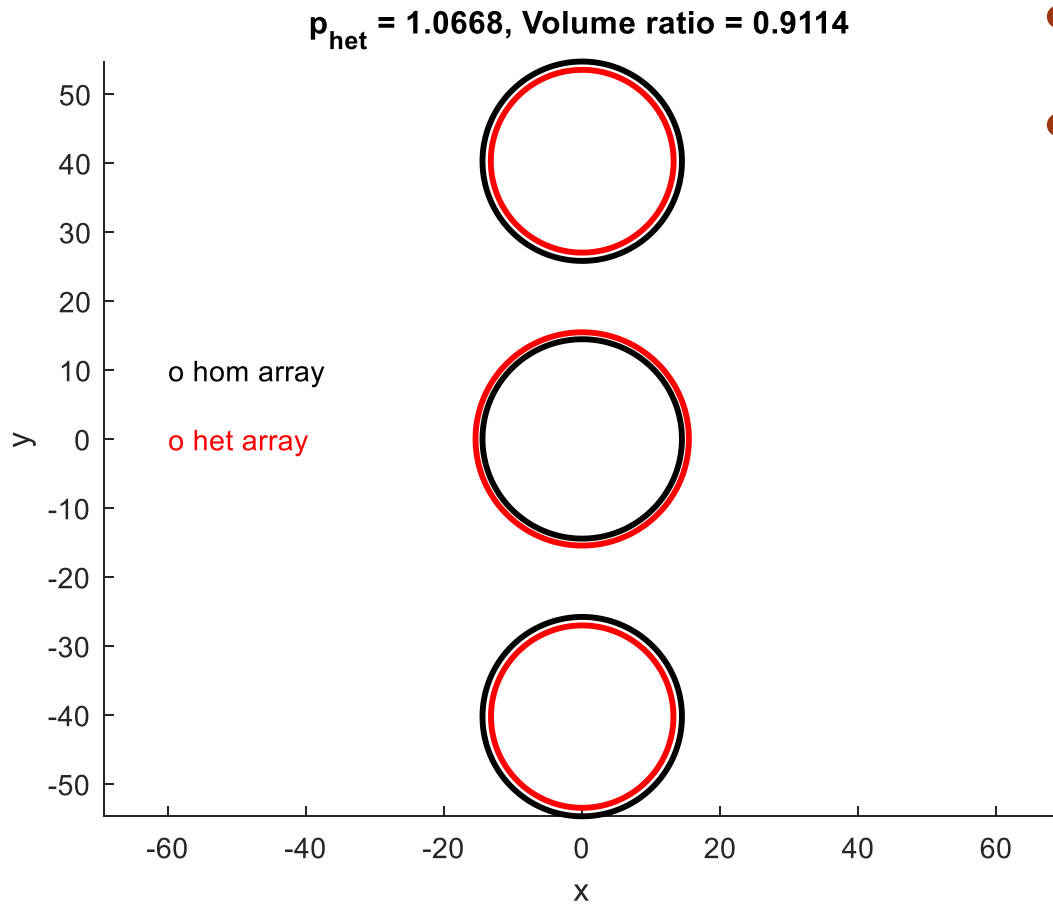
Homogenous array result – 5 Devices



- Optimized Radius: $R = 6.1196\text{m}$



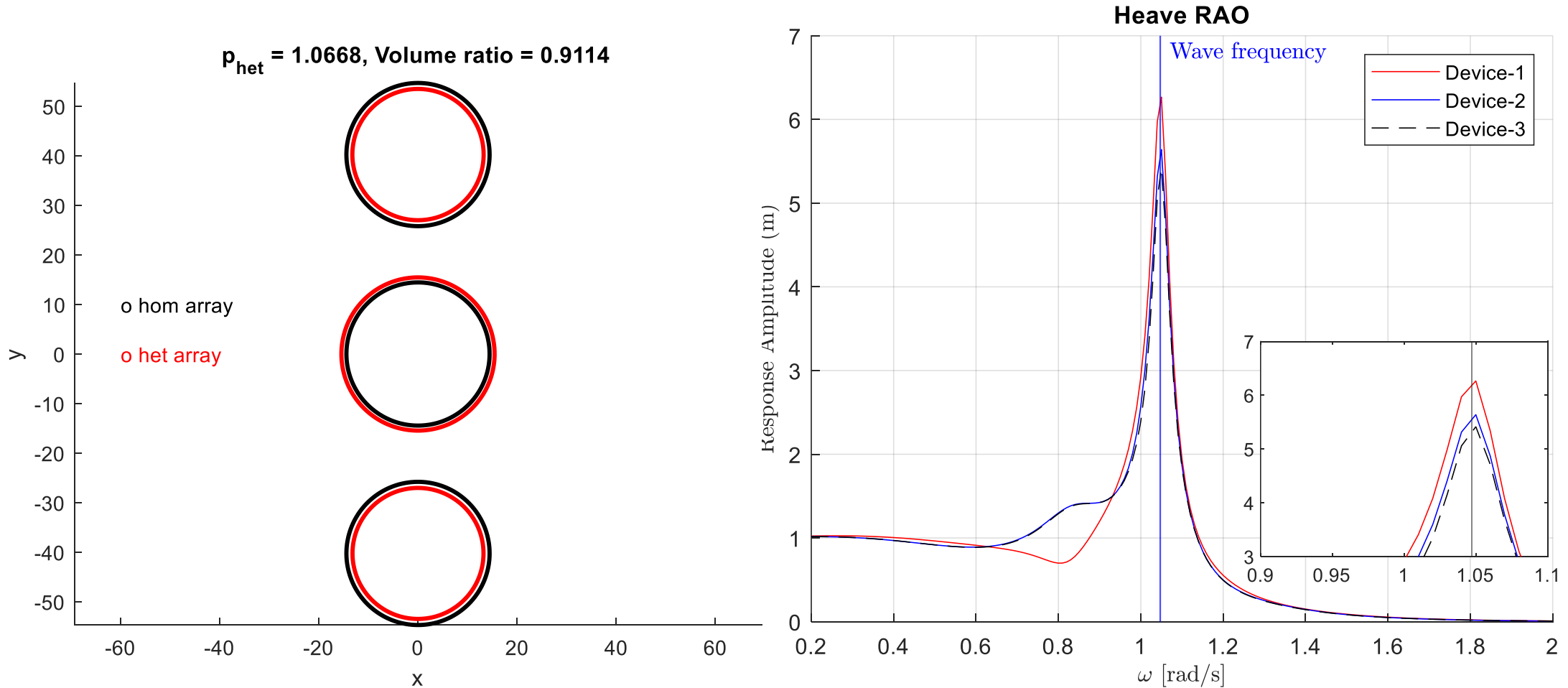
Heterogeneous array result: 3 devices



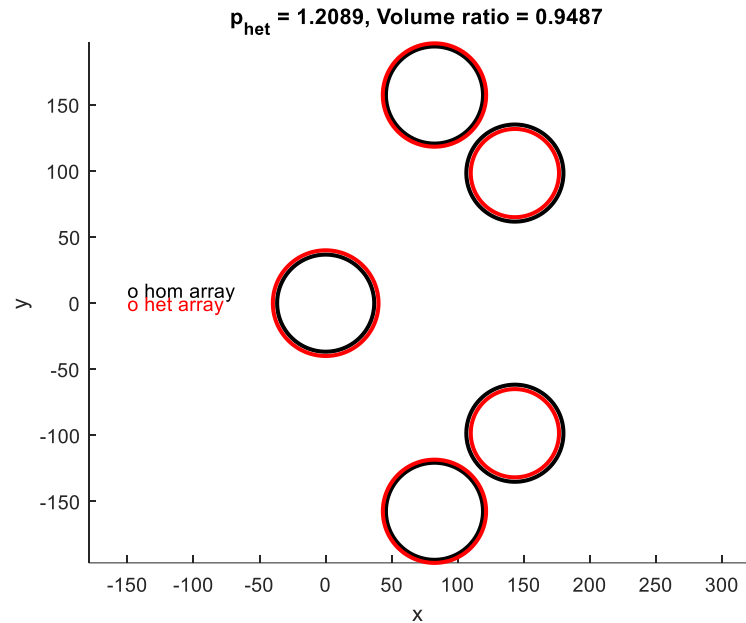
- Optimized dimensions
- *Homogeneous*: $R = 7.2249\text{ m}$

R1	R2	R3	p
7.7297	6.6232	6.6095	1.0668
7.7527	6.6143	6.6214	1.0667

Heterogeneous array result: 3 devices



Heterogeneous array result: 5 devices

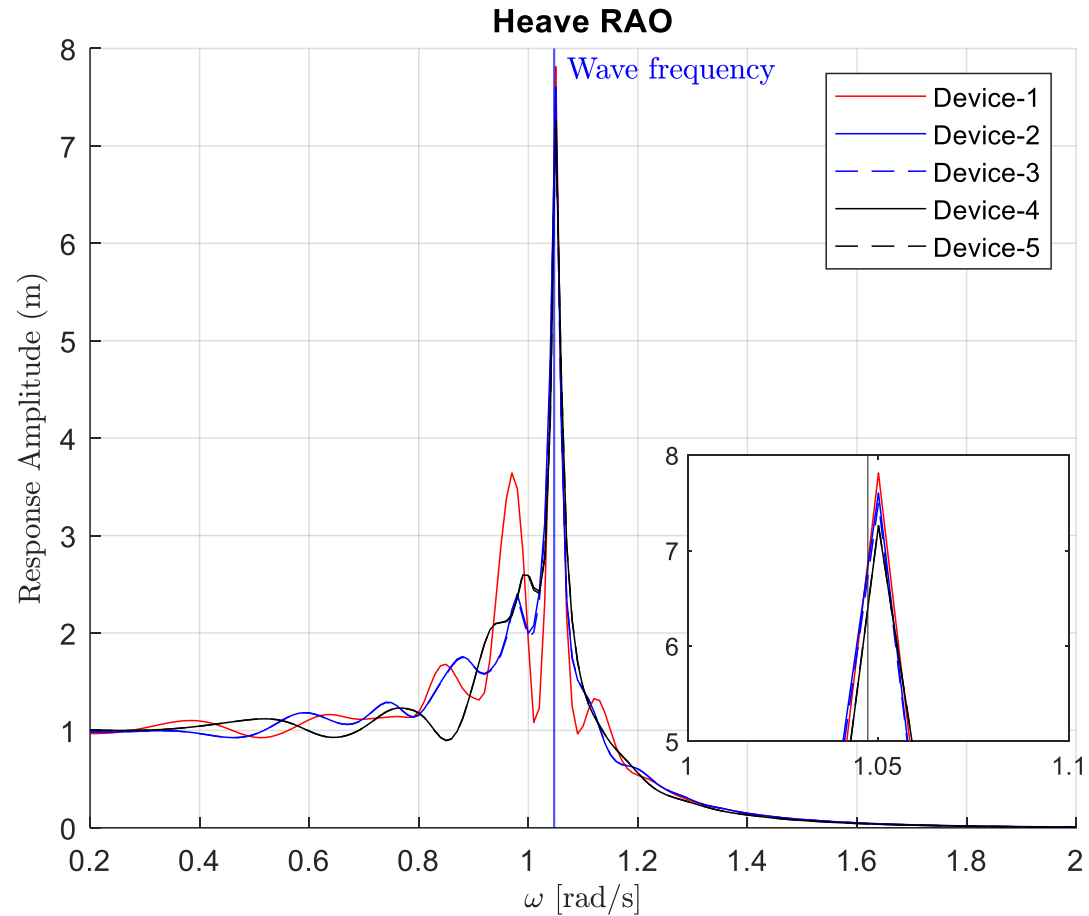
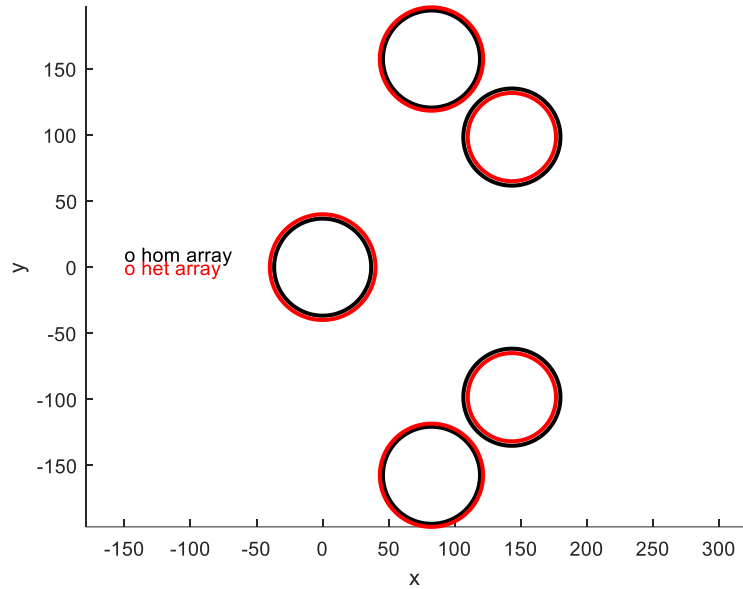


- Optimized dimensions
- Homogeneous: $R = 6.1196 m$

R1	R2	R3	R4	R5	p
6.6600	6.5131	6.5064	5.5635	5.5623	1.2089
6.6368	6.4822	6.4776	5.5457	5.5254	1.2087

Heterogeneous array result: 5 devices

$\rho_{\text{het}} = 1.2089$, Volume ratio = 0.9487

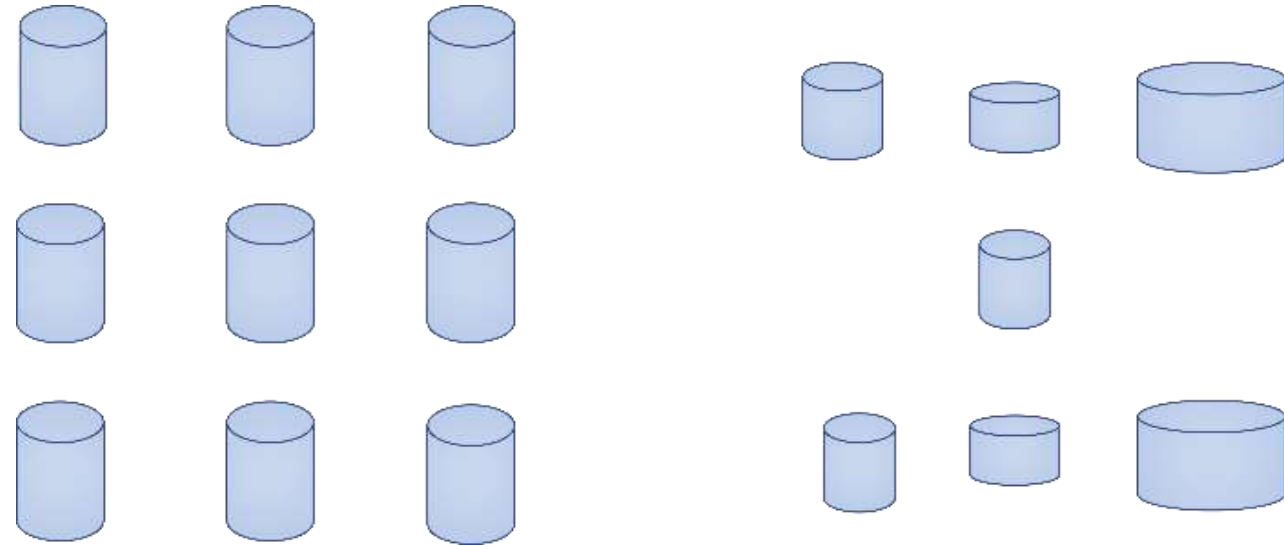


Problem III: HGGA-Heterogenous array optimization

Heterogeneous array

$$\text{Maximize: } p = \frac{P_{\text{heterogeneous}}}{P_{\text{homogeneous}}}$$

Subject to:

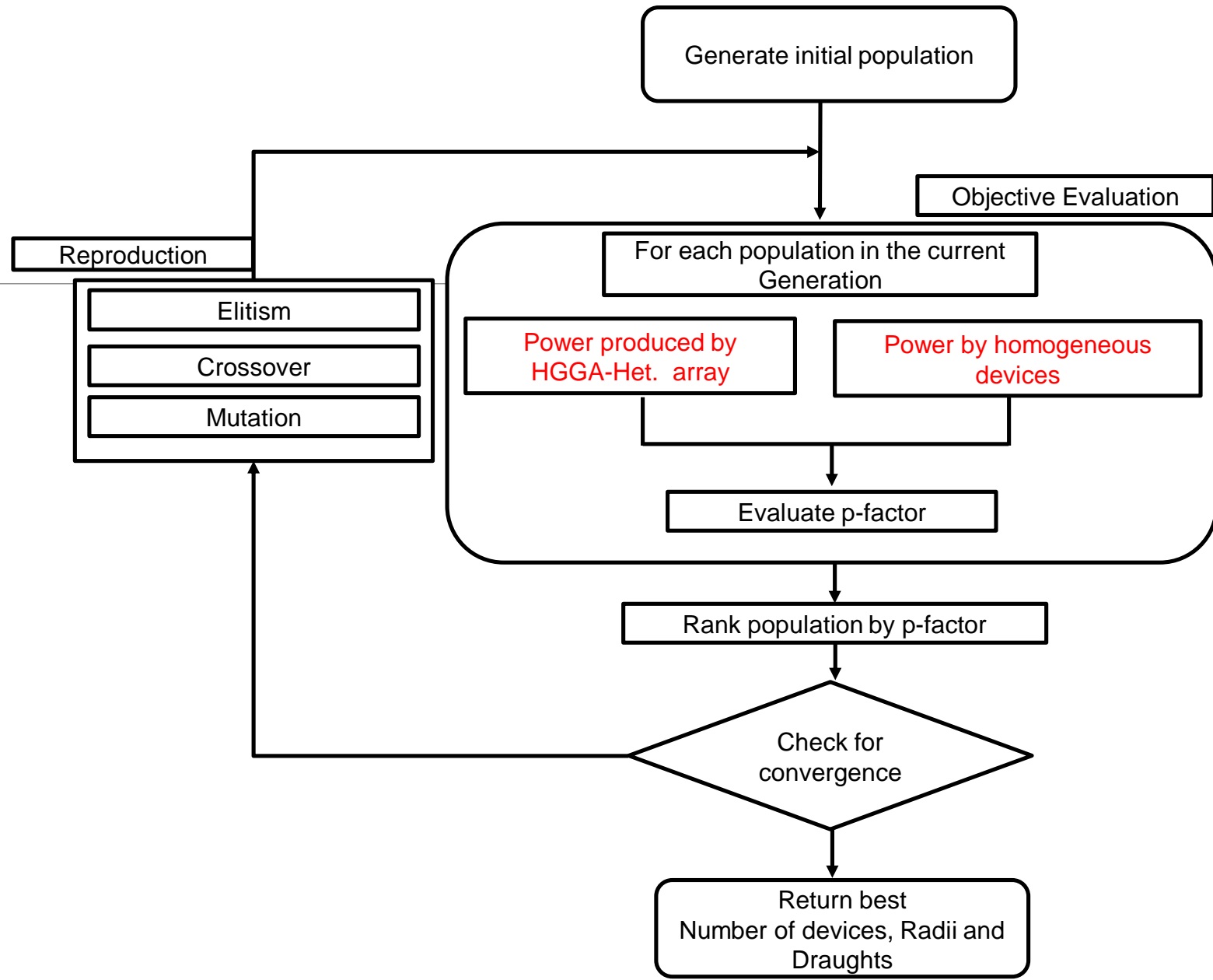


Hom. array Vs Het. array.

$$R_i \in [R_{\min}, R_{\max}], D_i \in [D_{\min}, D_{\max}], N \in [1, N_{\text{homogenous}}]$$

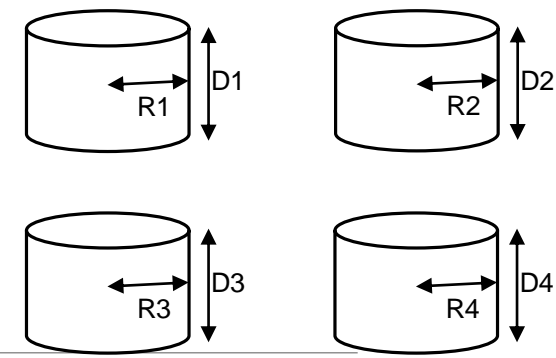
$$\text{Total Vol. of Het array} \leq \text{Total Vol. of Hom. array.}$$

Problem III: HGGA-Heterogenous array optimization



GA flow chart.

Hidden Genes GA (HGGA)



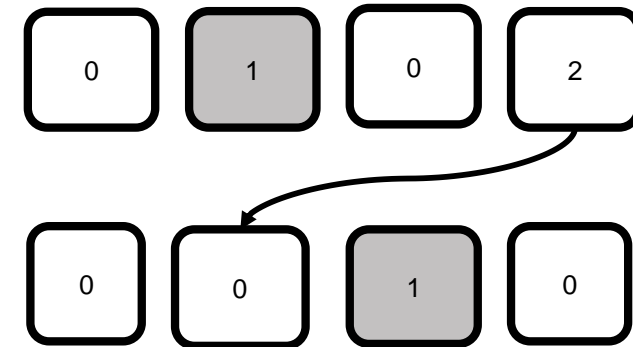
HGGA

- A variation on GA that allows optimizing the number of design variables, simultaneously with the variables.



Example of 4 WECs

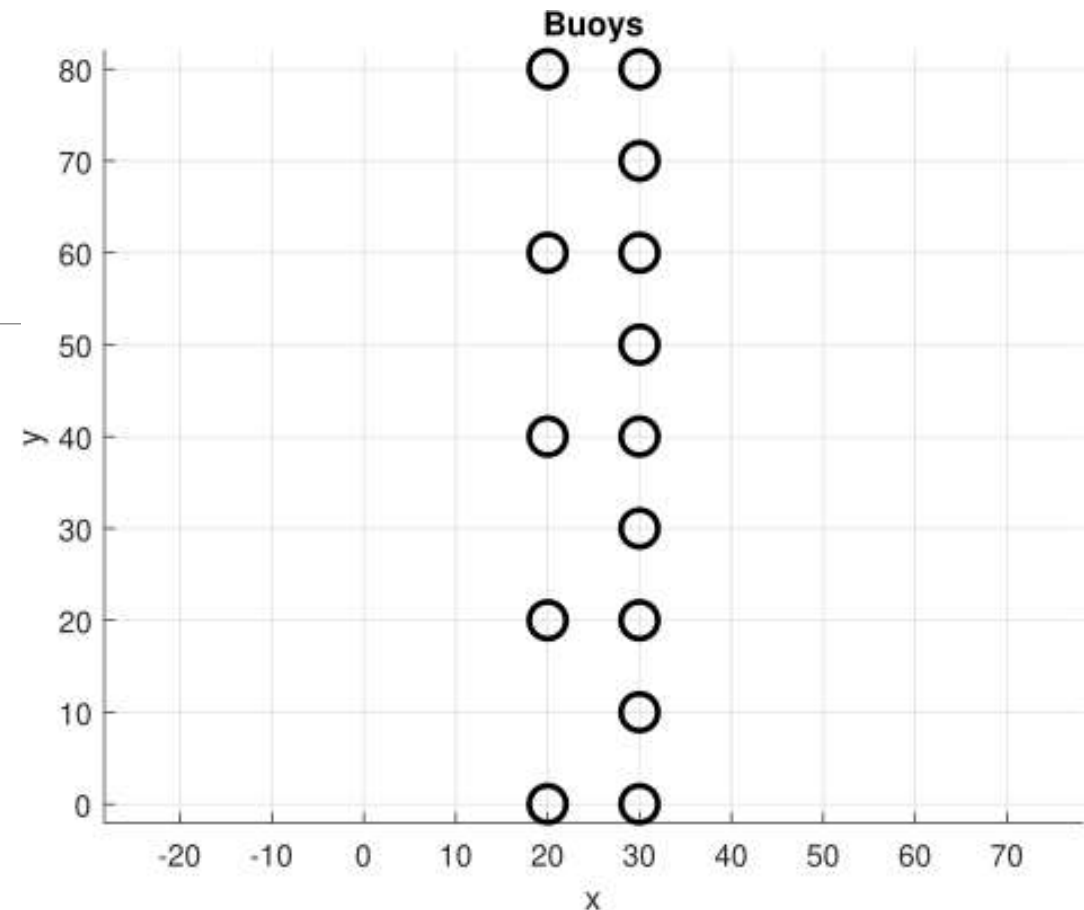
- A maximum of 4 WECs
- Variables: Radius R1 – R4, Draughts D1 – D4, and tags.



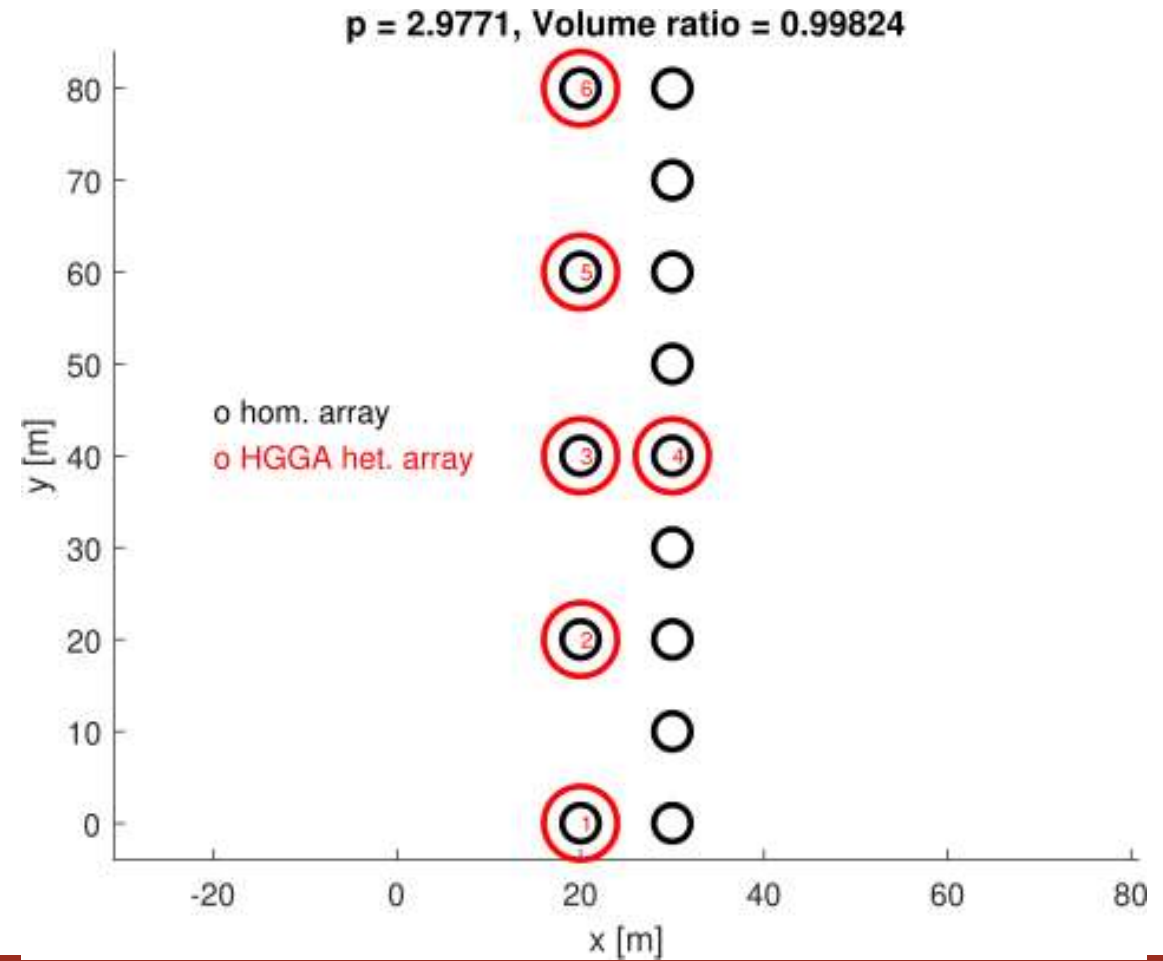
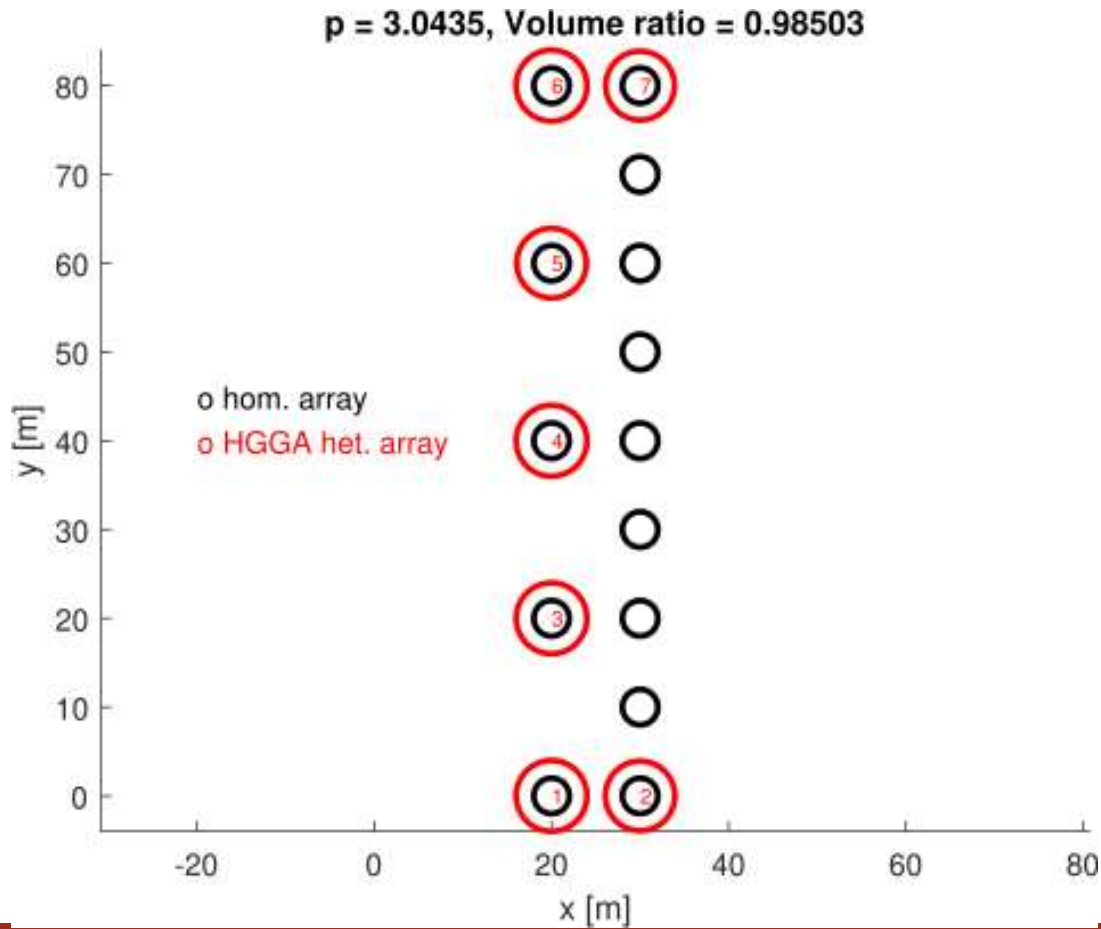
Homogeneous Array from literature

- Test case from Giassi 2018.
- $R = 2$ m, draft $d = 0.5$ m, and water depth $h = 25$ m.
- Wave site in Lysekil on the Swedish west coast.
- Regular wave, wave height $H = 1.53$ m , period $T = 5.01$ s.
- Wave propagating along the x-axis.

$$\text{Maximize: } p = \frac{P_{\text{heterogeneous}}}{P_{\text{homogeneous}}}$$



HGGA-Heterogeneous array result



Conclusion

- Investigated increasing power by allowing devices of different dimensions in the same array.
- Could allow the number of devices to vary during optimization
- Heterogenous arrays can produce more power while reducing total volume of buoys.

Acknowledgements

- This paper is based upon work supported by NSF, Grant Number 2048413.
- Authors would like to thank the collaborators from Maynooth University and Queens University Belfast for their input feedback: John Ringwood, Oliver Mason, Andrei Ermakov, and Pal Schmitt.

Questions

Semi-analytic hydro coefficients

- In the whole fluid domain, the governing equation $\nabla^2 \phi = 0$
- Boundary conditions:
 - Free surface boundary conditions $\omega^2 \phi - g \frac{\partial \phi}{\partial z} \Big|_{z=0} = 0$
 - Seabed condition $\frac{\partial \phi}{\partial z} \Big|_{z=-d} = 0$
 - Impermeable surface condition on the body surface
 $\frac{\partial \phi}{\partial r} = 0, (r = a, -h \leq z \leq 0), \frac{\partial \phi}{\partial z} = 0, (0 \leq r \leq a, z = -h)$
 - Sommerfeld radiation condition $\lim_{x \rightarrow \infty} \sqrt{r} \left(\frac{\partial \phi}{\partial r} - ik_n \phi \right) = 0$

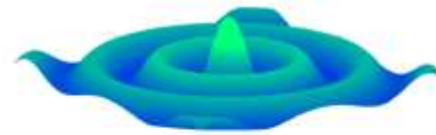
Radiation: exterior potential functions

➤ The homogenous potential function

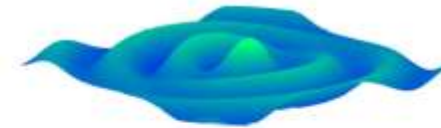
$$\phi_{3,h}^E = D_{R0} \frac{H_m(k_0 r)}{H_m(k_0 a)} + \sum_{q=1}^{\infty} D_{Rq} \frac{K_m(k_q r)}{K_m(k_q a)}$$

$$\phi_{3,p}^E = 0$$

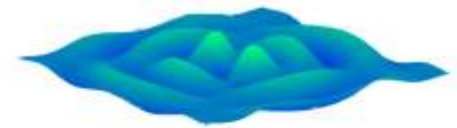
Progressive and evanescent waves.



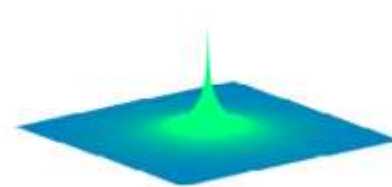
(a) $m = 0, n = 0$



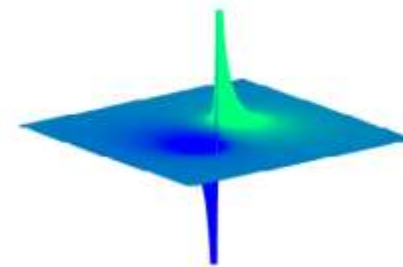
(b) $|m| = 1, n = 0$



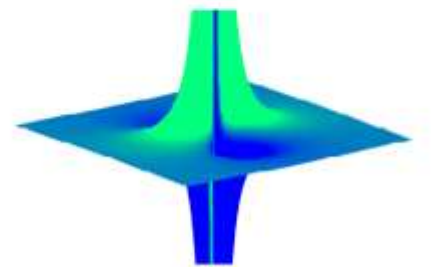
(c) $|m| = 2, n = 0$



(d) $m = 0, n = 1$



(e) $|m| = 1, n = 1$



(f) $|m| = 2, n = 1$

Radiation: Interior potential functions

- Based on the methods of variable separation and matching eigenfunction expansion for the velocity potential.
- Separation of variables : $\phi_{3,m}^I(r, z) = \phi_{3,h}^I + \phi_{3,p}^I$
- The homogenous potential function

$$\phi_{3,h}^I = \frac{C_{R0}}{2} \left(\frac{r}{a}\right)^m + \sum_{n=1}^{\infty} C_{Rn} \frac{I_m\left(\frac{n\pi r}{(d-h)}\right)}{I_m\left(\frac{n\pi a}{(d-h)}\right)} \cos\left(\frac{n\pi z}{(d-h)}\right)$$

- The particular solution

$$\phi_{3,p}^I = \frac{1}{2(d-h)} \left[(z+d)^2 - \frac{r^2}{2} \right]$$

Continuity conditions

- In both the radiation and diffraction problems, the matching conditions represent the **continuity of mass flux, pressure and normal velocity**.
- The velocity potentials between interior and exterior domains are **matched at the imaginary boundary ($r = a$)**.

$$\phi^I = \phi^E, \quad \frac{\partial \phi^E}{\partial r} = \frac{\partial \phi^I}{\partial r} \quad (-h \leq z \leq -d), \quad \frac{\partial \phi^E}{\partial r} = 0, \quad (-h \leq z \leq 0),$$

- The **unknown Fourier coefficients** C_n, D_n, C_{Rn}, D_{Rn} are solved using the matching conditions.
- The hydrodynamic coefficients are found by **integrating the potential functions over their corresponding area**.