



# Differentiable Hydrodynamics

for Optimization and Sensitivity Analysis

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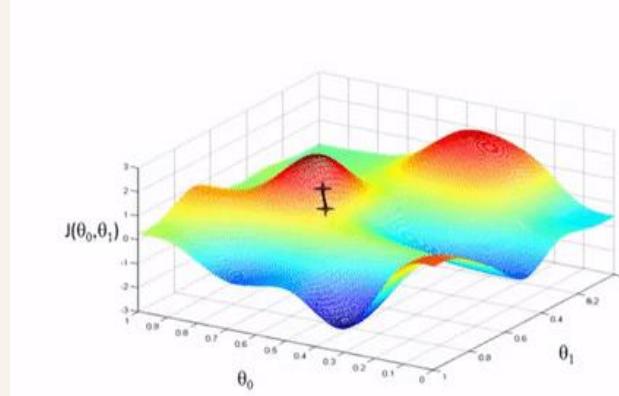
- a. Sandia National Laboratories,
- b. Cornell University
- c. Eurobios Mews Lab



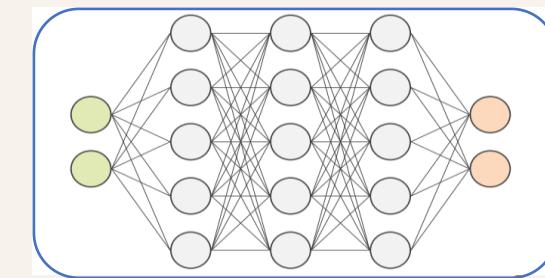
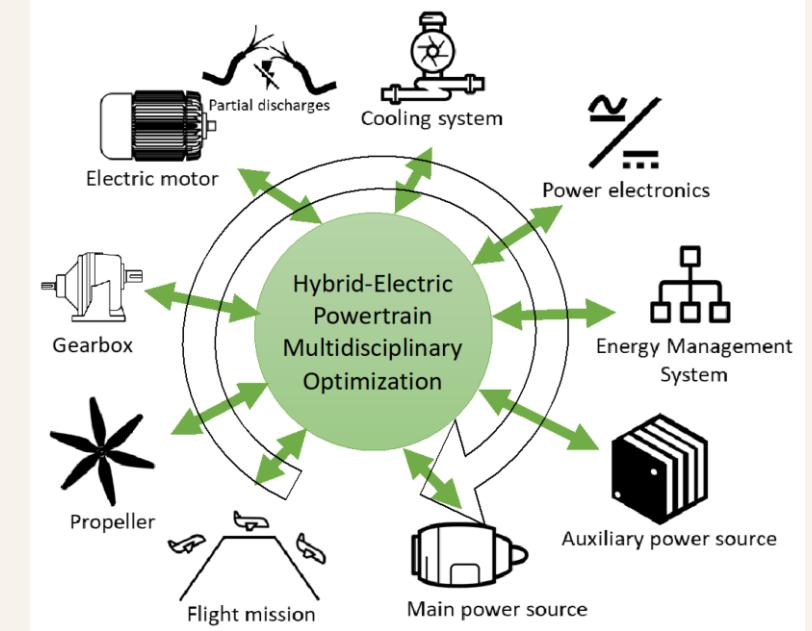
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# Why $\nabla$ Hydrodynamics?

- Adjoint-based optimization
  - Large multi-disciplinary optimization (MDO)
  - Non-parametric geometry optimization
- Control co-design
- Physics-Informed Machine Learning



Andrew Ng



$$\begin{aligned} \mathbf{u} \cdot \nabla \mathbf{u} - \nu \nabla^2 \mathbf{u} + \nabla \cdot \boldsymbol{\tau} + \nabla p - \mathbf{g} &= \mathbf{0} \\ \nabla \cdot \mathbf{u} &= 0 \end{aligned}$$

# Automatic Differentiation

$$f' = \frac{f(x+h) - f(x)}{h}$$

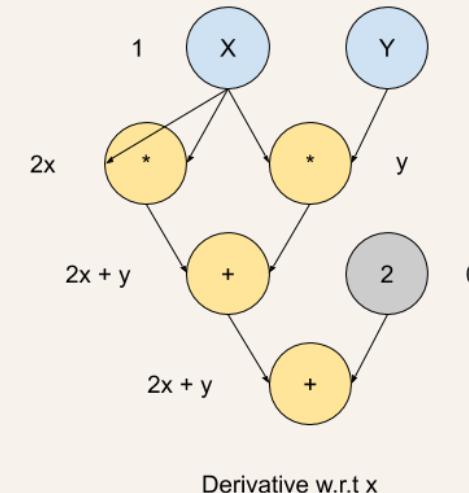
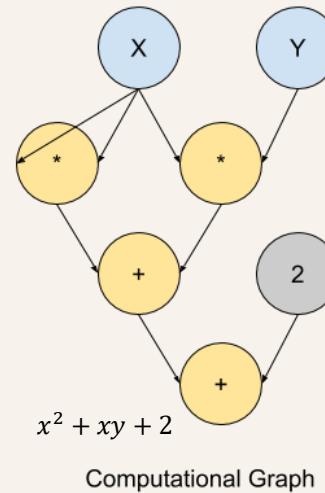
Finite Difference:

- *Cost = n\_inputs x function*

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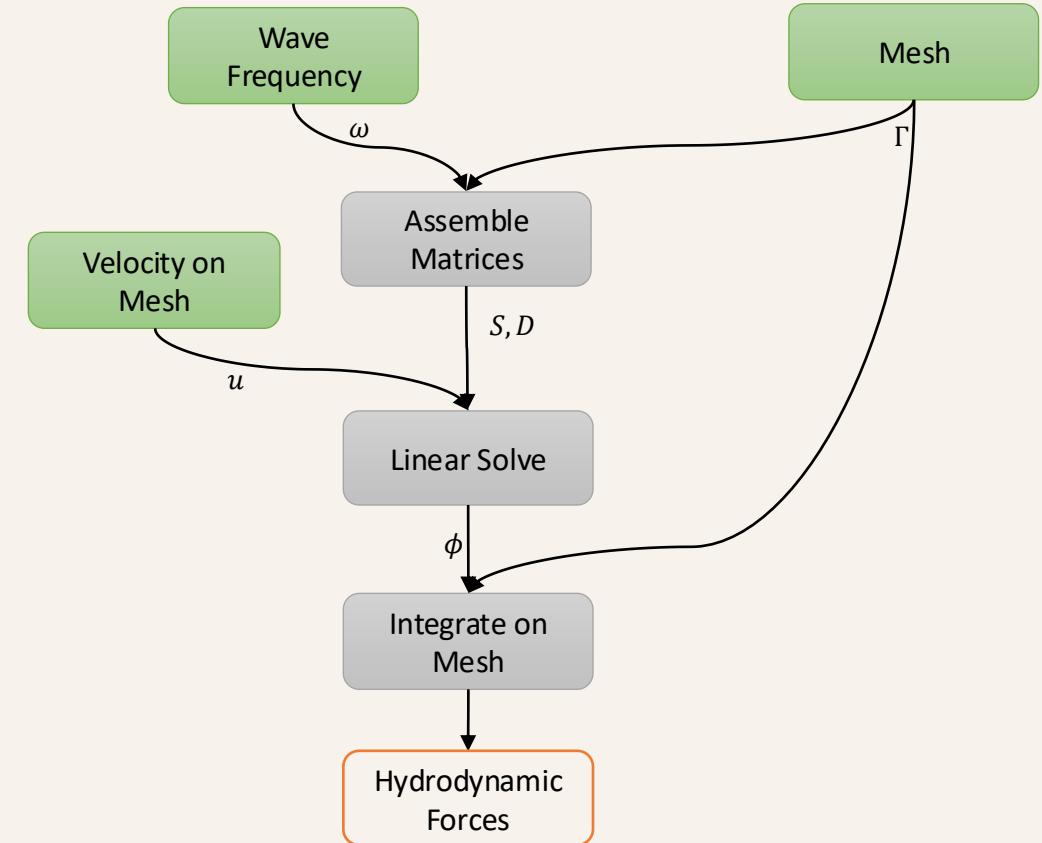
Automatic Differentiation:

- *Cost = 2 x function*



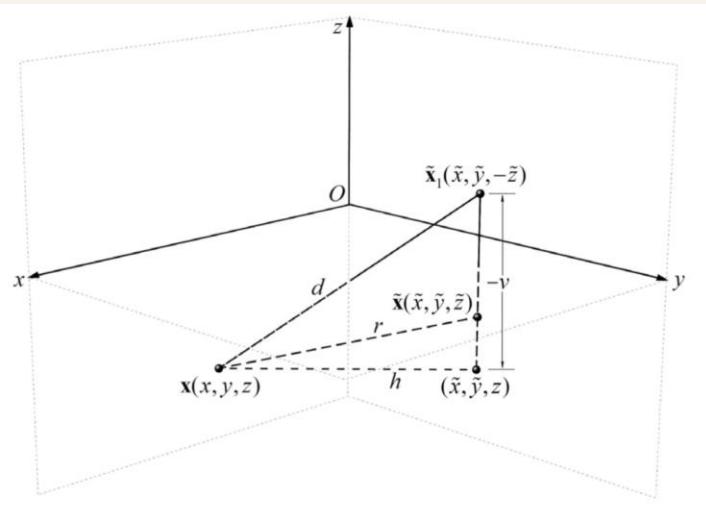
# Boundary Element Method

$$\begin{aligned} S_{ij} &= \iint_{\Gamma_j} G(x_i, \xi) ds_\xi \\ D_{ij} &= \frac{\delta_{ij}}{2} + \iint_{\Gamma_j} \nabla_\xi G(x_i, \xi) \cdot n_j ds_\xi \\ D\varphi &= Su \end{aligned} \quad \left. \begin{array}{l} \text{Assemble Matrices} \\ \text{Linear Solve} \end{array} \right\}$$



# Boundary Element Method

$$4\pi G(x, \xi) = -\frac{1}{r} - \frac{1}{d} + L(x, \xi) + 2\pi [\tilde{H}_0(h) - iJ_0(h)] e^v$$



$$L^a \equiv -\frac{1}{d} + \frac{2P}{1+d^3} + 2\rho(1-\rho)^3 R \quad (33a)$$

where  $P$  and  $R$  are defined by (22b) and (26b) as

$$P \equiv e^v \left( \log \frac{v - v}{2} + \gamma - 2d^2 \right) + d^2 - v \quad (33b)$$

$$R \equiv (1 - \beta)A - \beta B - \frac{\alpha C}{1 + 6\alpha\rho(1 - \rho)} + \beta(1 - \beta)D. \quad (33c)$$

Here,  $\gamma = 0.577\dots$  is Euler's constant, and  $\alpha, \beta, \rho$  are defined by (15) and (21a). Moreover, the polynomials  $A(\rho), B(\rho), C(\rho)$  and  $D(\rho)$  in (33c) are defined as

$$\begin{aligned} A \equiv & 1.21 - 13.328\rho + 215.896\rho^2 - 1763.96\rho^3 + 8418.94\rho^4 \\ & - 24314.21\rho^5 + 42002.57\rho^6 \\ & - 41592.9\rho^7 + 21859\rho^8 - 4838.6\rho^9 \end{aligned} \quad (33d)$$

$$\begin{aligned} B \equiv & 0.938 + 5.373\rho - 67.92\rho^2 + 796.534\rho^3 - 4780.77\rho^4 \\ & + 17137.74\rho^5 - 36618.81\rho^6 + 44894.06\rho^7 \\ & - 29030.24\rho^8 + 7671.22\rho^9 \end{aligned} \quad (33e)$$

$$\begin{aligned} C \equiv & 1.268 - 9.747\rho + 209.653\rho^2 - 1397.89\rho^3 + 5155.67\rho^4 \\ & - 9844.35\rho^5 + 9136.4\rho^6 - 3272.62\rho^7 \end{aligned} \quad (33f)$$

$$\begin{aligned} D \equiv & 0.632 - 40.97\rho + 667.16\rho^2 - 6072.07\rho^3 + 31127.39\rho^4 \\ & - 96293.05\rho^5 + 181856.75\rho^6 - 205690.43\rho^7 \\ & + 128170.2\rho^8 - 33744.6\rho^9. \end{aligned} \quad (33g)$$

# Automatic Differentiation of BEM

- [implicitAD.jl](#)
- Custom gradients

```
function bem_program(radius,omega = 1.3 ,dof = [0,0,1])
    mesh = differentiableMesh(radius) #fd
    wavenumber = omega^2 / 9.8
    S,D = assemble_matrices(mesh,wavenumber)
    BC = neumanBC(mesh.normals,dof,omega)
    φ = implicit_linear(D,S*BC)
    A = added_mass(φ,mesh.normals,mesh.areas,omega,dof)
    return A
end

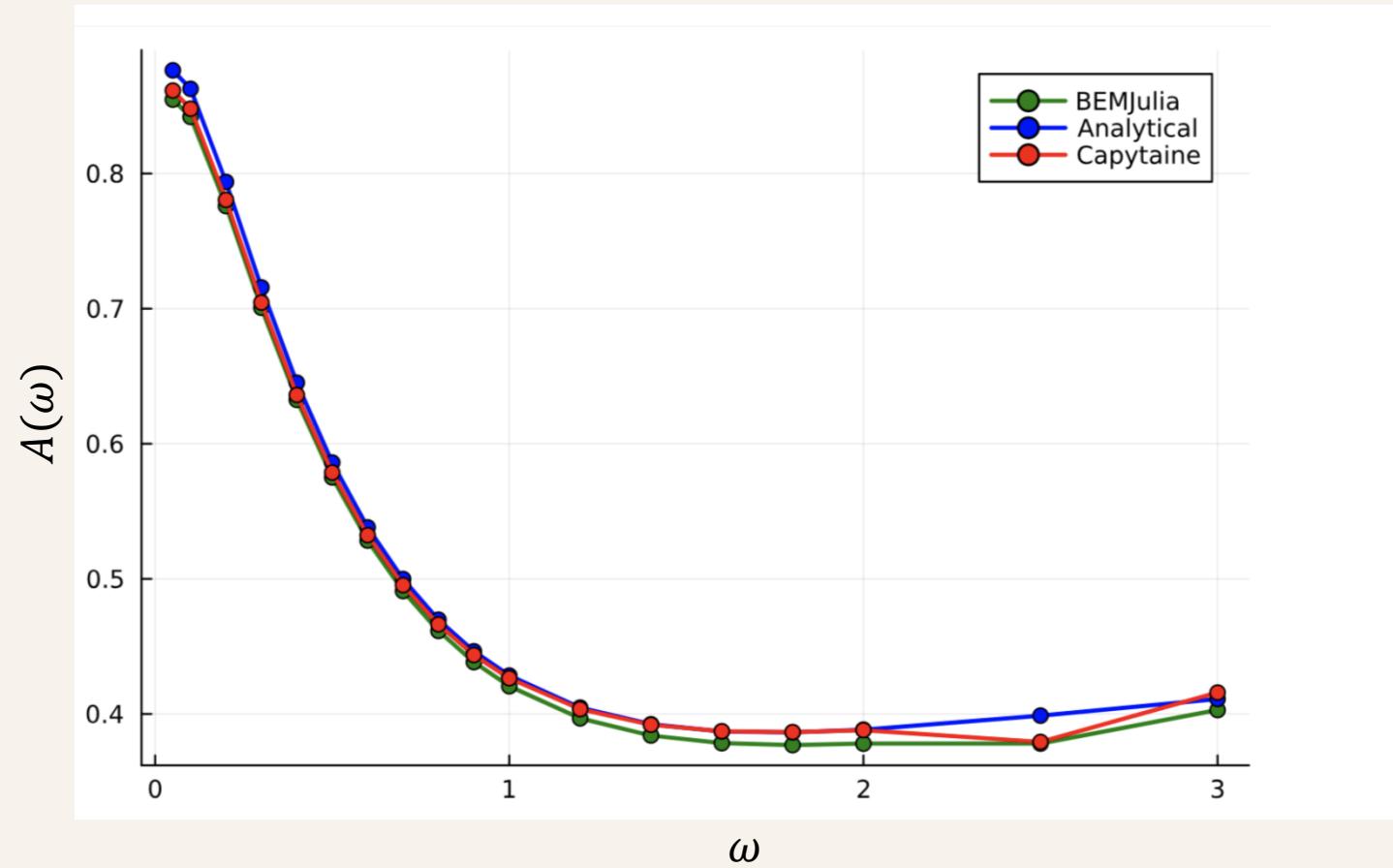
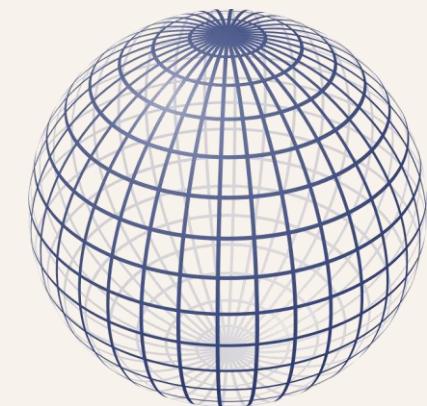
# gradient with respect to mesh, omega and dof
Zygote.gradient(X -> bem_program(X[1], X[2], X[3]), [r, w, heave])
```



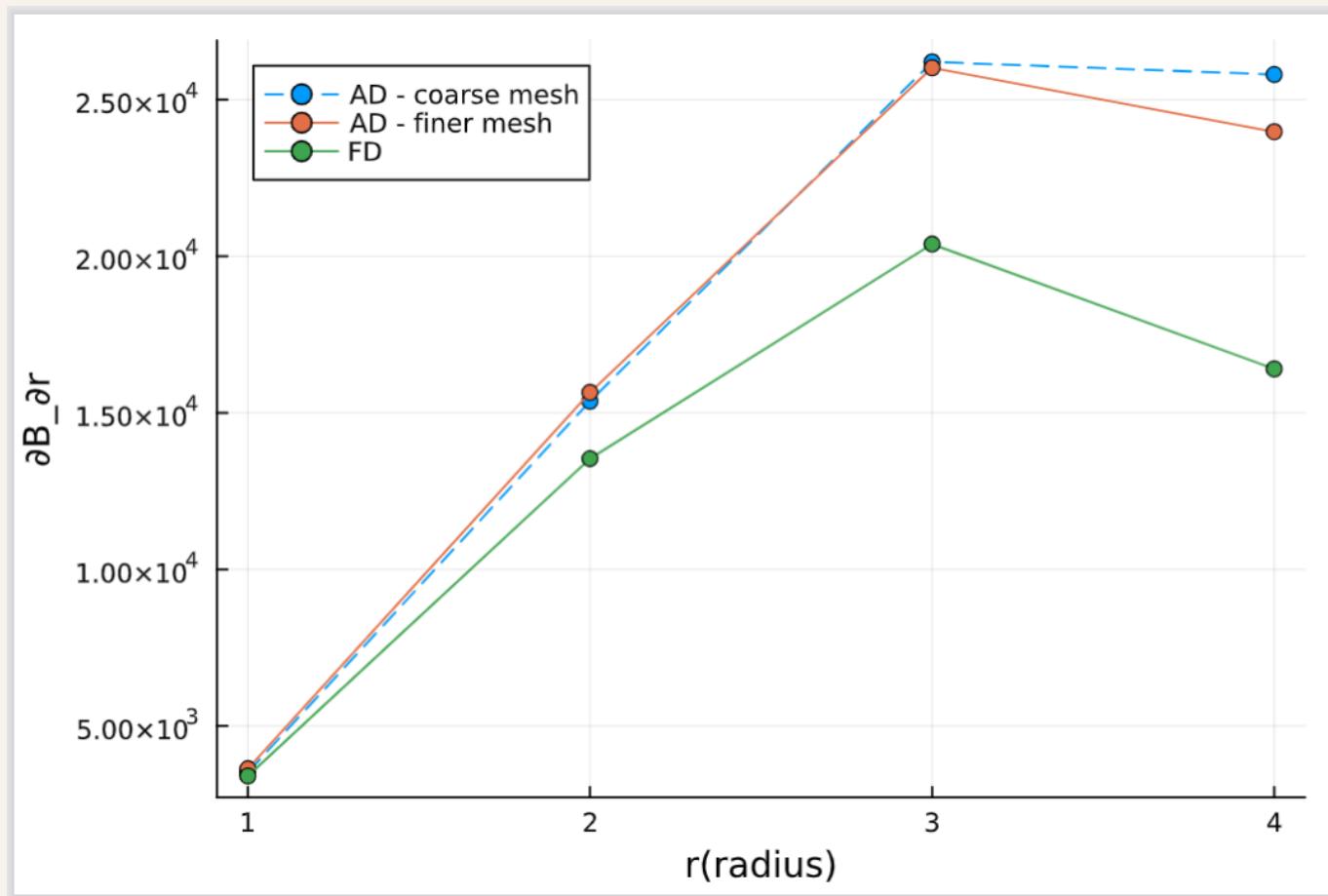
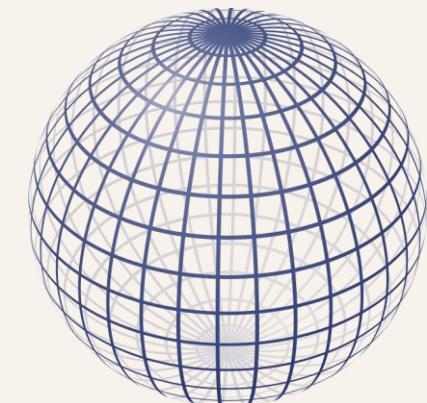
# Preliminary Results



# Added Mass



# Gradient of Added Mass w.r.t. Radius



# Next Steps

- Finish verification of gradients
- Demonstrate use in optimization study
- Release: Code structure & documentation
- Parallelization & GPUs

# Questions?

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