



# Advanced Features and Recent Developments in the WEC-Sim Open-Source Design Tool



*PRESENTED BY*

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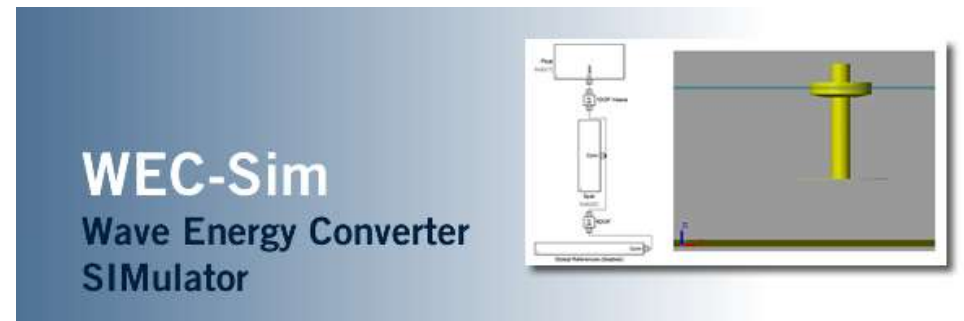
Sandia National Laboratories



# What is WEC-Sim?

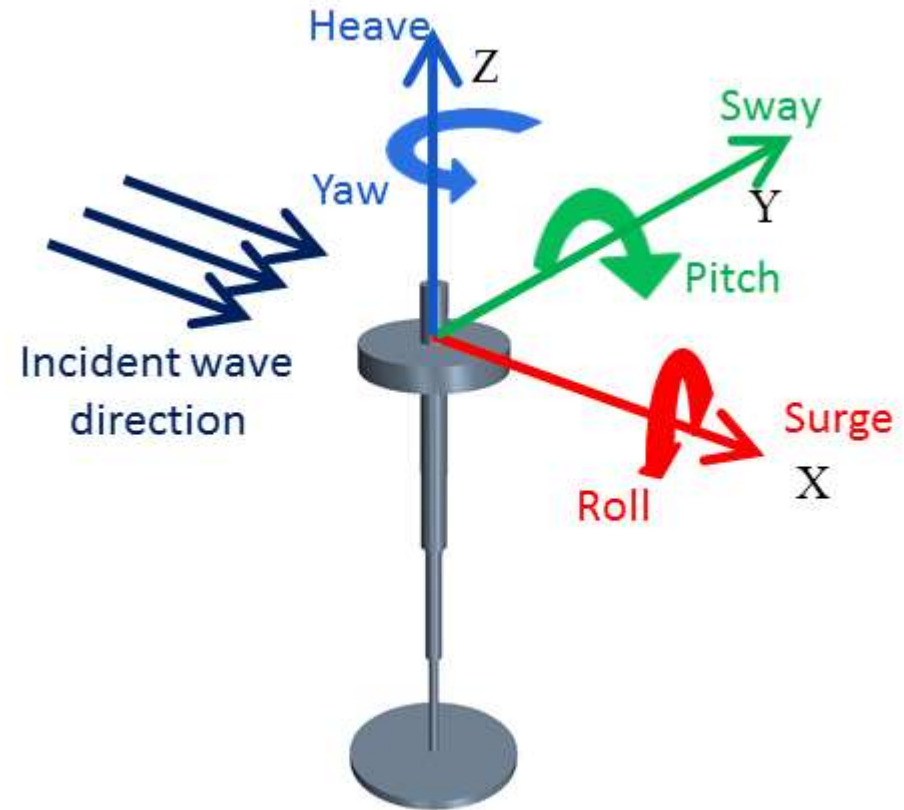
## WEC-Sim (Wave Energy Converter Simulator)

- Simulates wave energy converter dynamics in operational waves
- Time-domain rigid body equation of motion solver based on Cummins' formulation
- Open source software developed in MATLAB/SIMULINK
  - Available at <https://github.com/WEC-Sim/WEC-Sim>
- Joint NREL/Sandia project funded by the US Department of Energy
- First Release: v1.0 in June 2014
- Current Release: v5.0.1 in Sept 2022



## Why use WEC-Sim?

- WEC-Sim has the ability to model the dynamics of devices that are comprised of rigid bodies, power-take-off (PTO) systems, and mooring systems.
- WEC-Sim uses hydrodynamic coefficients derived from frequency-domain boundary element (BEM) simulations
- Time-domain simulations are performed by solving the governing WEC equations of motion in 6 degrees-of-freedom.



# Why use WEC-Sim?



CPU time/  
Simulation  
Time

$10^{10}$

$10^8$

$10^6$

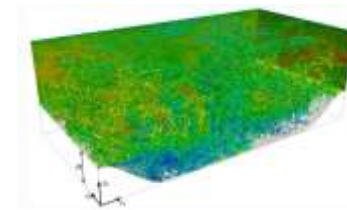
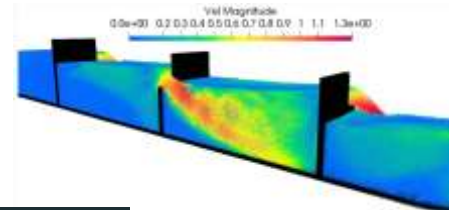
$10^4$

$10^2$

Real Time → 1

$10^{-2}$

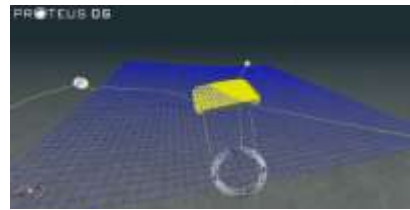
$10^{-4}$



English, A., Domínguez, J.M., Vacondio, R. et al. (2022)

**LES SPH** (SPH-FLOW, SPHYSICS, ...)

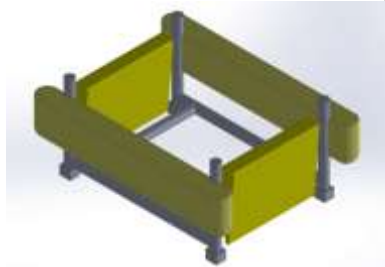
**RANSe** based approaches (STARCCM+, FLUENT, ISIS-CFD, ICARE-SWENSE, OPENFOAM...)



Krank, B., Kronbichler, M. & Wall, W.A (2018)

**Non-linear** potential flow based approaches (LAMP3-4, AEGIR)

<https://dsaocean.com/tag/oscilla-power/>



Linear **time domain** potential flow theory based BEM Codes & approaches based on **Morison** equations (LAMP1-2, Orcaflex, Deeplines, **WEC-SIM**, InWave, Proteus3D, ...)



Linear **frequency domain** potential flow theory based BEM Codes (WAMIT, NEMOH, Capytaine...)

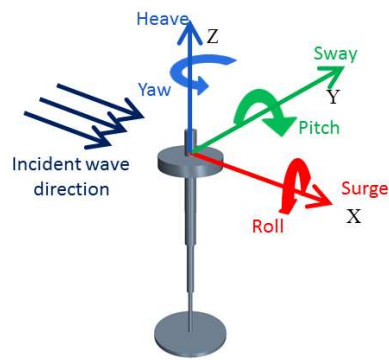
Low Fidelity

High Fidelity



# WEC-Sim Theory

- Dynamics simulated by solving time-domain equation of motion (Cummins, 1962)



$$m\ddot{x}(t) = \boxed{f_{hs}(t)} + \boxed{f_{ex}(t)} + \boxed{f_{rad}(t)} + \boxed{f_v(t)} + \boxed{f_{pto}(t)} + \boxed{f_m(t)}$$

Hydrostatic restoring force

Wave excitation & diffraction force  
(from BEM simulations)

Radiation force: added mass and radiation damping  
(from BEM simulations)

Viscous force

Power take-off force

Mooring force

- Use radiation and diffraction method and calculate the hydrodynamic forces from frequency-domain Boundary Element Method (BEM)

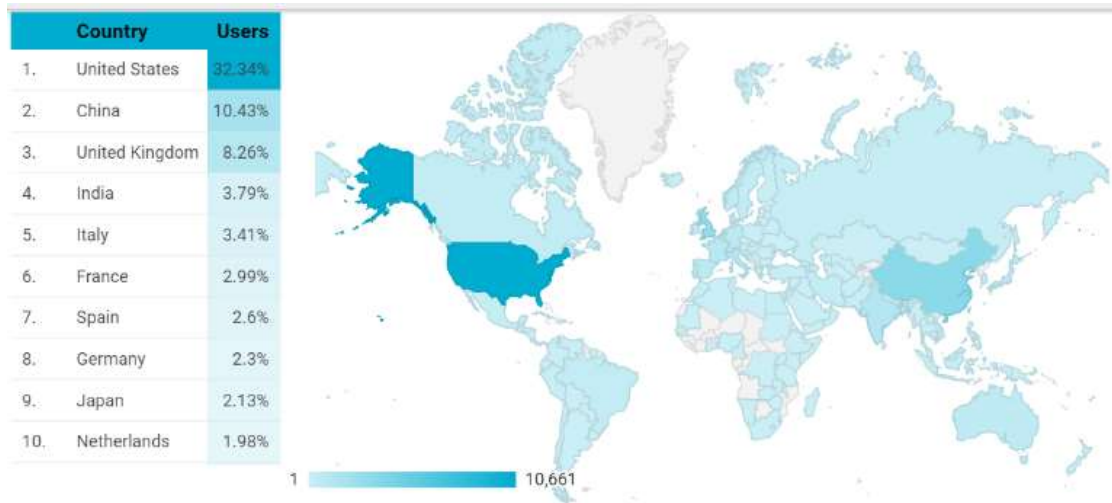
$$f_{rad}(t) = -A_{\infty}\ddot{X} - \int_0^t K(t-\tau)\dot{X}(\tau)d\tau$$

$$f_{ex}(t) = \Re \left[ R_f F_X(\omega_r) e^{i(\omega_r t + \phi)} \int_0^{\infty} \sqrt{2S(\omega_r)} d\omega_r \right]$$

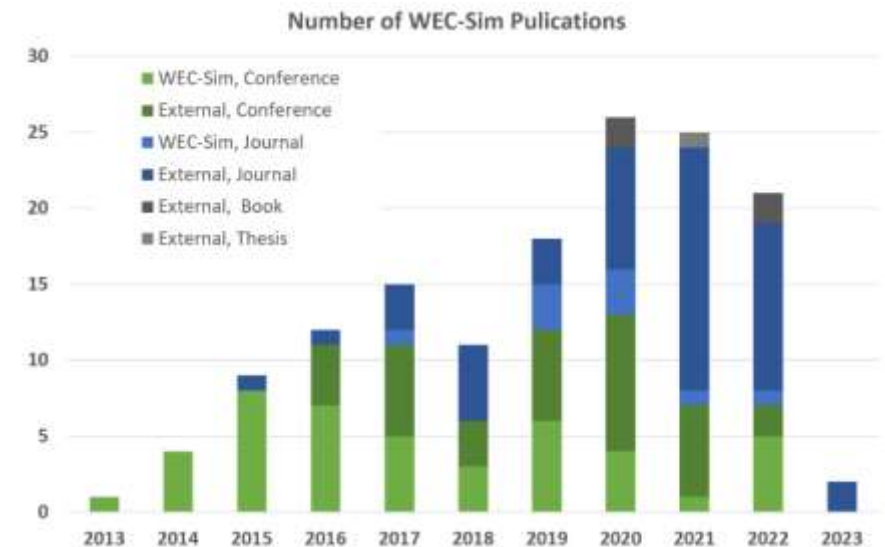
$$= \int_{-\infty}^{\infty} \eta(\tau) f_e(t-\tau) d\tau$$

# WEC-Sim User Base

- Users have a crucial role for the software development and continuous improvement
- As January 2024, more than 1200 issues have been addressed and more than 1200 pull requests have been developed to improve the source code
- As of May 2023, approximately 144 scientific publications have been developed using WEC-Sim



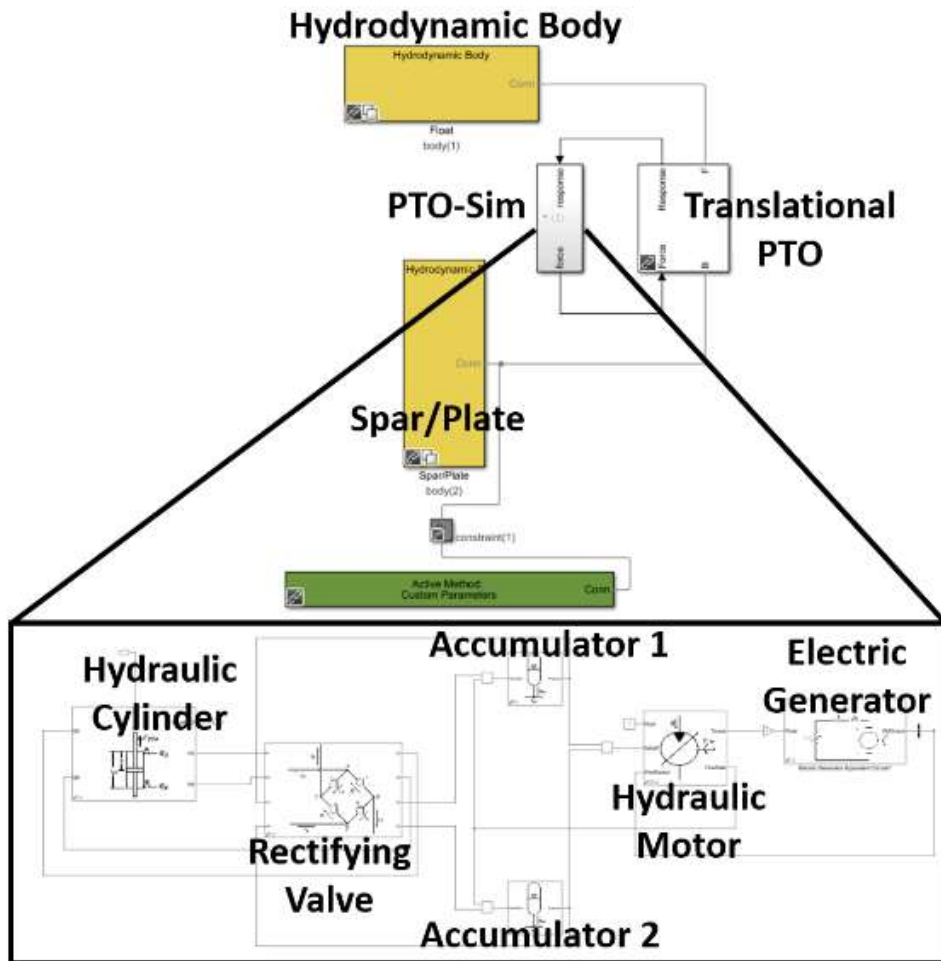
Google Analytics WEC-Sim users from November 2016 to June 2023



Number of WEC-Sim publications by year and category

# WEC-Sim Recent Applications

## PTO-Sim



## Control Examples

Controller Application	Description
Passive (P)	Sphere with proportional (damping) control
Reactive (PI)	Sphere with proportional-integral (spring and damping) control
Latching	Sphere with latching (locking) control
Declutching	Sphere with declutching control
Model Predictive Control (MPC)	Sphere with model predictive control

# Capytaine Development

## Background

- Capytaine is a Python package with a Fortran core
- Based on the open-source BEM solver Nemoh
- First version of Capytaine was released in 2019

## Sandia Labs and NREL funding Capytaine

- Collaboration started in April 2022
- Five new versions have been released since then
- ~60 issues have been closed
- ~130 pull requests have been merged on GitHub

## High-priority tasks for Capytaine/WEC-Sim collaboration

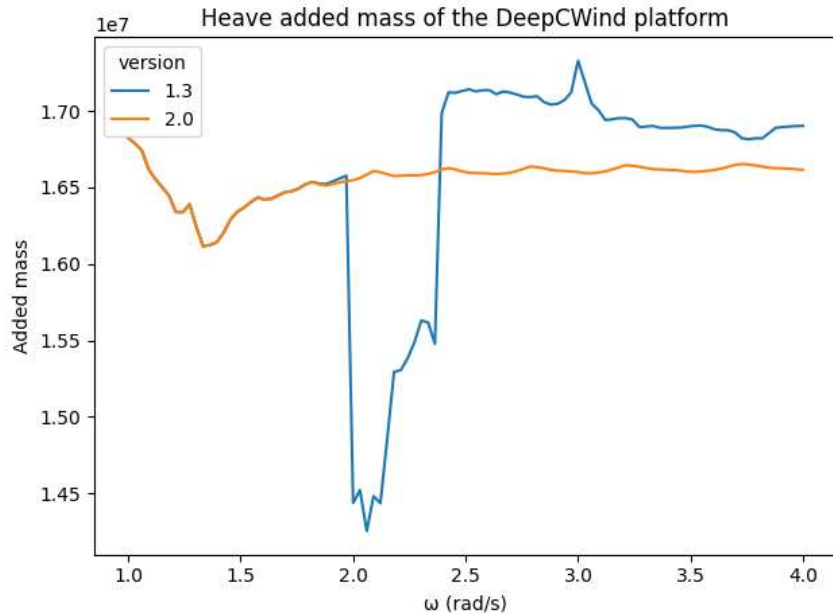
- Improve the precision and performance of the resolution of the radiation/diffraction problems
- Ensuring Capytaine distribution on several platforms and its long term preservation
- Supporting users and improving documentation



# Capytaine Development

## Improve precision for Radiation/diffraction problems

- Precision issues in high frequencies have been reported.
- The issues cause jumps in the computed hydrodynamic coefficients.



Added mass calculated with two versions of Capytaine

### Source of this issue:

- Computation of the green function for panels deeper than  $\sim 1.2$  wavelengths
- Most of panels had this issue for high frequencies
- This problem was solved in the latest version of Capytaine

# Capytaine Development

## Improvement of performance

Resolution time for a 705-panel rectangular barge with 6 degrees of freedom, 2 wave directions, and 20 frequencies, computed with a single core of a high-end CPU from 2017 (Intel Core i7-8700). All tests were run with default settings

Solver	Release date	Resolution time (infinite depth)	Resolution time (finite depth)
Capytaine v1.3	October 2021	4.9 s	13.1 s
Capytaine v1.4	July 2022	6.5 s	14.1 s
Capytaine v1.5	December 2022	3.7 s	11.1 s
Capytaine v2.0	June 2023	2.3 s	5.5 s
Nemoh v2	May 2016	36 s	56 s
Nemoh v3.0 (*)	December 2022	6 s	20 s

The Generalized Minimal Residual Method (GMRES) linear solver was replaced by a more robust direct solver

- Caching the lower-upper (LU) decomposition of the direct solver.
- Fix of a performance bug in the evaluation of the green function.

# Capytaine Development

## Some other updates:

- The build and packaging toolchain has been updated to follow the recent changes in the Python packaging ecosystem and to offer more installation options to users.
- Hydrostatics have been added in version 1.4.
- Exporting results to WEC-Sim has been streamlined.

## Upcoming new features:

- Irregular frequency removal
- Approximate forward speed
- More accuracy and performance improvement

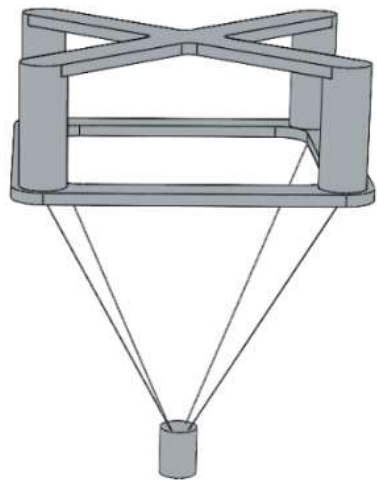
## Capytaine Repository:

<https://github.com/capytaine/capytaine>

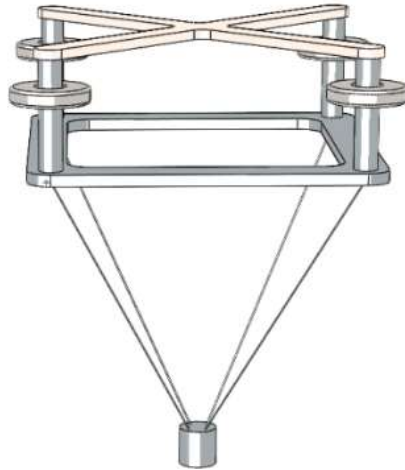
# MOST: Matlab for Offshore wind turbine Simulation Tool

## Background

- Developed by the Politecnico di Torino
- The purpose of MOST is to simulate floating wind turbines
- MOST is integrated within the WEC-Sim environment
- The combined functionalities of MOST and WEC-Sim allows the possibility of modeling wave energy converters with wind turbine platforms or pendulum-type platforms.



(a)

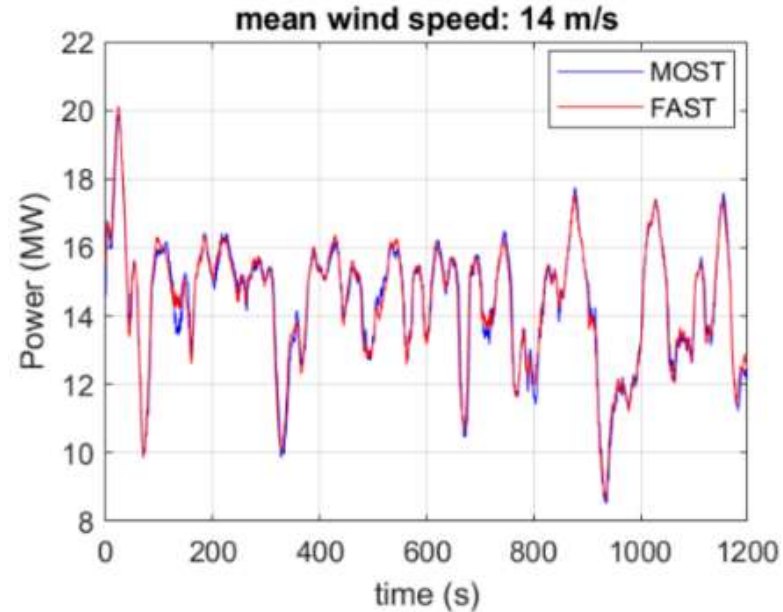
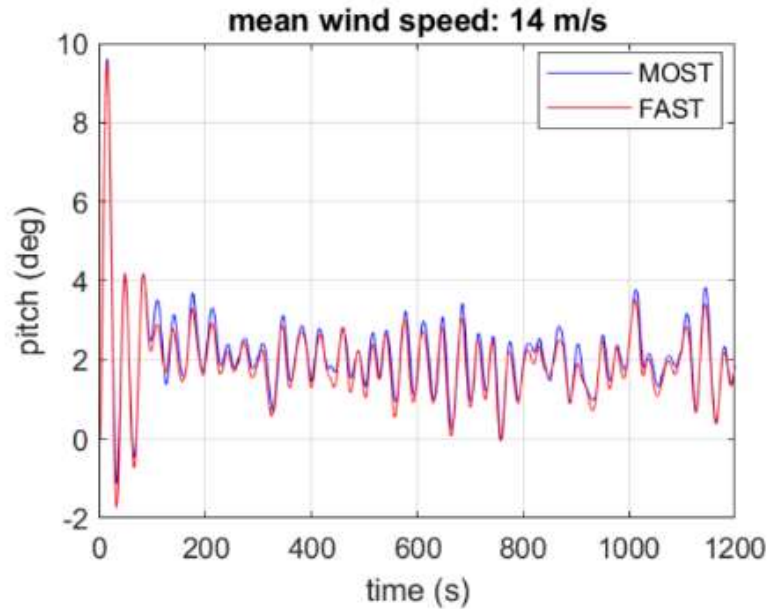


(b)

Example of hybrid concepts a) of a semisubmersible-pendulum platform and b) of a platform with integrated WEC

# MOST: Matlab for Offshore wind turbine Simulation Tool

MOST has been validated using OpenFAST results:

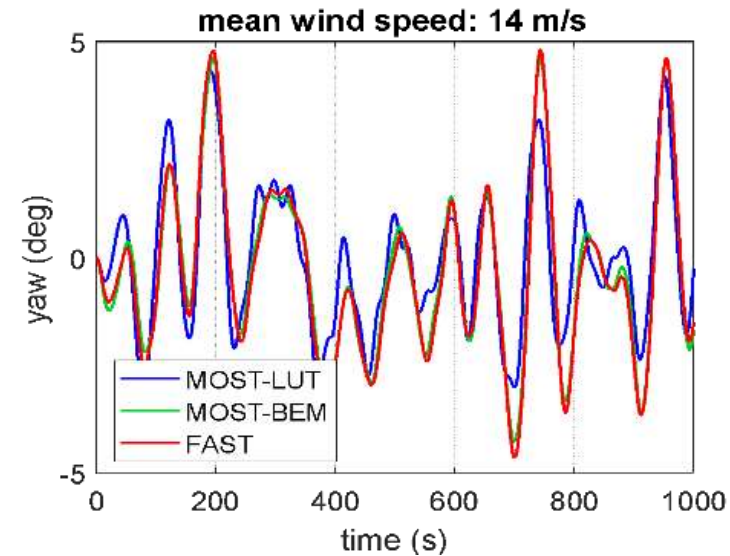
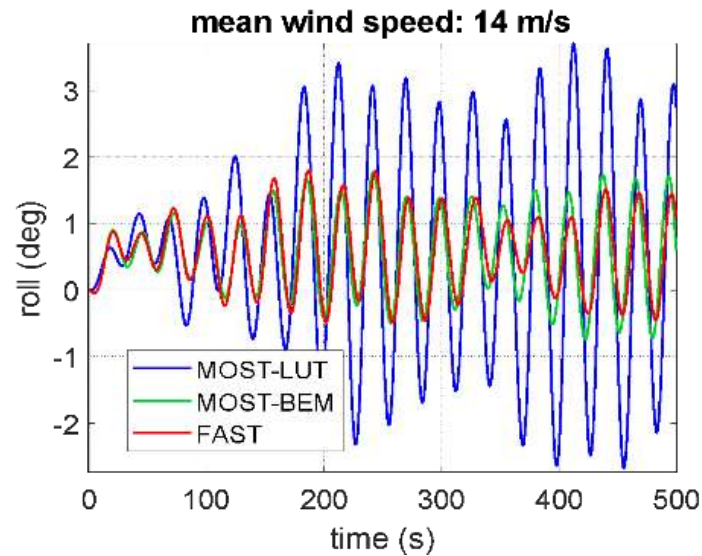


Platform pitch and power output comparison between MOST-LUT (Lookup Table) and FAST for the IEA 15 MW reference wind Turbine

- Primary distinction between MOST and OpenFast lies in their treatment of aerodynamic forces
- Aerodynamics forces in MOST are calculated using look-up tables, resulting in a speed improvement of 3 to 5 times.
- MOST is well suited for optimization studies.

# MOST: Matlab for Offshore wind turbine Simulation Tool

- Next steps involve developing a model to deal with all 6 DOF
- The complete resolution of the BEM has been implemented in MOST with good results



Platform roll and yaw comparison between MOST-LUT, MOST-BEM and FAST for the IEA 15 MW wind Turbine

# Thank you

For more information please visit the WEC-Sim website:

<http://wec-sim.github.io/WEC-Sim>

If you have questions on this presentation please reach out to any of the WEC-Sim Developers on GitHub:

<https://github.com/WEC-Sim/WEC-Sim>



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This work was authored in part by the National Renewable Energy Laboratory, operated by Alliance for Sustainable Energy, LLC, for the U.S. Department of Energy (DOE) under Contract No. DE-AC36-08GO28308.

Funding provided by the U.S. Department of Energy Office of Energy Efficiency and Renewable Energy Water Power Technologies Office. The views expressed in the article do not necessarily represent the views of the DOE or the U.S. Government. The U.S. Government retains and the publisher, by accepting the article for publication, acknowledges that the U.S. Government retains a nonexclusive, paid-up, irrevocable, worldwide license to publish or reproduce the published form of this work, or allow others to do so, for U.S. Government purposes.

