



Measuring non-intrusively free surface waves with motion capture systems

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Assessment of Wave Properties

- Fundam

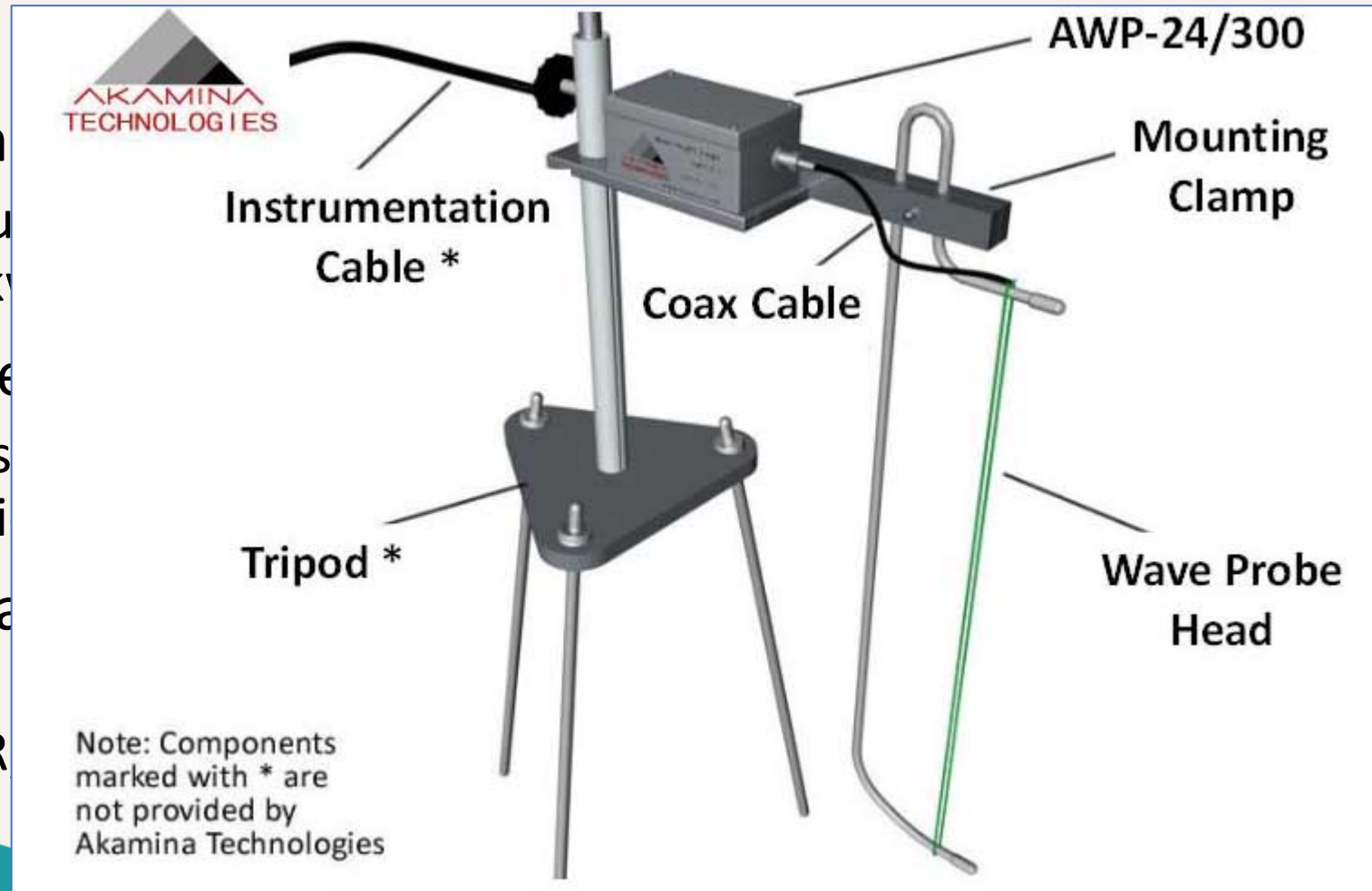
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break

- In the fie

- Buoys
rectifi

- In labora

- Wave
LiDAR



<http://www.akamina.com/AWP-300-3.html>

Assessment of Wave Properties

- Knowledge of wave kinematics

- Free surface
- Orbital velocities
- Particle accelerations
- Pressure distribution
- Orbital excursions
- Non-linearities
- Principles of superposition
- Directionality
- Spreading
- ...

$$\phi(x, z, t) = \frac{ga}{\omega} \frac{\cosh[k(z+d)]}{\cosh(kd)} \sin(\theta)$$

$$u(x, z, t) = \frac{gak}{\omega} \frac{\cosh[k(z+d)]}{\cosh(kd)} \cos(\theta) ; \quad w(x, z, t) = \frac{gak}{\omega} \frac{\sinh[k(z+d)]}{\cosh(kd)} \sin(\theta)$$

$$a_x(x, z, t) = gak \frac{\cosh[k(z+d)]}{\cosh(kd)} \sin(\theta) ; \quad a_z(x, z, t) = -gak \frac{\sinh[k(z+d)]}{\cosh(kd)} \cos(\theta)$$

$$A = \text{horizontal axis} = a \frac{\cosh[k(z_o + d)]}{\sinh(kd)} ; \quad B = \text{vertical axis} = a \frac{\sinh[k(z_o + d)]}{\sinh(kd)}$$

$$\frac{\omega^2}{k} = g \tanh(kd) ; \quad C = \frac{gT}{2\pi} \tanh(kd) ; \quad C = \sqrt{\frac{gL}{2\pi} \tanh(kd)} ; \quad L = \frac{gT^2}{2\pi} \tanh(kd)$$

https://cavity.caee.utexas.edu/kinnas/wow/public_html/waveroom/linthe/node25.html

Assessment of Wave Properties

Input

Wave Theory

- ☒ 1. Order Stoke
- ☒ 5. Order Stoke
- ☒ Stream Function Theory

Water Depth [m] 10

Wave Period [s] 3

Wave Height [m] 2

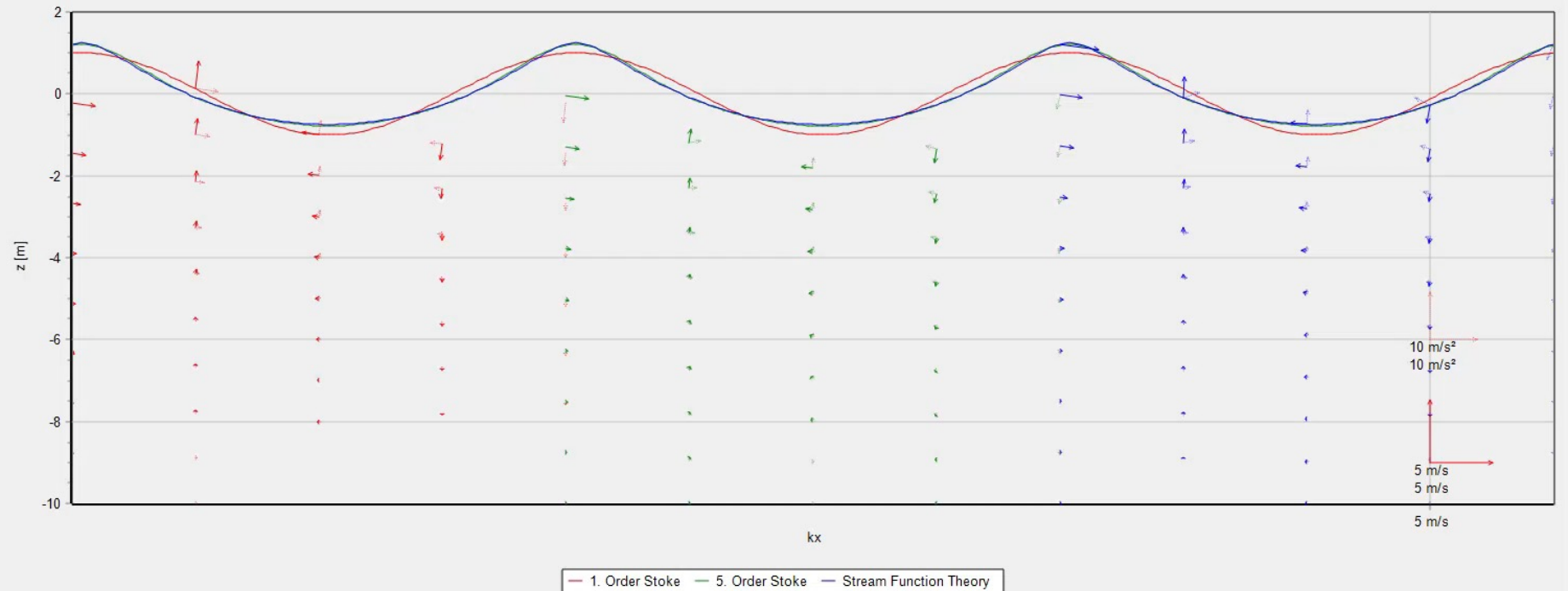
Type of calculation Current (U) given

U [m/s]	0
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Start Calculation

Advanced Options

Output

[illegible]

Assessment of Wave Properties

Input

Wave Theory

- ☒ 1. Order Stoke
- ☒ 5. Order Stoke
- ☒ Stream Function Theory

Water Depth [m]

Wave Period [s]

Wave Height [m]

Type of calculation

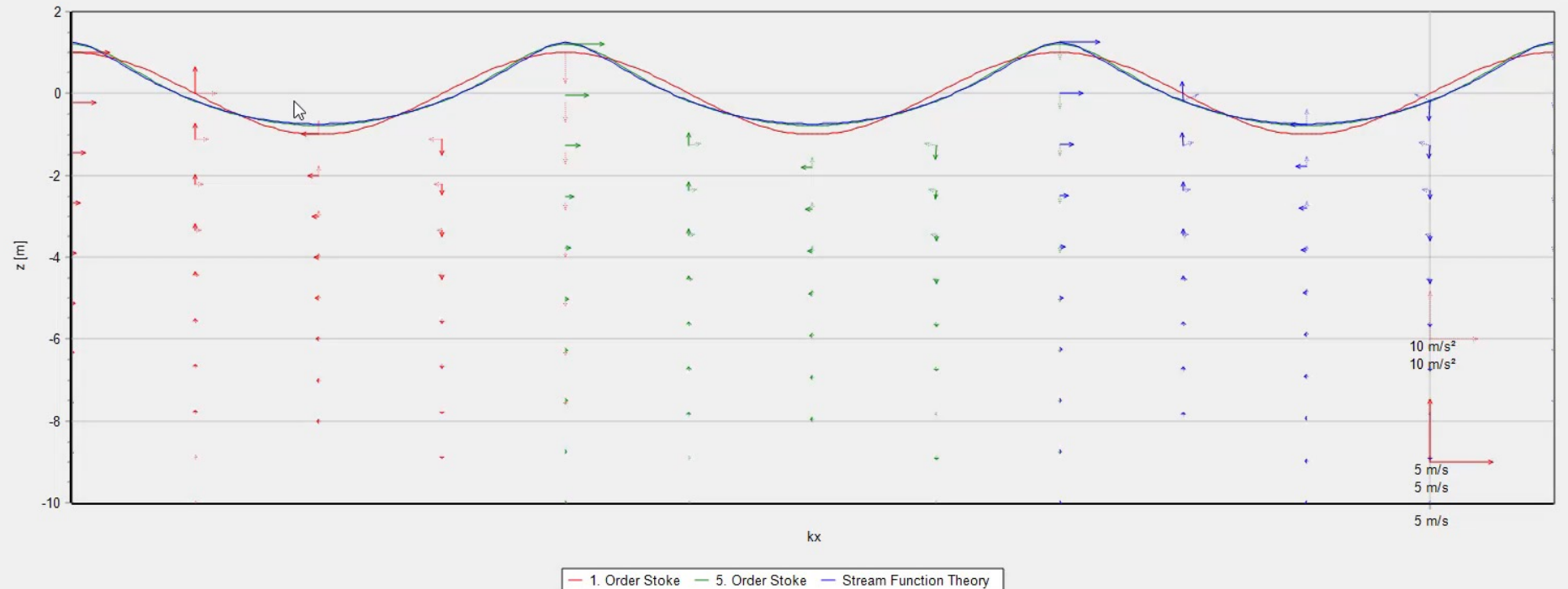
U [m/s]

Start Calculation

Advanced Options

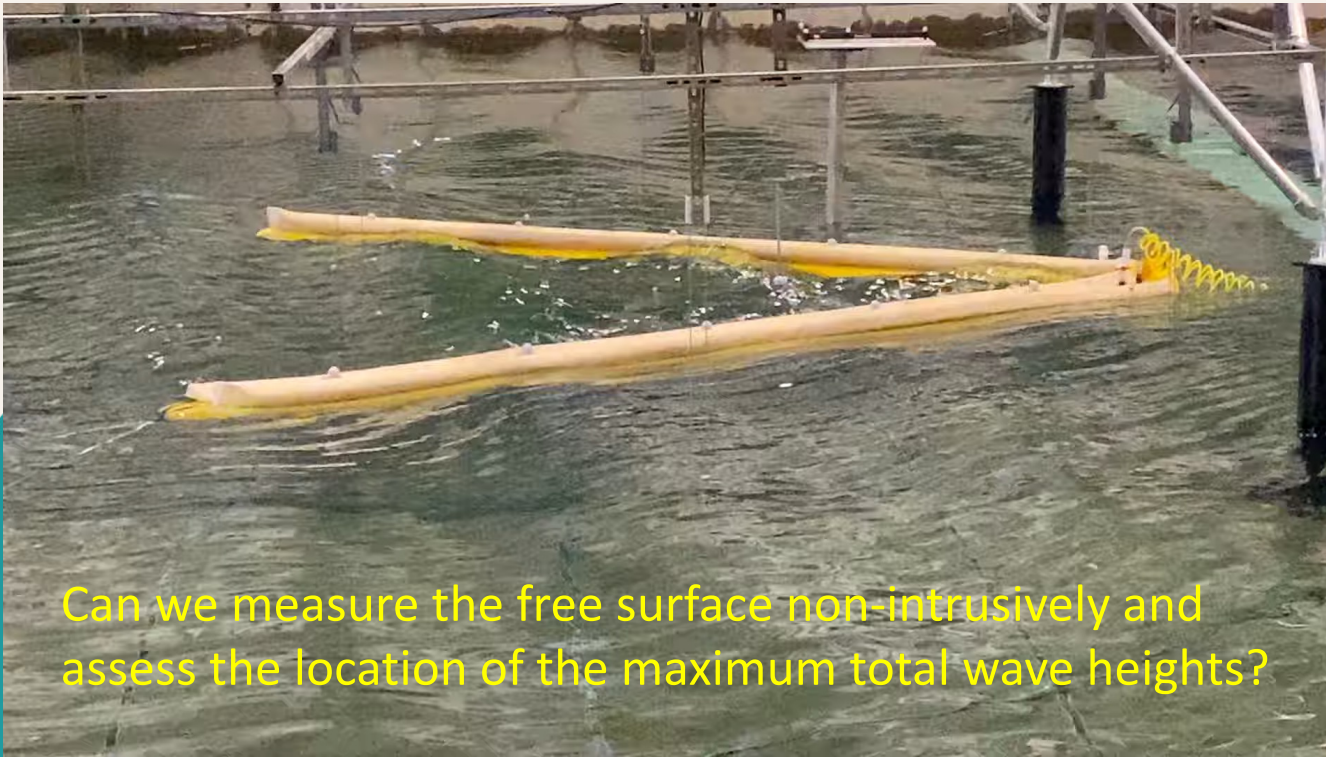
Output

Parameter	1. Order Stoke	5. Order Stoke	Stream Function Theory
Wavelength (L) [m]	14.055	16.184	16.288
Wave number ($k=2\cdot\pi/L$)	0.447	0.388	0.386
Current Discharge Q [...]	1.059	0.893	0.841
kx	2.820	2.820	2.820
z [m]	-0.170	-0.170	-0.170
η [m]	-0.949	-0.755	-0.724
u [m/s]	Out of Range	Out of Range	Out of Range
w [m/s]	Out of Range	Out of Range	Out of Range
du/dt [m/s ²]	Out of Range	Out of Range	Out of Range
dw/dt [m/s ²]	Out of Range	Out of Range	Out of Range
p_d [Pa]	Out of Range	Out of Range	Out of Range
p [Pa]	Out of Range	Out of Range	Out of Range

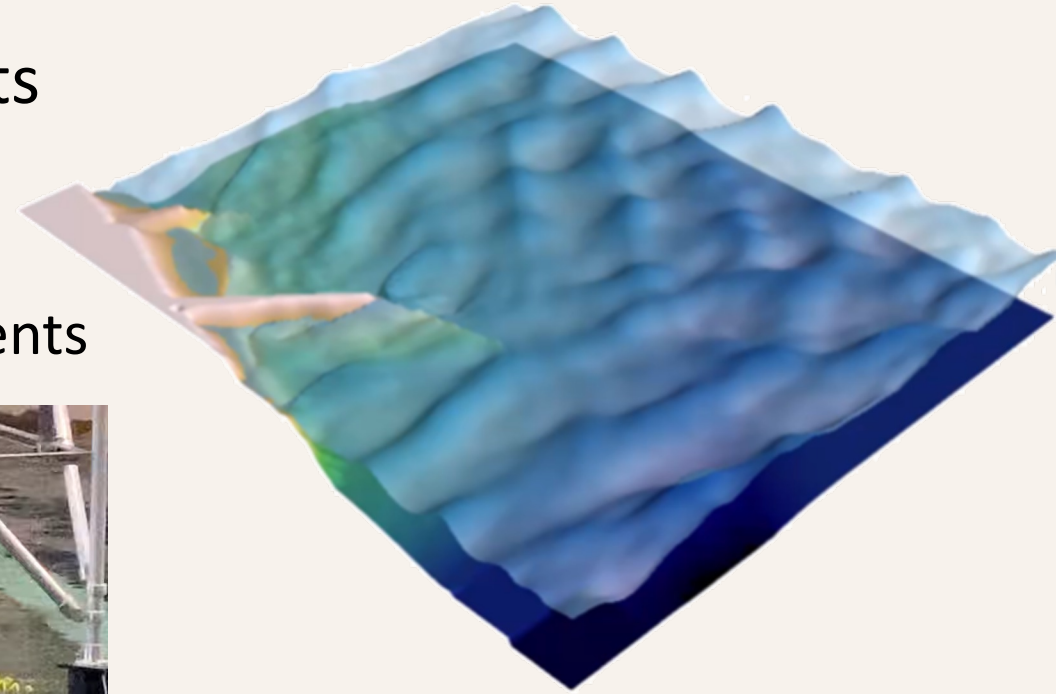


Assessment of Wave Properties

- Limitations on free surface measurements
 - Complex and highly variable 3D wave fields
 - Incompatibility with floating devices
 - Interference of intrusive hardware/instruments



Can we measure the free surface non-intrusively and assess the location of the maximum total wave heights?



<https://jbpacific.com.au/projects/coastal-hazards/diatreme-barge-landing-facility-coastal-assessment-qld/>

Mocap – Motion Capture System

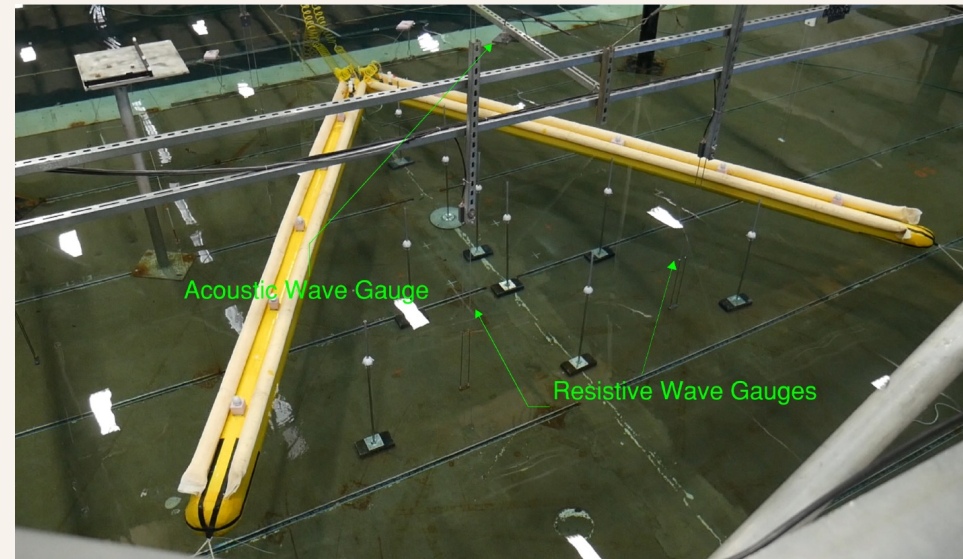
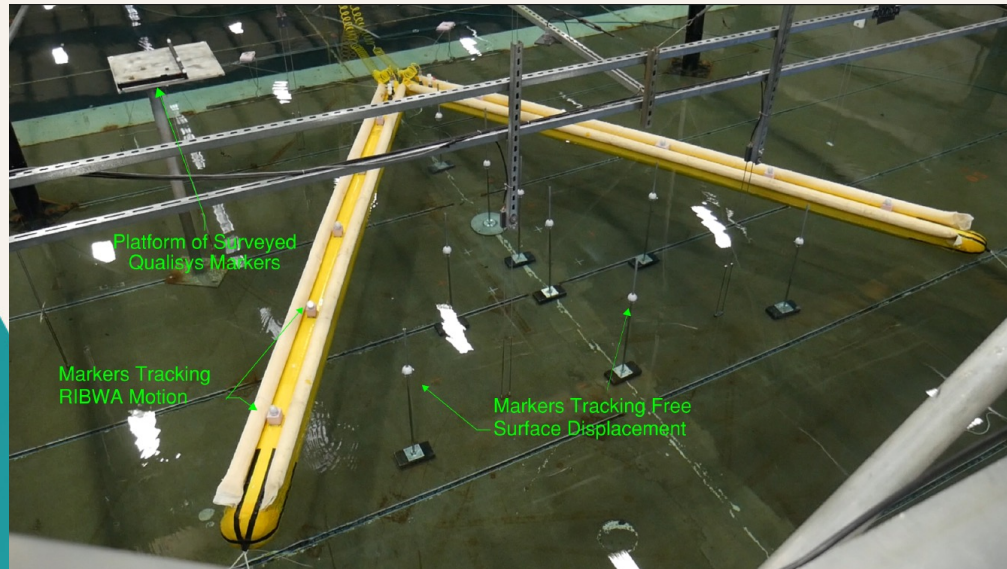
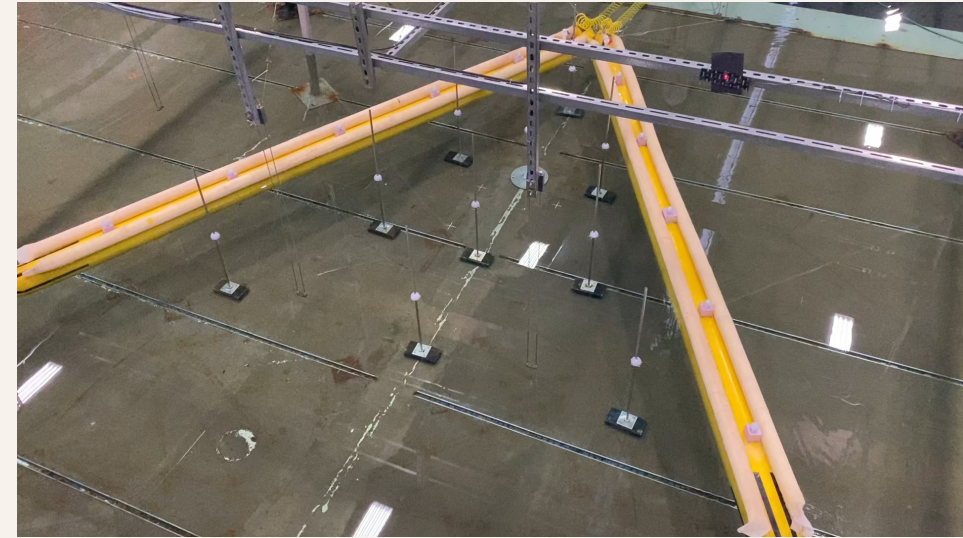
- Registering the motion of objects
- Non-intrusive
- Use of cameras
- Use of passive or active markers
- Capturing the 3D coordinates with a high sampling rate
- Applications in marine engineering, coastal engineering, health science, video game industry, movies, ...



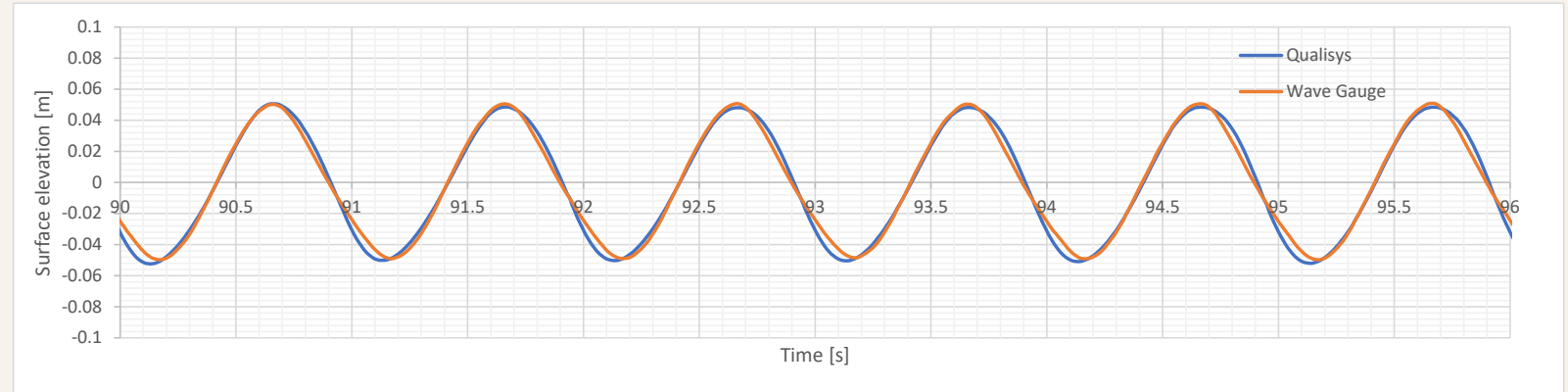
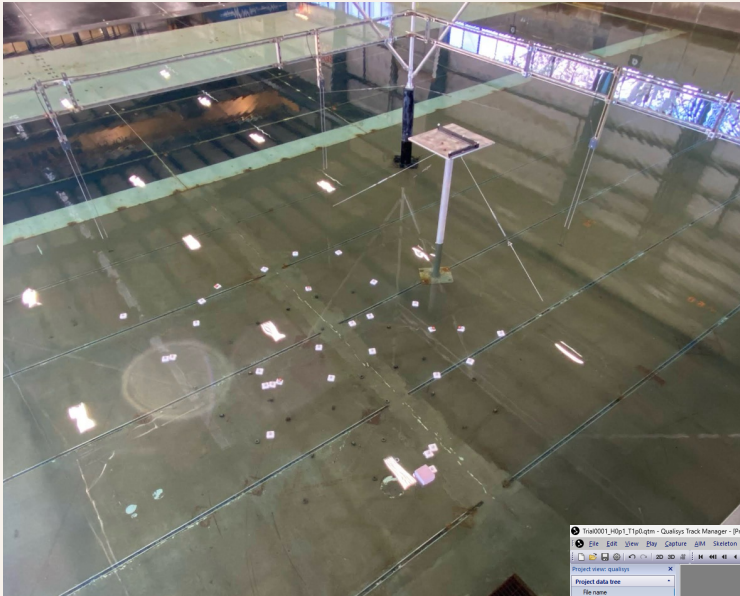
<https://www.youtube.com/watch?v=qtXz6qocciM>

TEAMER - Rapidly Installed Breakwater for WEC Enhanced Performance

- Experiments presented in UMERC 2023
- Qualisys Motion Capture:
 - RIB/WA motions and deformations
 - Free surface tracking

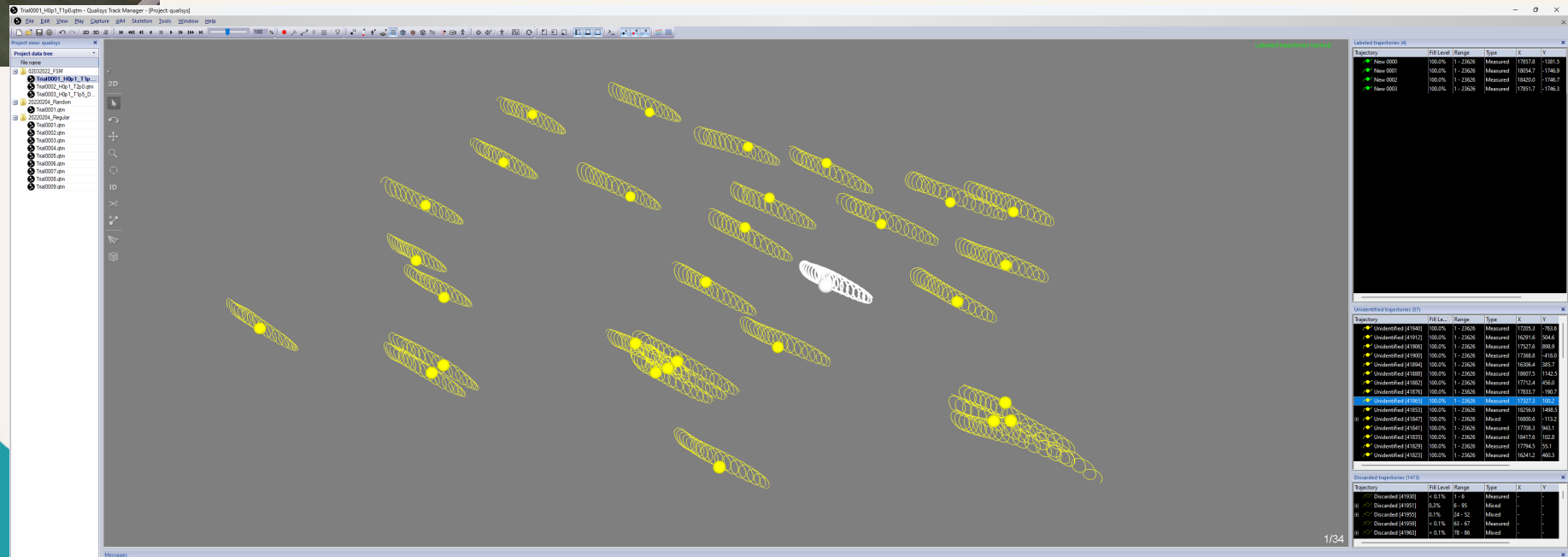


Undisturbed conditions (no RIB/WA)



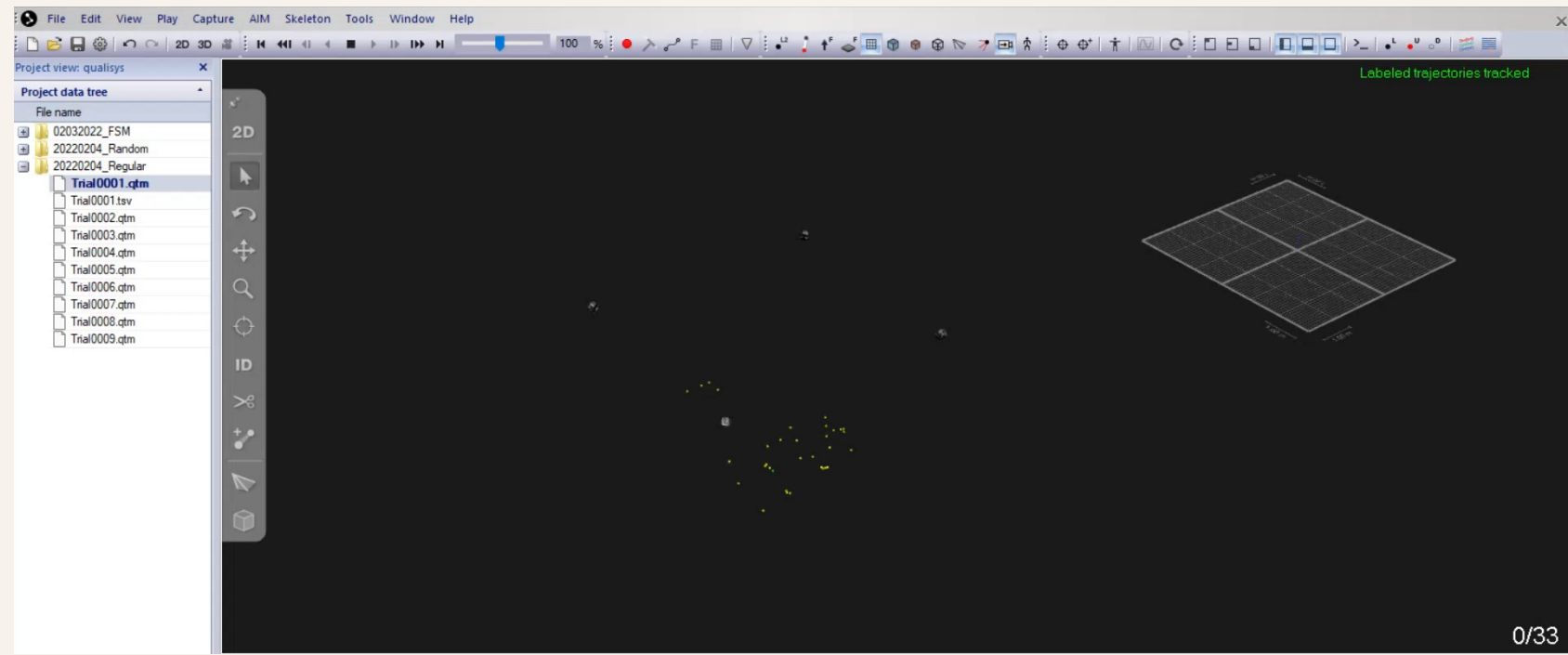
Wave gauge:
Qualisys:

$H=0.096$ m, $T=1.0$ s
 $H=0.097$ m, $T=1.002$ s

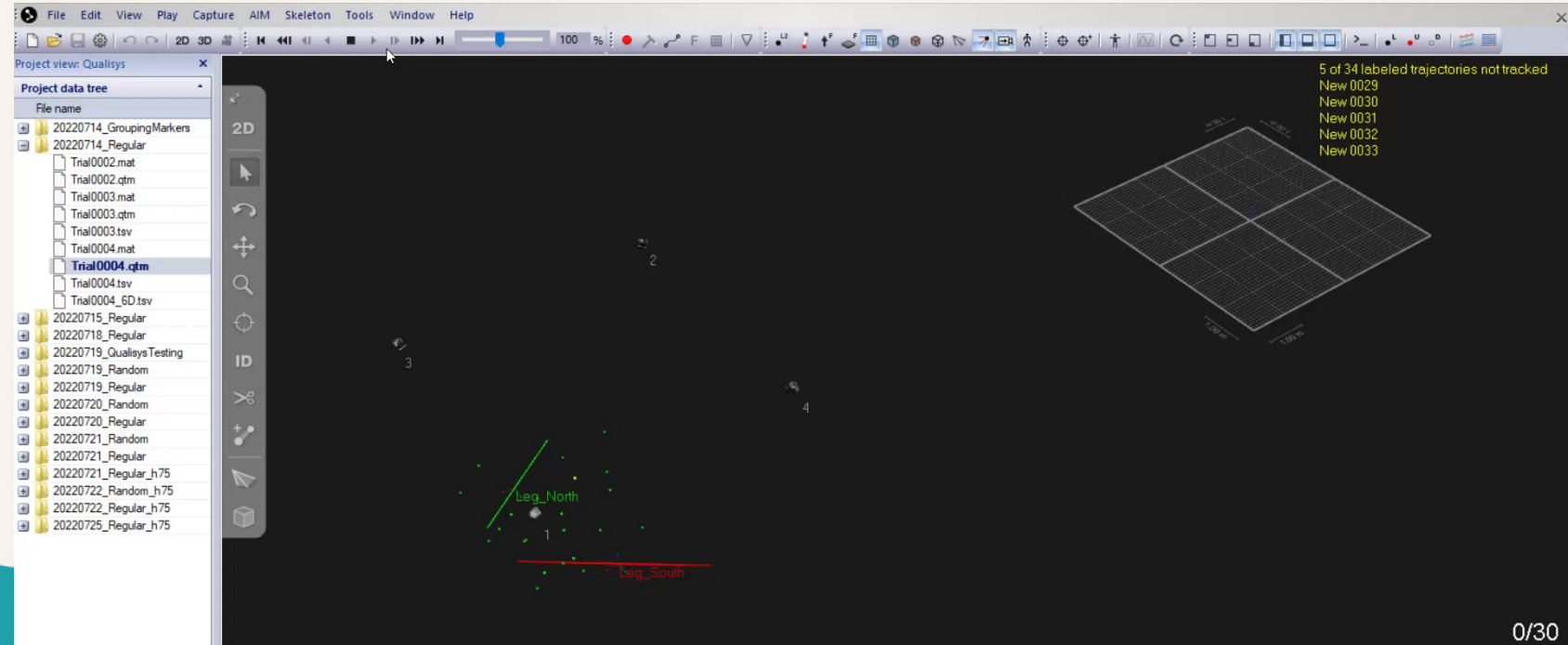


RIB/WA effect

Undisturbed



RIB/WA



Conclusions

- Motion capture with floating markers is an alternative to measure non-intrusively free surface waves
- Complex and highly-variable 3D free surface waves can be measured accurately
- Standard time- and frequency-domain techniques should be adapted to pseudo-Lagrangian measurements
- Multi-directional wave analysis remains another application of Mocap measurements
- Drifting and clustering of markers requires additional improvement for broader applications
- Shallow water measurements and wave breaking remain another aspect for future testing

