

Measuring non-intrusively free surface waves with motion capture systems

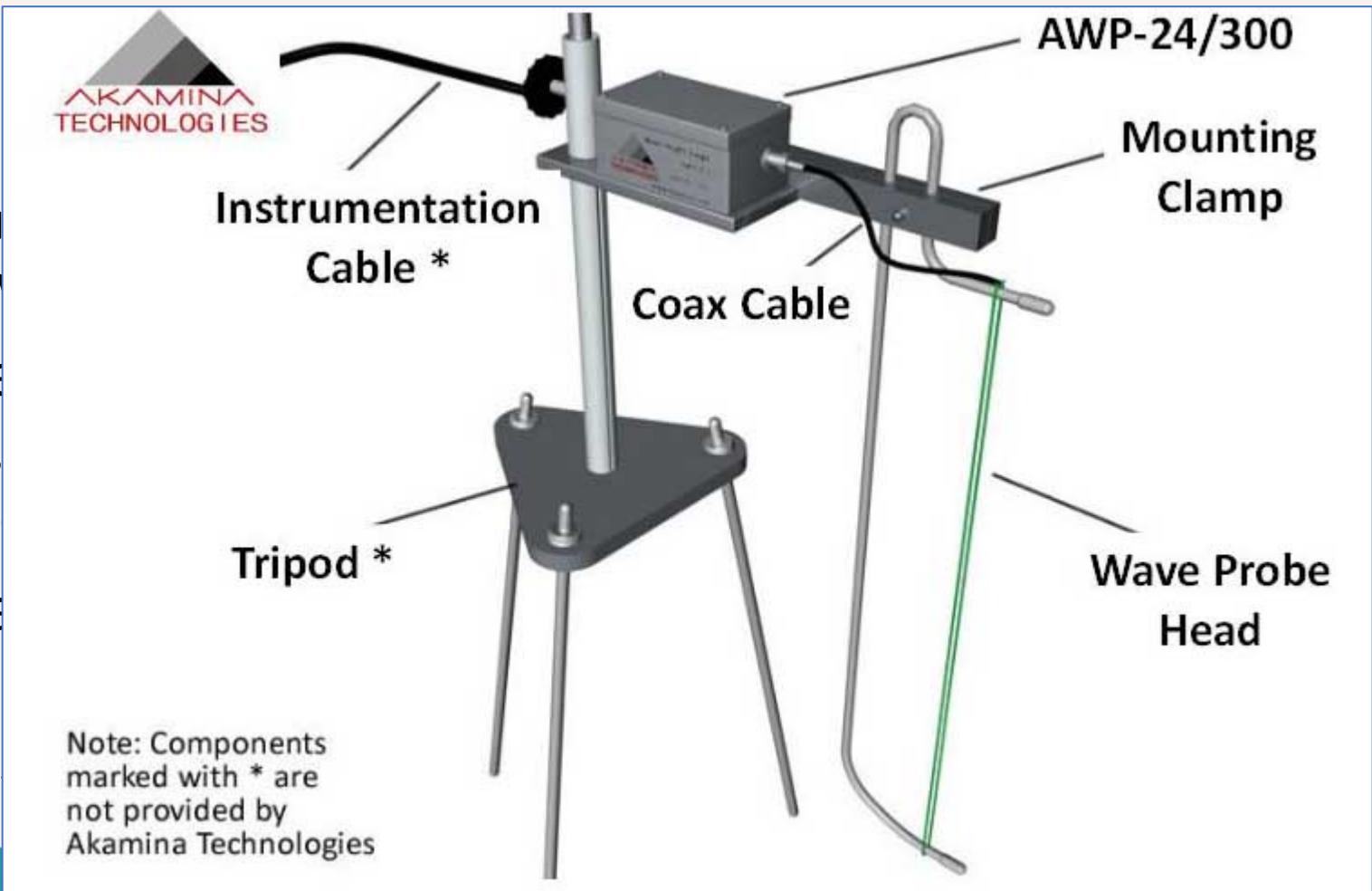
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Assessment of Wave Properties

- Fundamentals
 - Resources for wave breaking
- In the field
 - Buoys, rectifiers
- In laboratory
 - Wave tanks, LiDAR



<http://www.akamina.com/AWP-300-3.html>

Assessment of Wave Properties

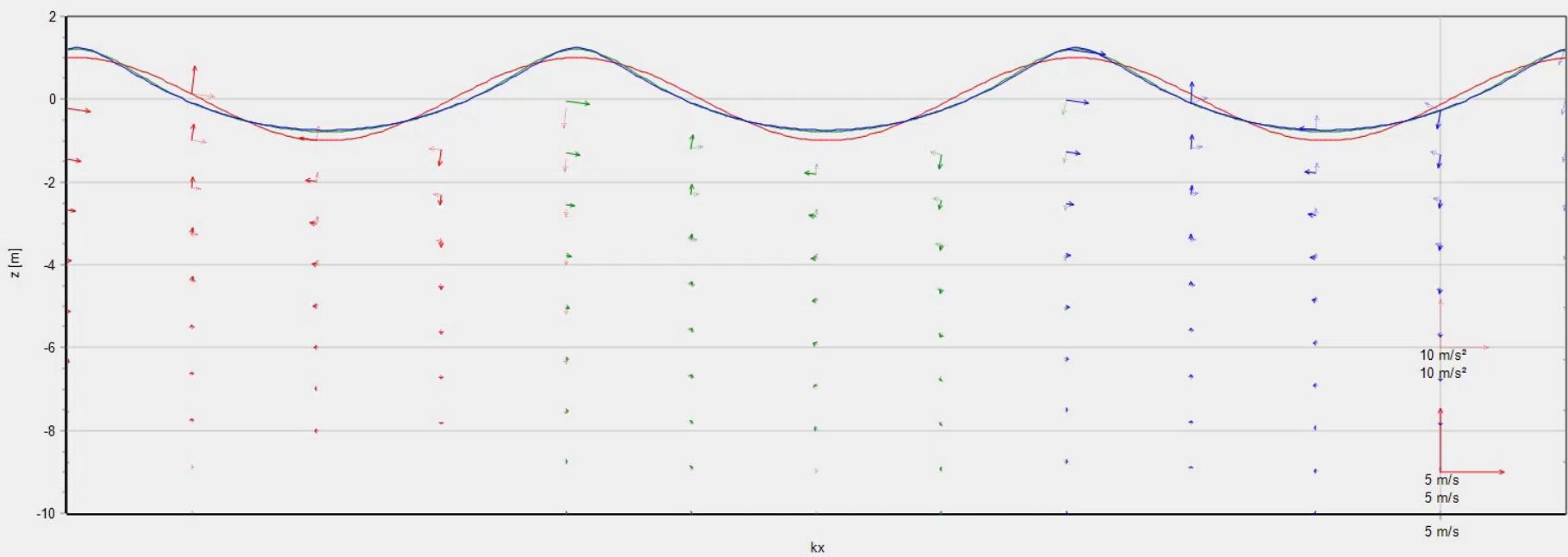
- Knowledge of wave kinematics
 - Free surface
 - Orbital velocities
 - Particle accelerations
 - Pressure distribution
 - Orbital excursions
 - Non-linearities
 - Principles of superposition
 - Directionality
 - Spreading
 - ...

$$\phi(x, z, t) = \frac{ga}{\omega} \frac{\cosh[k(z + d)]}{\cosh(kd)} \sin(\theta)$$
$$u(x, z, t) = \frac{gak}{\omega} \frac{\cosh[k(z + d)]}{\cosh(kd)} \cos(\theta) ; \quad w(x, z, t) = \frac{gak}{\omega} \frac{\sinh[k(z + d)]}{\cosh(kd)} \sin(\theta)$$
$$a_x(x, z, t) = gak \frac{\cosh[k(z + d)]}{\cosh(kd)} \sin(\theta) ; \quad a_z(x, z, t) = -gak \frac{\sinh[k(z + d)]}{\cosh(kd)} \cos(\theta)$$
$$A = \text{horizontal axis} = a \frac{\cosh[k(z_o + d)]}{\sinh(kd)} ; \quad B = \text{vertical axis} = a \frac{\sinh[k(z_o + d)]}{\sinh(kd)}$$
$$\frac{\omega^2}{k} = g \tanh(kd) ; \quad C = \frac{gT}{2\pi} \tanh(kd) ; \quad C = \sqrt{\frac{gL}{2\pi} \tanh(kd)} ; \quad L = \frac{gT^2}{2\pi} \tanh(kd)$$

https://cavity.caee.utexas.edu/kinnas-wow/public_html/waveroom/linthe/node25.html

Assessment of Wave Properties

Input	
Wave Theory	
<input checked="" type="checkbox"/> 1. Order Stoke	
<input checked="" type="checkbox"/> 5. Order Stoke	
<input checked="" type="checkbox"/> Stream Function Theory	
Water Depth [m]	10
Wave Period [s]	3
Wave Height [m]	2
Type of calculation	Current (U) given
U [m/s]	0



— 1. Order Stoke — 5. Order Stoke — Stream Function Theory

Assessment of Wave Properties

Input

Wave Theory

1. Order Stoke
 5. Order Stoke
 Stream Function Theory

Water Depth [m] 10

Wave Period [s] 3

Wave Height [m] 2

Type of calculation Current (U) given

U [m/s] 0

Start Calculation

Advanced Options

Output

Parameter	1. Order Stoke	5. Order Stoke	Stream Function Theory
Wavelength (L) [m]	14.055	16.184	16.288
Wave number ($k=2 \pi/L$)	0.447	0.388	0.386
Current Discharge Q [m³/s]	1.059	0.893	0.841
kx	2.820	2.820	2.820
z [m]	-0.170	-0.170	-0.170
eta [m]	-0.949	-0.755	-0.724
u [m/s]	Out of Range	Out of Range	Out of Range
w [m/s]	Out of Range	Out of Range	Out of Range
du/dt [m/s²]	Out of Range	Out of Range	Out of Range
dw/dt [m/s²]	Out of Range	Out of Range	Out of Range
pd [Pa]	Out of Range	Out of Range	Out of Range
p [Pa]	Out of Range	Out of Range	Out of Range

z

kx

1. Order Stoke

5. Order Stoke

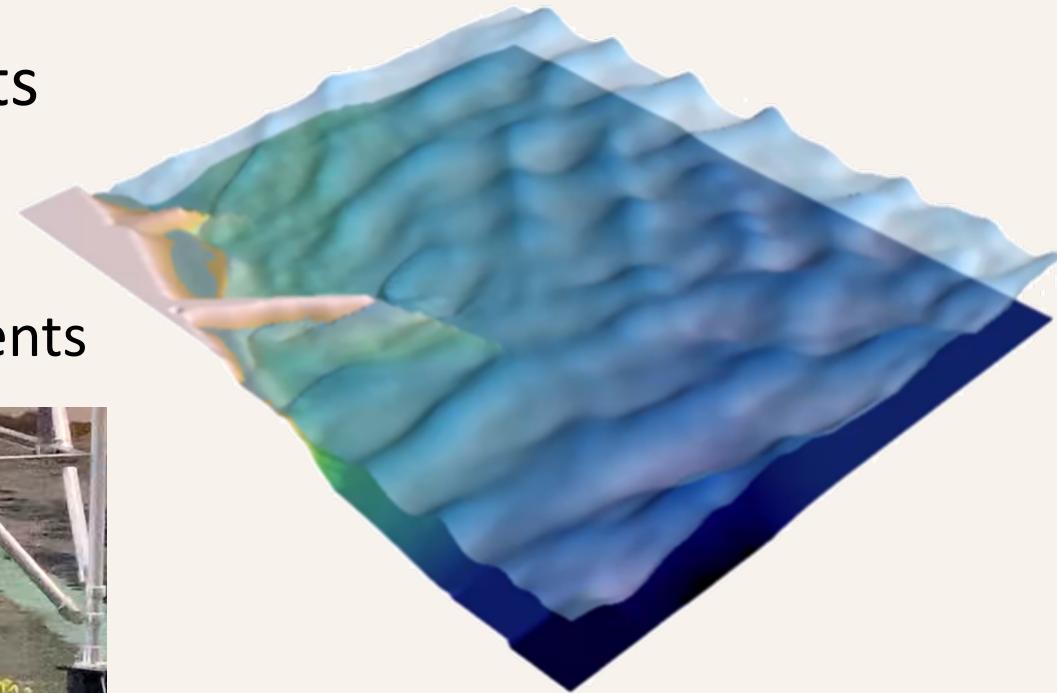
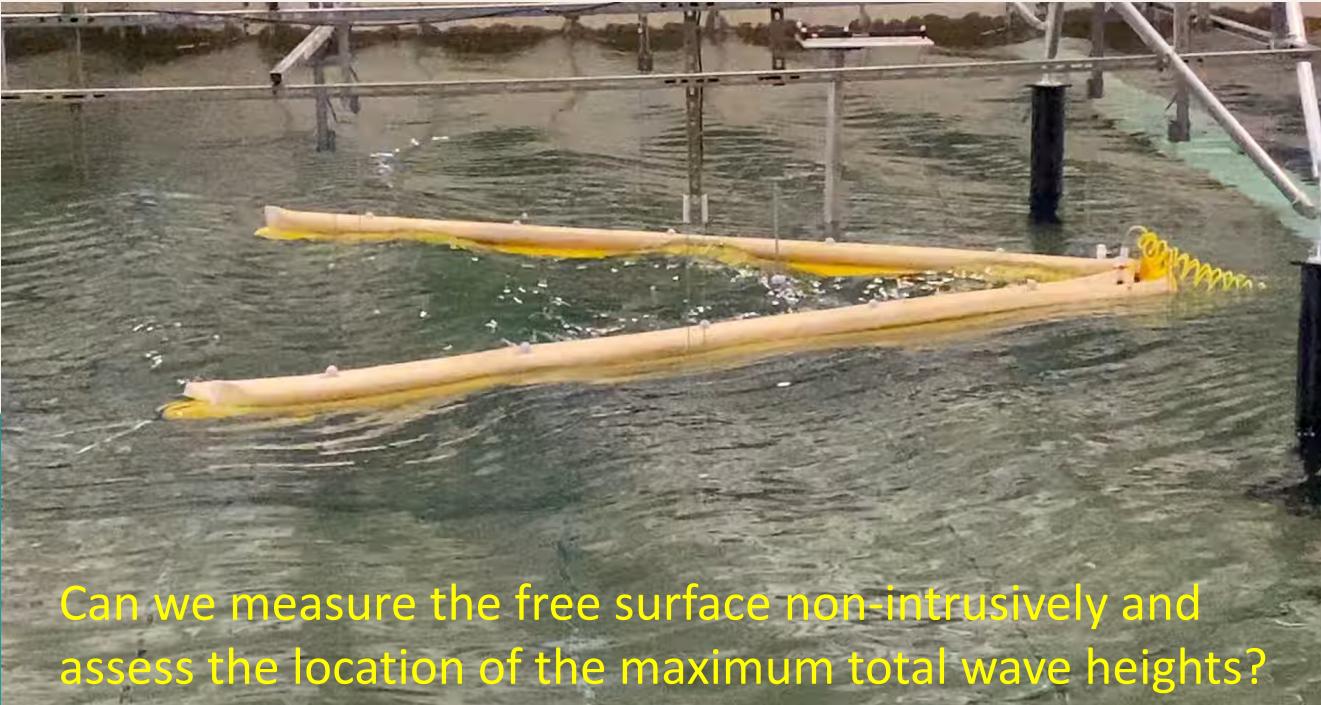
Stream Function Theory

5 m/s 5 m/s

10 m/s² 10 m/s²

Assessment of Wave Properties

- Limitations on free surface measurements
 - Complex and highly variable 3D wave fields
 - Incompatibility with floating devices
 - Interference of intrusive hardware/instruments



<https://jbpacific.com.au/projects/coastal-hazards/diatreme-landing-facility-coastal-assessment-qld/>

Mocap – Motion Capture System

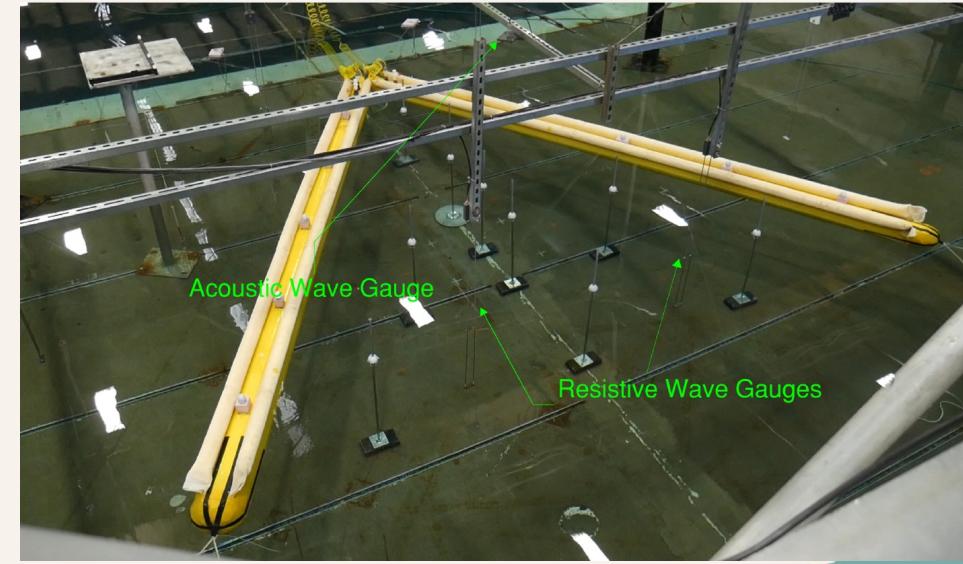
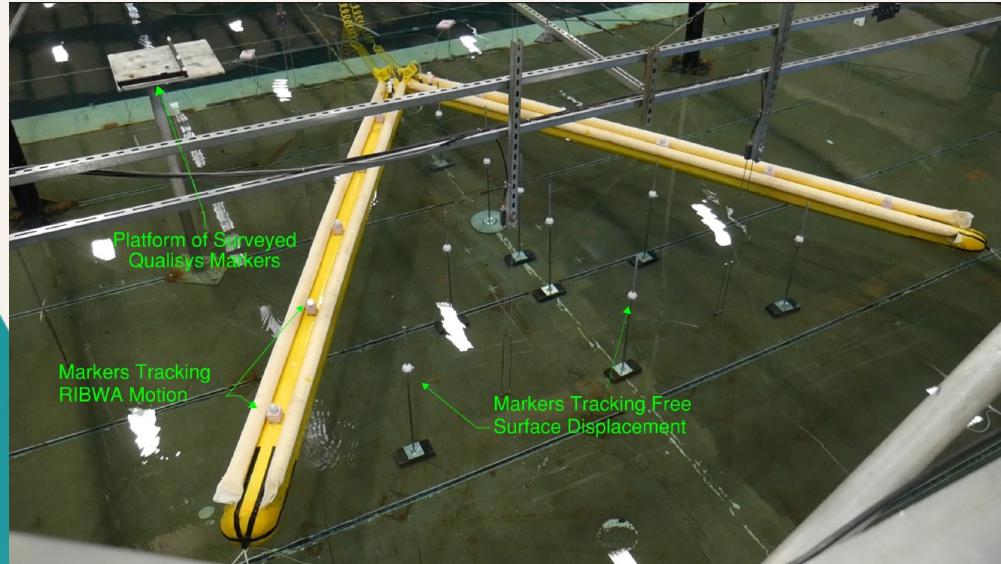
- Registering the motion of objects
- Non-intrusive
- Use of cameras
- Use of passive or active markers
- Capturing the 3D coordinates with a high sampling rate
- Applications in marine engineering, coastal engineering, health science, video game industry, movies, ...



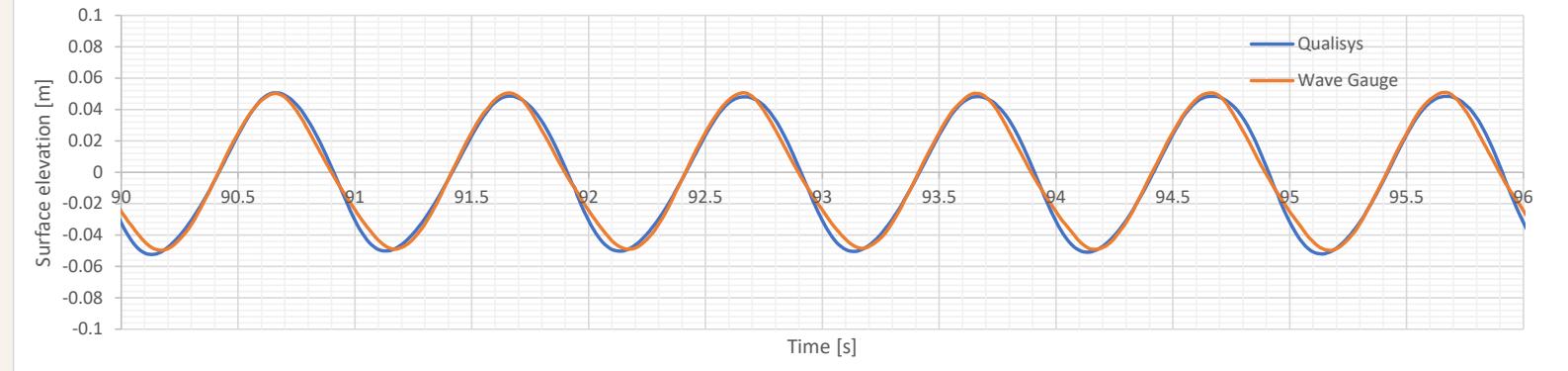
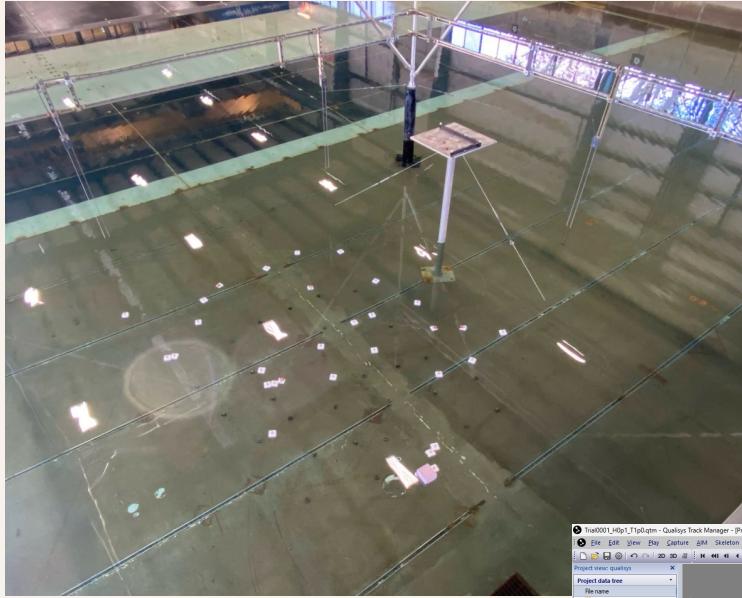
<https://www.youtube.com/watch?v=qtXz6qocciM>

TEAMER - Rapidly Installed Breakwater for WEC Enhanced Performance

- Experiments presented in UMERC 2023
- Qualisys Motion Capture:
 - RIB/WA motions and deformations
 - Free surface tracking

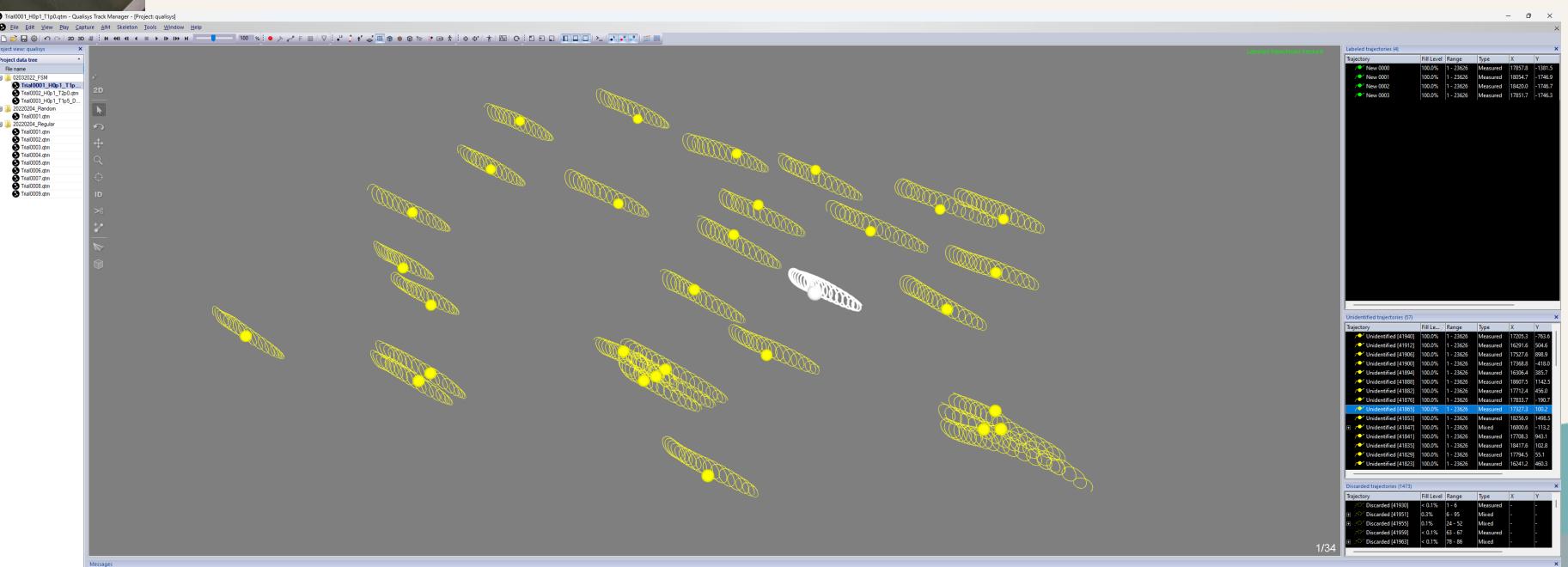


Undisturbed conditions (no RIB/WA)



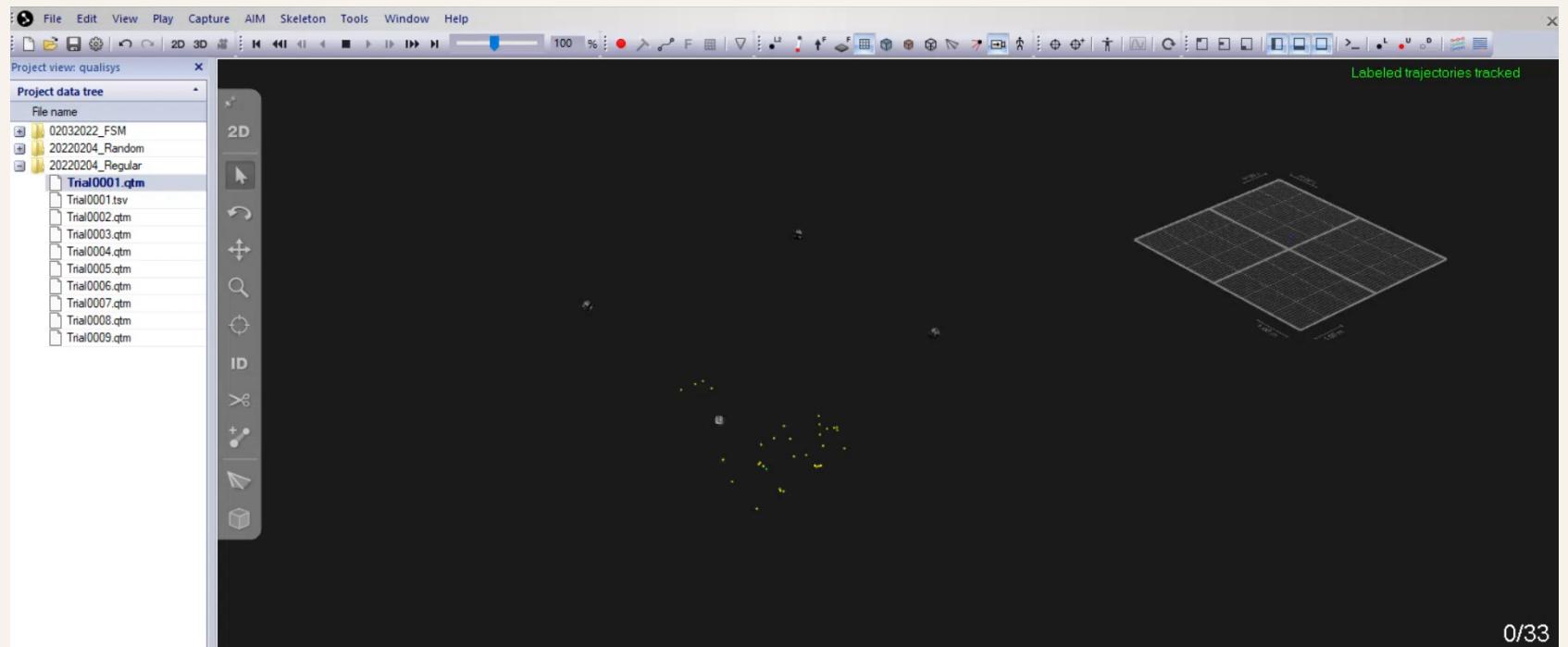
Wave gauge:
Qualisys:

$H=0.096 \text{ m}$, $T=1.0 \text{ s}$
 $H=0.097 \text{ m}$, $T=1.002 \text{ s}$

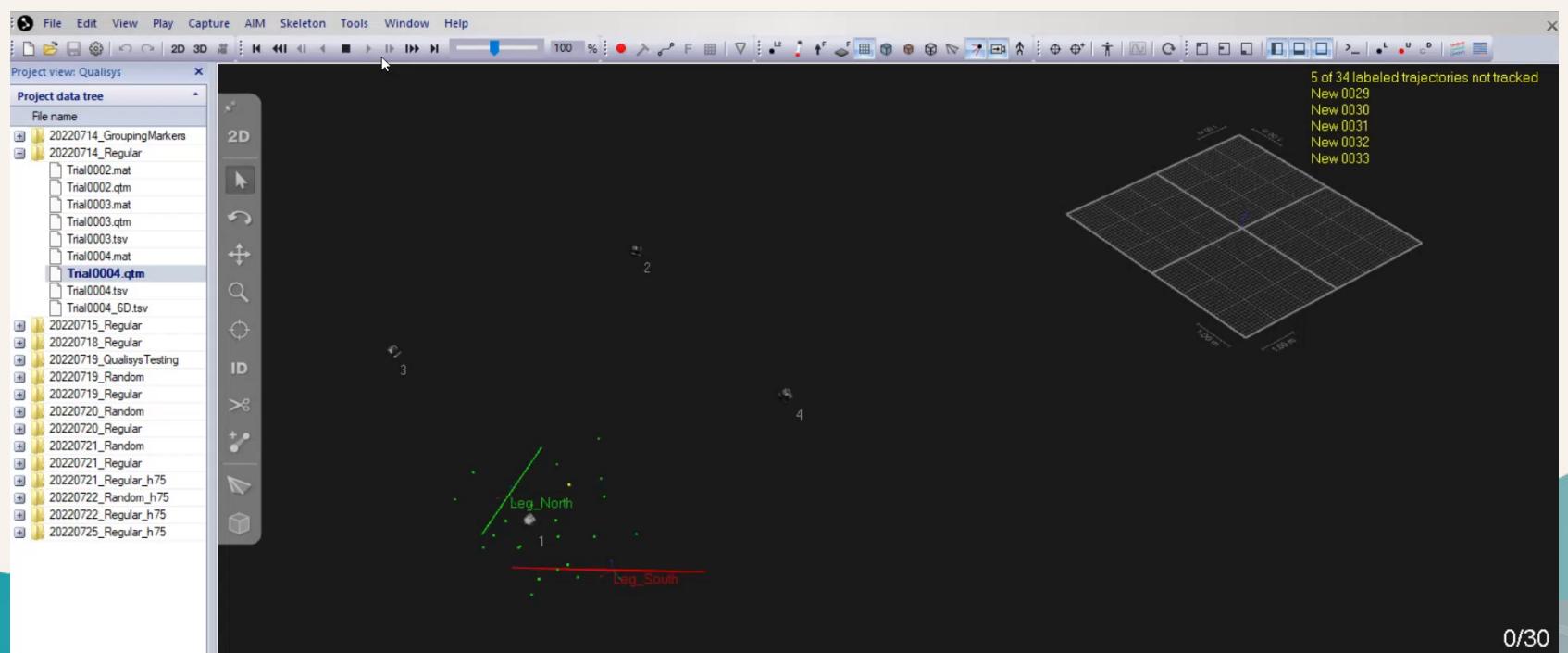


RIB/WA effect

Undisturbed



RIB/WA



Conclusions

- Motion capture with floating markers is an alternative to measure non-intrusively free surface waves
- Complex and highly-variable 3D free surface waves can be measured accurately
- Standard time- and frequency-domain techniques should be adapted to pseudo-Lagrangian measurements
- Multi-directional wave analysis remains another application of Mocap measurements
- Drifting and clustering of markers requires additional improvement for broader applications
- Shallow water measurements and wave breaking remain another aspect for future testing