

LUPA: An Open-Source Lab Scale WEC





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UNIVERSITY of
WASHINGTON

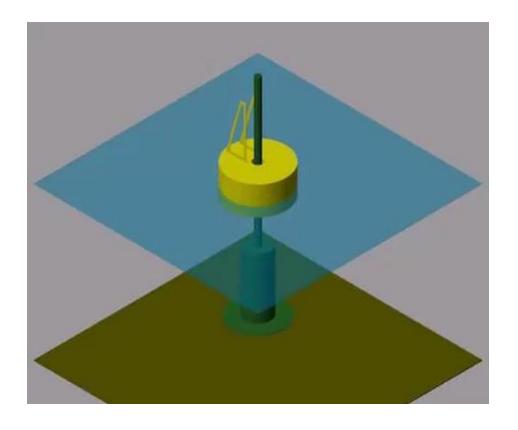
Motivation

Modular & Flexible

Incremental Complexity

Open-Source & Validated

Successes & Failures



LUPA - Two-body point absorber





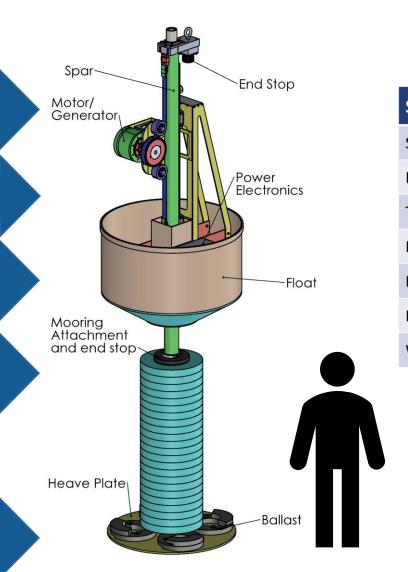
Generator/PTO control

Gear Ratio

Float geometry

Mooring Configuration

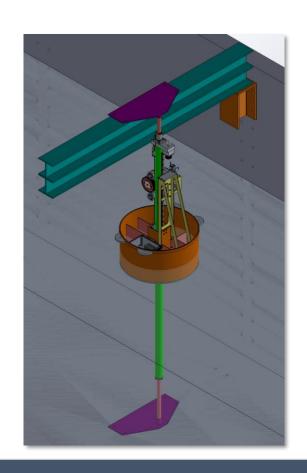
Heave plate geometry



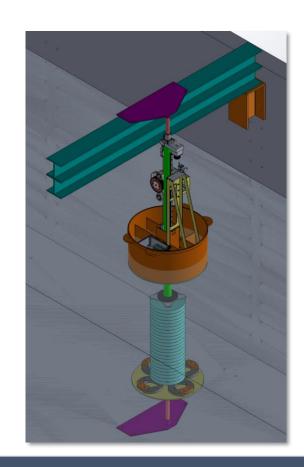
| Value | Units |
|-------|--------------------------------------|
| 1/20 | m/m |
| 1 | m |
| 3.7 | m |
| 0.5 | m |
| 436 | kg |
| 46 | Nm |
| 2.7 | m |
| | 1/20 1 3.7 0.5 436 46 |



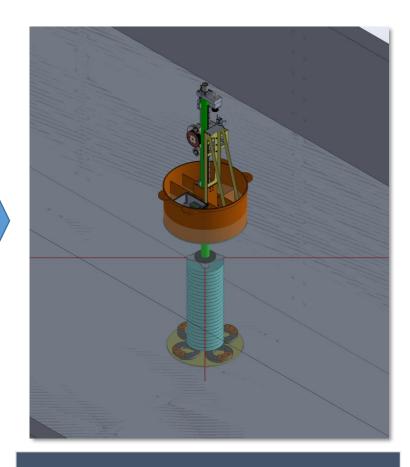
Incremental Complexity







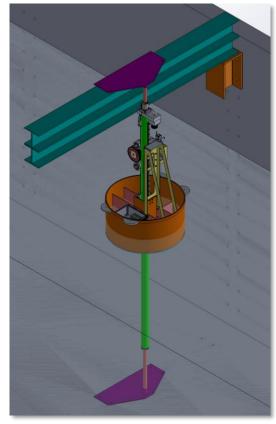
Two-body, 1 DOF



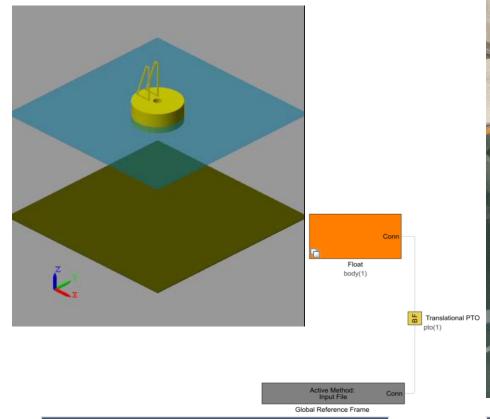
Two-body, 6 DOF



One-Body, Heave Only







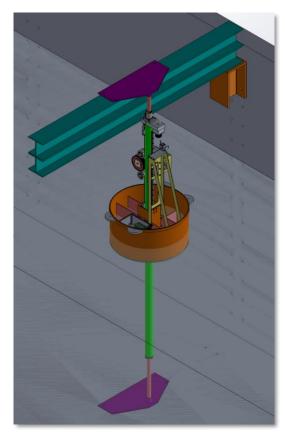
WEC-Sim Model

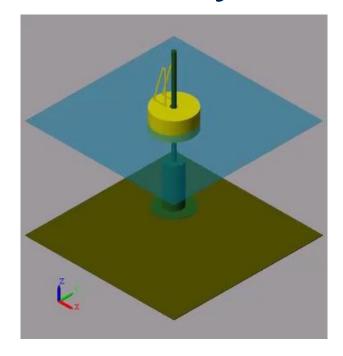


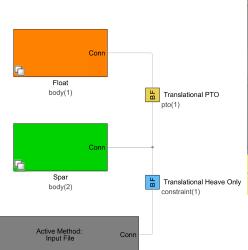
Experimental Data



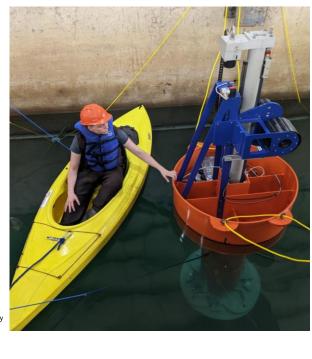
Two-Body, Heave Only







Global Reference Frame



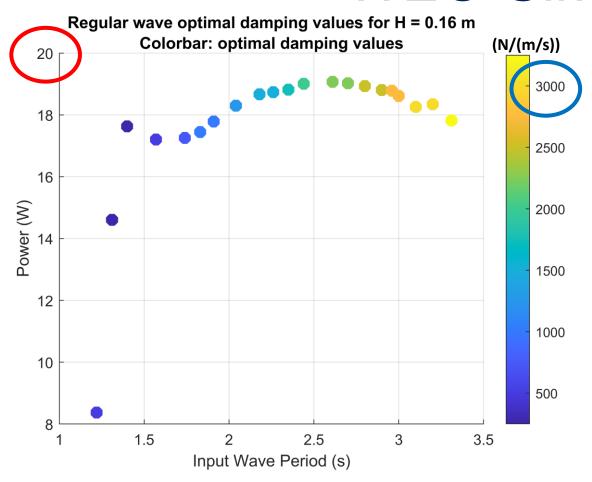
Solidworks

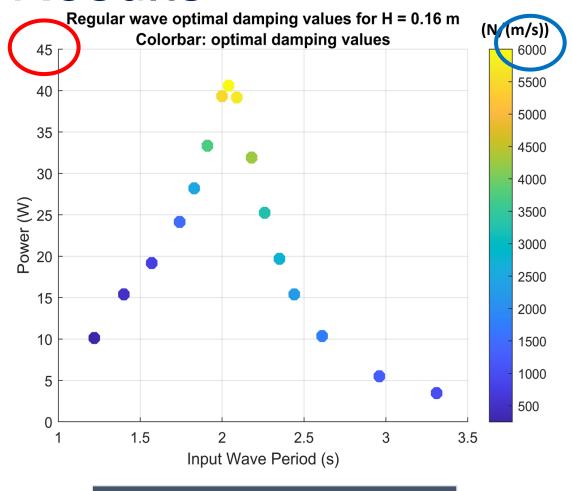
WEC-Sim Model

Experimental Data



WEC-Sim Results



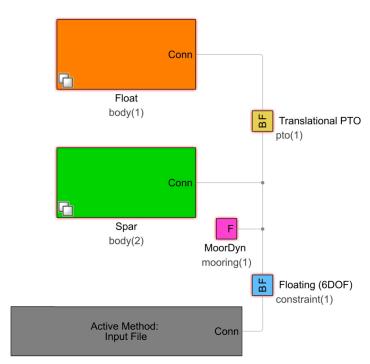


One-body heave only

Two-body heave only

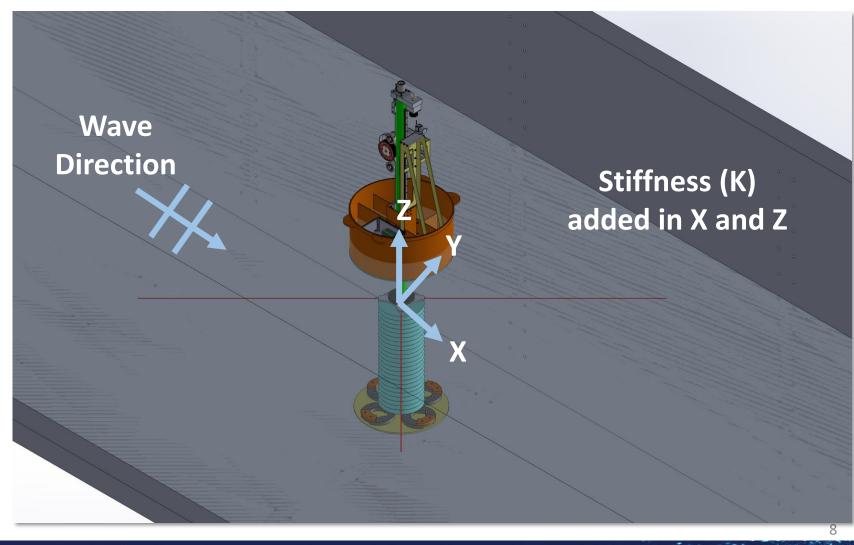


Two Body, 6 DOF



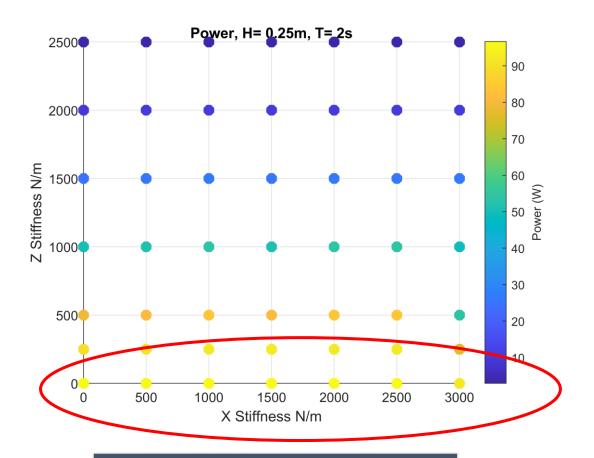
WEC-Sim Model

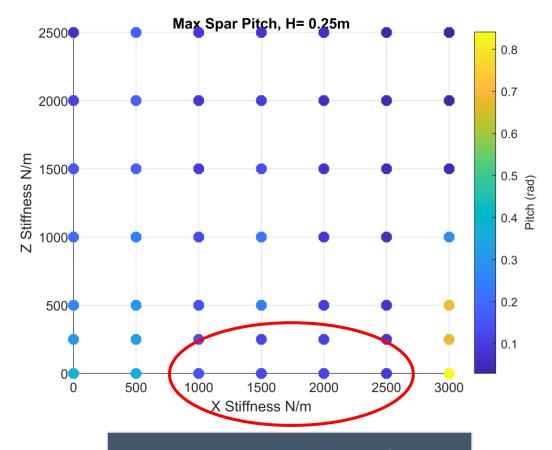
Mooring Matrix and Cable Block





6 DOF, WEC-Sim Results





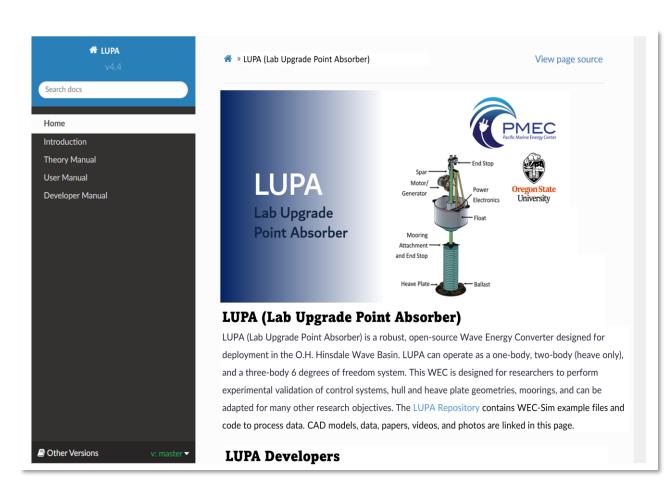
Maximize power

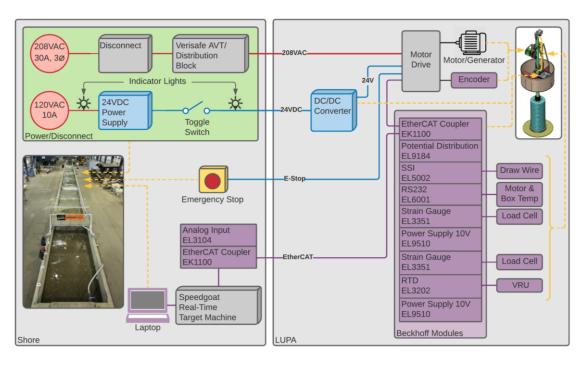
Minimize pitch





Open-Source and Validated (TBV)





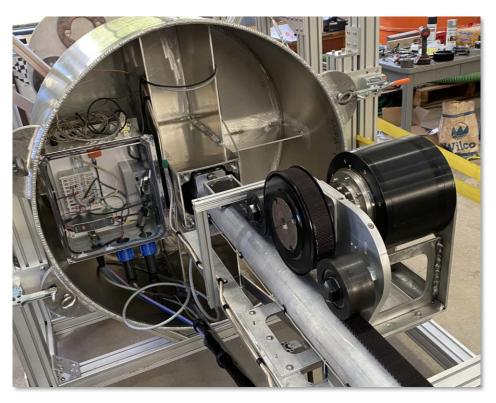
https://pmec-osu.github.io/LUPA/

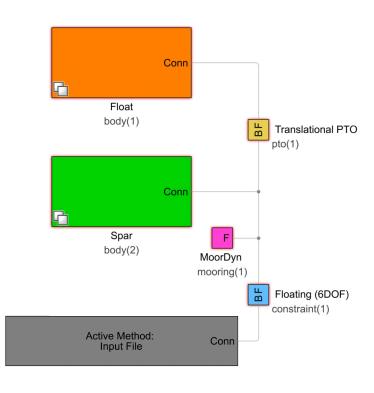




Lessons Learnt







Minimizing Friction

Sizing Components

Model Tank Mooring

Future Work

'Validation' of Optimized Hull and Heave Plate Shapes

WEC Hydrodynamics for AUV Docking and Recharge

WEC Power Dynamics in Remote Microgrids

Non-Linear Wave Structure Interaction Models

WEC Power Integration in OSU Campus Grid

Yours?



